

GETTING STARTED WITH VICON SHOGUN

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About this guide

About this guide

This guide provides an introduction to Vicon Shogun and an end-to-end workflow for capturing data with Vicon Shogun Live, and processing and exporting it with Vicon Shogun Post.

Videos of the procedures described in this guide, including many additional tips and examples, are available from the [Vicon Shogun playlist on YouTube](#)¹, and the [Vicon Shogun channel on Vimeo](#)², beginning with [1 - Shogun Live - Introduction](#)³.

i Note

As some videos were recorded using an earlier version of Shogun, you may notice minor differences in the user interface.

1 <https://www.youtube.com/playlist?list=PLxtdgDam3USVknig2N6QU1ARXR22LXJfJ>

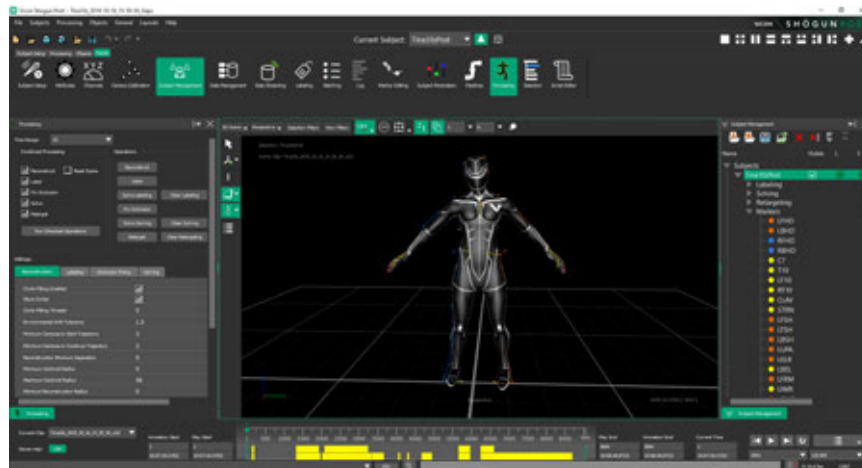
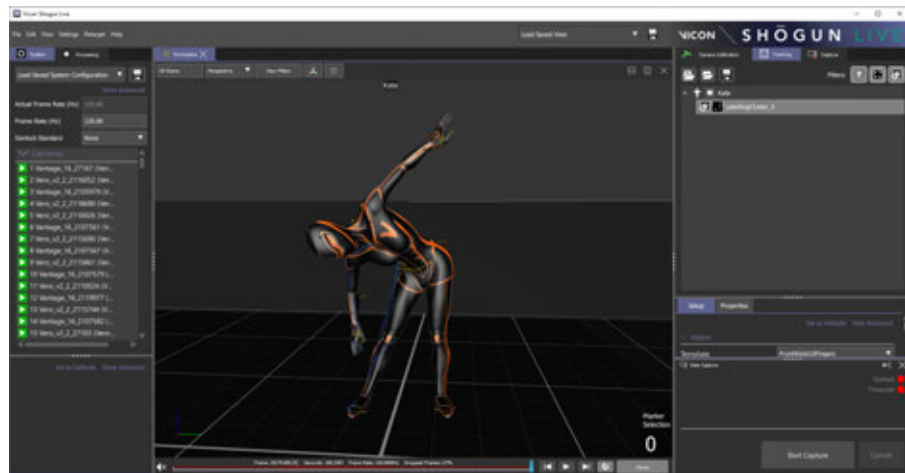
2 <https://vimeo.com/channels/1249217>

3 <https://vimeo.com/218944959>

Introducing Vicon Shogun

Introducing Vicon Shogun

The information in this section helps you to get to know Shogun.



These topics are useful if you are new to Shogun and want to familiarize yourself with the user interface, but if you're ready to start working straight away, go to [Prepare your Vicon system](#) (page 55).


- [Introducing Shogun Live](#) (page 6)
- [Introducing Shogun Post](#) (page 23)

Introducing Vicon Shogun

Introducing Shogun Live

These topics provide a brief introduction to Vicon Shogun Live.

- [Live - Customize views \(page 7\)](#)
- [Live - Work with panels \(page 13\)](#)
- [Live - Set preferences \(page 17\)](#)
- [Live - Hot keys and shortcuts \(page 20\)](#)

 See also the Vicon video: [1 - Shogun Live - Introduction⁴](#), which also provides an introduction to Vicon Shogun Live.



Note

As the videos were recorded using an earlier version of Shogun, you may notice small differences in the user interface.

⁴ <https://youtu.be/XrmM2KXiaPQ>

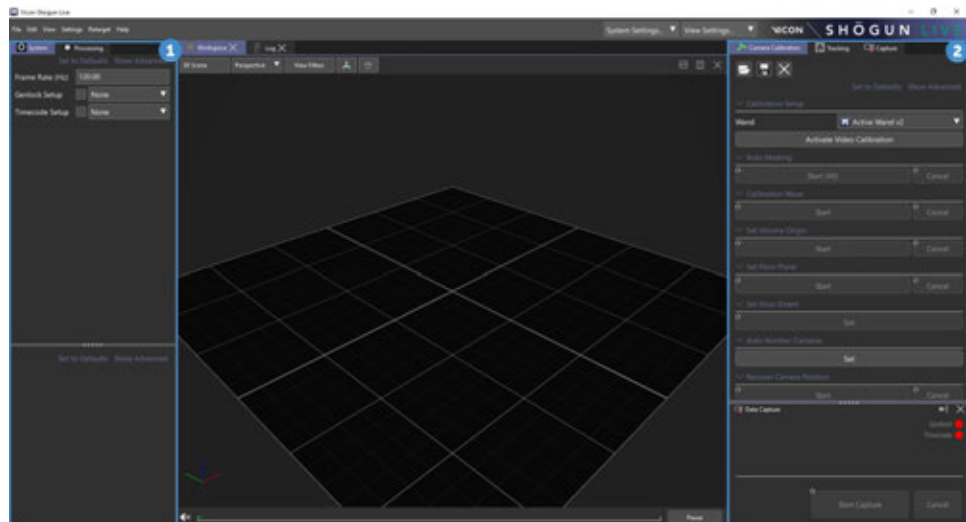
Introducing Vicon Shogun

Live - Customize views

The default Vicon Shogun Live window is arranged in a way that is ready to use for your first capture.

The **System** panel **1** is displayed on the left (with the **Processing** panel displayed as a tab below it).

On the right of the Shogun Live window, the **Camera Calibration** **2**, **Tracking**, and **Capture** panels are displayed as tabs. These tabs are displayed in the order you are likely to want to use them (from left to right) and on each tab, the sections are arranged in order of a typical workflow.



To find out more about working with views, see:

- [Change the view type \(page 8\)](#)
- [Change the layout \(page 9\)](#)
- [Select displayed view options \(page 10\)](#)

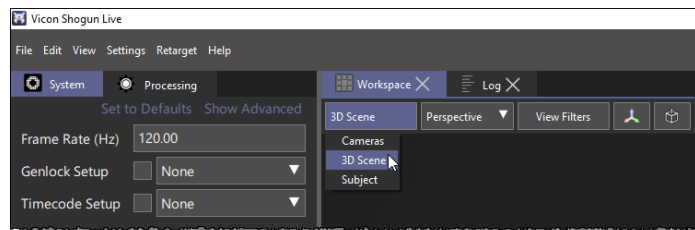
Introducing Vicon Shogun

Change the view type

In the **Workspace**, you can change the type of data that is displayed, as well as the way in which the view is split, enabling you to view different types of data simultaneously. To save time, you can save and reload frequently used layouts.

To change the view type:

1. In the **Workspace**, click the view menu.



2. Select the required view from the list.

- **Cameras:** 2D optical data from Vicon cameras.
- **3D Scene:** 3D reconstructions of Vicon camera data.

When you choose the **3D Scene** view, you can also select a **Perspective** view, or orthogonal views:

- **Perspective 3D** view of data in the view pane
- **Front, Back, Right, Left, Top, or Bottom:** Orthogonal views of 3D data
- **Subject:** Visualization of the subject.

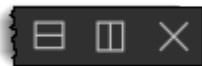
Introducing Vicon Shogun

Change the layout

In addition to selecting the type of view that is displayed in Shogun Live (see [Change the view type \(page 8\)](#)), you can split the view horizontally or vertically, with different view types in each part of the pane, and display different panels to suit the current stage in your workflow. You can save any favorite layouts so that you can quickly access them in future.

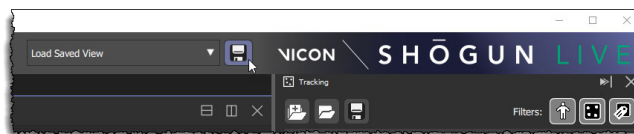
To select a layout for a view pane:

1. Click the required button at the top right of the view pane.

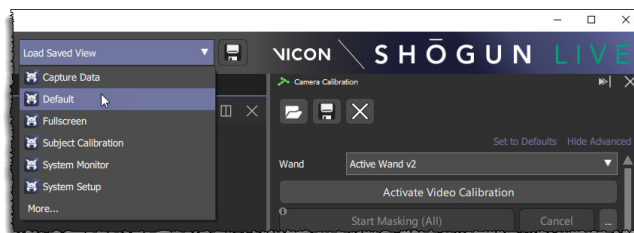


You can display a different view in each pane; for example, a Perspective view in one and a Cameras view in the other.

2. To save a favorite layout, click the Save button to the right of the Load Saved View list.



3. To return to the default layout, in the Load Saved View list, click Default.



Introducing Vicon Shogun

Select displayed view options

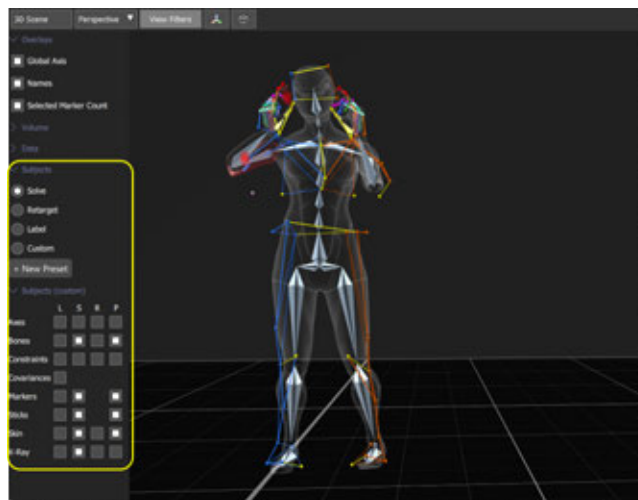
In the 3D Scene or Cameras views, you can display the View Filters to select and save your preferred options.

- [Select what is displayed in a selected view \(page 10\)](#)
- [Select snap option for rotating cameras \(page 11\)](#)
- [Set the marker reconstruction radius \(page 12\)](#)
- [Zoom in to grayscale markers \(page 12\)](#)

Select what is displayed in a selected view

1. In a 3D Scene or Cameras view, click **View Filters**.

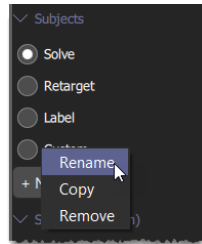
In a 3D Scene view, the view options are displayed in a matrix, with columns for Labeling, Solving, Retargeting and Props, enabling you to choose a view configuration that suits your current task.



The default view filter sets are for solving, retargeting, and labeling. If required, you can add your own filter sets by clicking **New Preset**.

Introducing Vicon Shogun

- To rename, copy or remove any filter sets, right-click on a filter set and then click the required option.



Your settings, including any custom presets, are automatically saved, so that you can easily re-use them for different workflows.

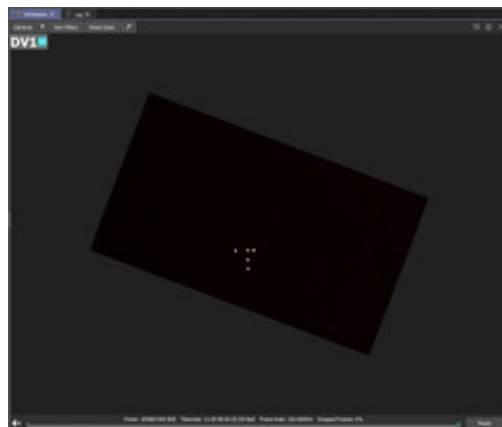


Tip

In the **View Filters**, you can select **Subjects** options to display the required data, for example, to view markers and bones through the skin, select **X-Ray**.

Select snap option for rotating cameras

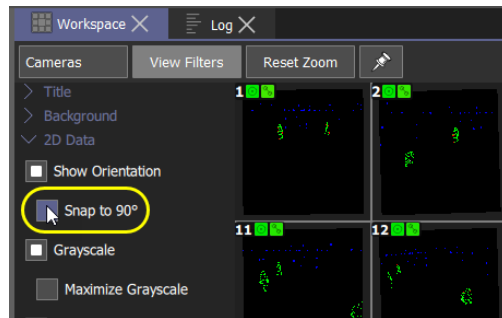
When cameras are physically rotated, Shogun Live adjusts to display the cameras with the correct rotation.



After system calibration, the camera 'tunes' itself to update its rotation based on calibration.

Introducing Vicon Shogun

To set the rotation to snap to the nearest 90 degrees, in the Cameras view, display the **View Filters** and in the **2D Data** section, select the **Snap to 90°** check box.

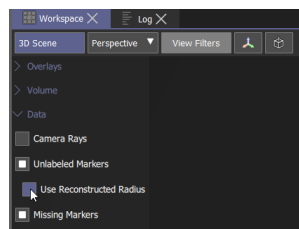


Set the marker reconstruction radius

You can select an option to display markers based on their physical size, instead of the default (7 mm) size. This is particularly useful if you have a high density of small markers, for example for facial motion capture, or if you're using the latest finger-marker sets.

To set the marker reconstruction radius:

1. In the **3D Scene** view, display the **View Filters**.
2. To display markers based on their physical size, select the **Use Reconstruction Radius** option.



Zoom in to grayscale markers

In the **Cameras** view, to zoom in to display any grayscale markers present, in the **View Filters**, go to the **2D Data** options and select **Maximize Grayscale**.

Introducing Vicon Shogun

Live - Work with panels

The Shogun Live window is fully customizable, enabling you to change the position of the panels and to hide and re-display panels as required by your workflow.

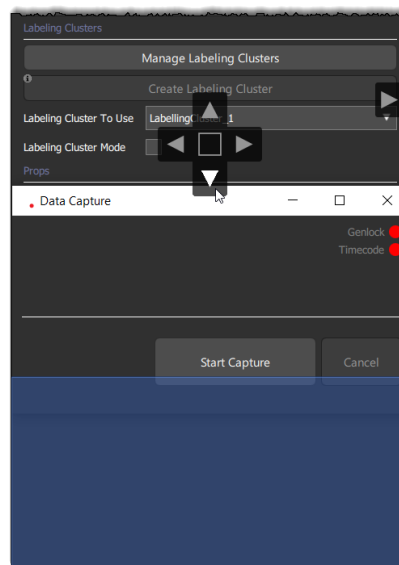
To find out more, see:

- [Change the position of panels \(page 13\)](#)
- [Hide and display panels \(page 14\)](#)
- [Expand and collapse panel sections \(page 15\)](#)
- [View feedback in the System panel \(page 15\)](#)
- [Search for properties in the Processing panel \(page 16\)](#)

Change the position of panels

In Shogun Live, you can position the panels to suit your way of working.

To move panels, drag them by their title bars and drop them into place using the guides that overlay the main window:



If you prefer, instead of docking the panels as described above, you can leave panels floating in an independent window.

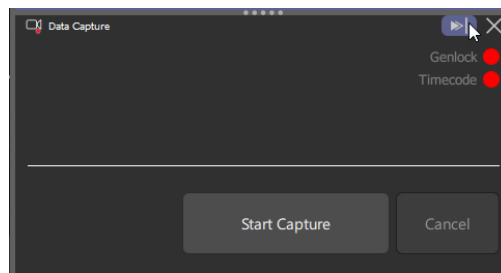
Introducing Vicon Shogun

Hide and display panels

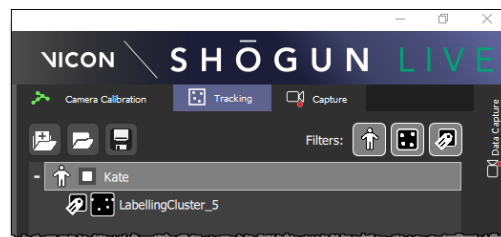
In addition to changing the position of panels (see [Change the position of panels](#)), you can also hide some panels, to give you more space in which to work.

To hide/redisplay a panel:

- On the title bar of a docked panel, click the Pin button.



The panel is hidden as a vertical tab along an edge of the main window.



If you hide multiple panels, they are tabbed vertically along the edge of the main window.




To re-display a pinned tab:

1. Click the required tab on the edge of the main window.
The panel is displayed in a floating window.
2. To dock it again, click its Pin button.

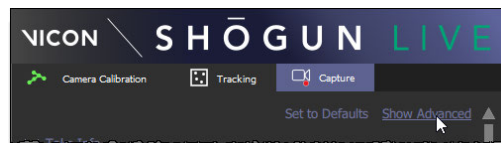
Introducing Vicon Shogun

Expand and collapse panel sections

Within each panel, you can expand and collapse sections, to make it easier to access the controls you want to use.

Action	Mouse
Expand section	Click the right-pointing arrow 
Collapse section	Click the downward-pointing arrow 
Show/hide further options	Click the ellipsis 

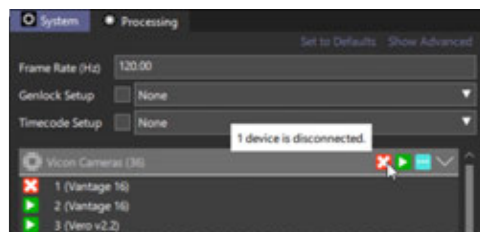
To help you find the controls, panels also let you show and hide Advanced settings, and where applicable, you can set the values to their defaults.



View feedback in the System panel

The System panel provides helpful feedback, which is especially useful for large systems.

For more information about the status of your system components, hover the mouse pointer over the relevant icon.

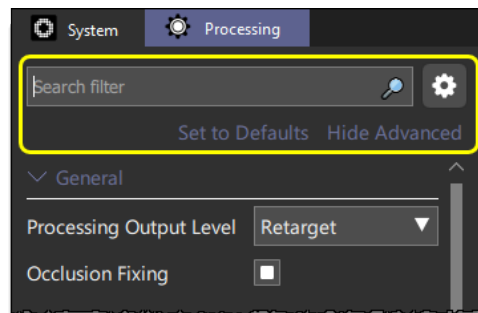


Introducing Vicon Shogun

Search for properties in the Processing panel

The Processing panel provides a search facility and other controls that determine the visibility of the component properties.

To use the search, display the Advanced properties and enter the first few letters of the property you want to find.



Introducing Vicon Shogun

Live - Set preferences

To access and change preferences such as data and capture folder locations, hot keys and auto-save options, you use the Preferences dialog box.

This topic introduces some of the ways you can customize Live.

- [Low disk space warning](#) (page 18)
- [Behavior of middle mouse button](#) (page 19)

Introducing Vicon Shogun

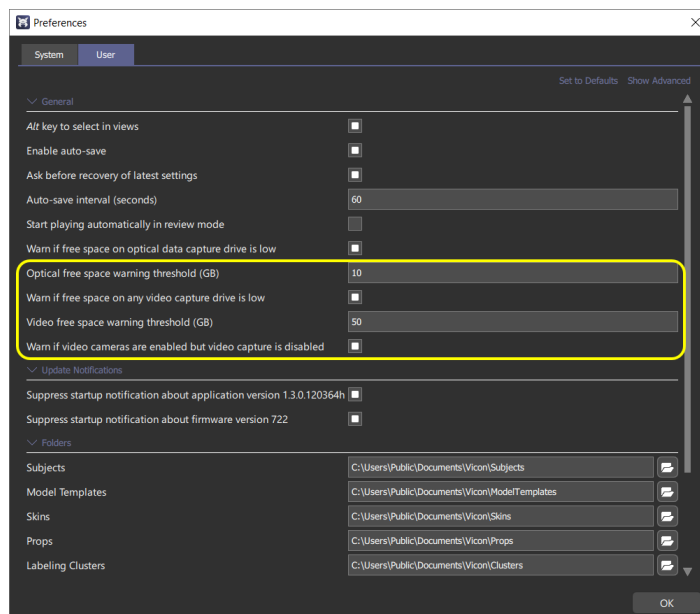
Low disk space warning

Shogun Live warns you if your capture drive(s) reaches a specified capacity.

To change the amount of free space remaining before Shogun Live alerts you:

1. In the **Preferences** dialog box (**Settings > Preferences**, or **Shift+P**), click the **User** tab.
2. In the **Capture** section, make the required changes.
The default free space remaining is:
 - For optical data capture: 10 GB
 - For video capture: 50 GB

You can also select or clear the check box to enable a warning if video cameras are enabled, but video capture is disabled.



Introducing Vicon Shogun

Behavior of middle mouse button

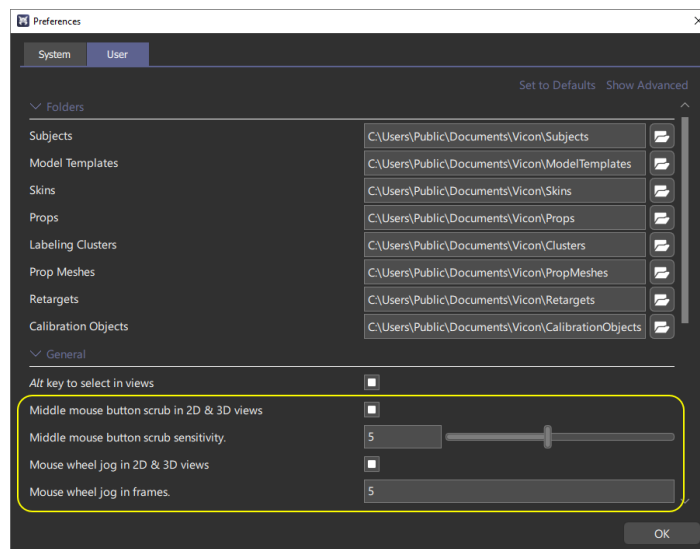
You can scrub the timeline by holding down the middle mouse button. You can use this shortcut in both the **3D Scene** view and the **Cameras** view.

You can adjust the behavior of the middle mouse button with options in the **Preferences** dialog box.

To change the settings for the middle mouse button or wheel:

1. Open the **Preferences** dialog box (Shift-P).
2. On the **User** tab, go to the **General** section and select/clear the required settings.

Note that the effect of changing the **Middle mouse button scrub sensitivity** (or the **Mouse wheel jog in frames**) option is exponential and is the same as the equivalent setting in Post.



Introducing Vicon Shogun

Live - Hot keys and shortcuts



Tip

To see a list of all current hot keys, on the **Settings** menu, click **Show Hot Keys** or press Shift+H.

To create your own hot keys, in the **Command** column, double-click the required command and in the **Set Hot Key** dialog box, specify the hot keys.

Use the mouse and keyboard to speed up your work with Vicon Shogun Live with the following commonly used shortcuts:

3D Scene view

Action	Mouse
Rotate	Click and drag
Translate	Left- and right-click and drag
Zoom	Right-click and drag
Scale the object manipulator	Press + (scale up) or - (scale down)
Pause/resume live streaming	Space bar
Scrub the timeline	Middle mouse button

Introducing Vicon Shogun

Cameras view

Action	Mouse
Zoom in or out	Middle mouse button + drag, or rotate the mouse wheel.
Enable the Grayscale view option for all or selected cameras	G
Disable the Grayscale view option	Shift+G
Pause/resume live streaming	Space bar
Scrub the timeline	Middle mouse button

Select objects

Action	Mouse/hotkey
Select	Click or Drag or ALT+drag (3D Scene, Perspective view)
Multiple select/de-select	CTRL+click or SHIFT+click

Set hot keys in Live

If you want to change what happens when you press a particular key or combination of keys, you can assign or un-assign commands to hot keys.

To assign or clear hot keys:

1. Open the Hot Keys dialog box (**Settings > Show Hot Keys** or Shift+H).
2. Double-click the required command to display the **Set Hot Key** dialog box, where you can set or clear the hot key for it.
3. To save to disk the current hot keys, including any changes you've made, click **Save**.
4. Click OK to close the Hot Keys dialog box.

Introducing Vicon Shogun

Selecting and the ALT key

To change the behavior of the ALT key:

1. On the **Settings** menu, click **Preferences** (or press SHIFT+P) and in the **Preferences** dialog box, click the **Preferences for *userName*** tab.
2. In the **Interface** section, clear or select **ALT key to select in views**.
This sets the ALT key as required when selecting.

When **ALT key to select in views** is cleared, the default behavior is selection without the ALT key.

Align a prop to the world axis

To align a selected prop to the world axis:

- With the prop selected, display the Object Manipulator, ensure it is set to **Global** and change all the prop's values to zero.

For more information, see [Move props \(page 128\)](#).

Select Grayscale Mode for cameras

To cycle through the Grayscale Mode options:

1. Ensure the relevant cameras are selected.
2. Press **Ctrl+G**.
This saves you from having to select the option for the camera(s) on the **System** tab.

Introducing Vicon Shogun

Introducing Shogun Post

These topics provide a brief introduction to Vicon Shogun Post.

- [Post - Customize views \(page 24\)](#)
- [Post - Work with panels \(page 31\)](#)
- [Post - Set preferences \(page 35\)](#)
- [Post - File types \(page 43\)](#)
- [Post - Hot keys and shortcuts \(page 47\)](#)

 See also the Vicon video: [1 - Shogun Post - Introduction⁵](#), which also introduces Vicon Shogun Post.

 **Note**

As the videos were recorded using an earlier version of Shogun Post, you may notice small differences in the user interface.

⁵ <https://youtu.be/A4cdCdaDTII>

Introducing Vicon Shogun

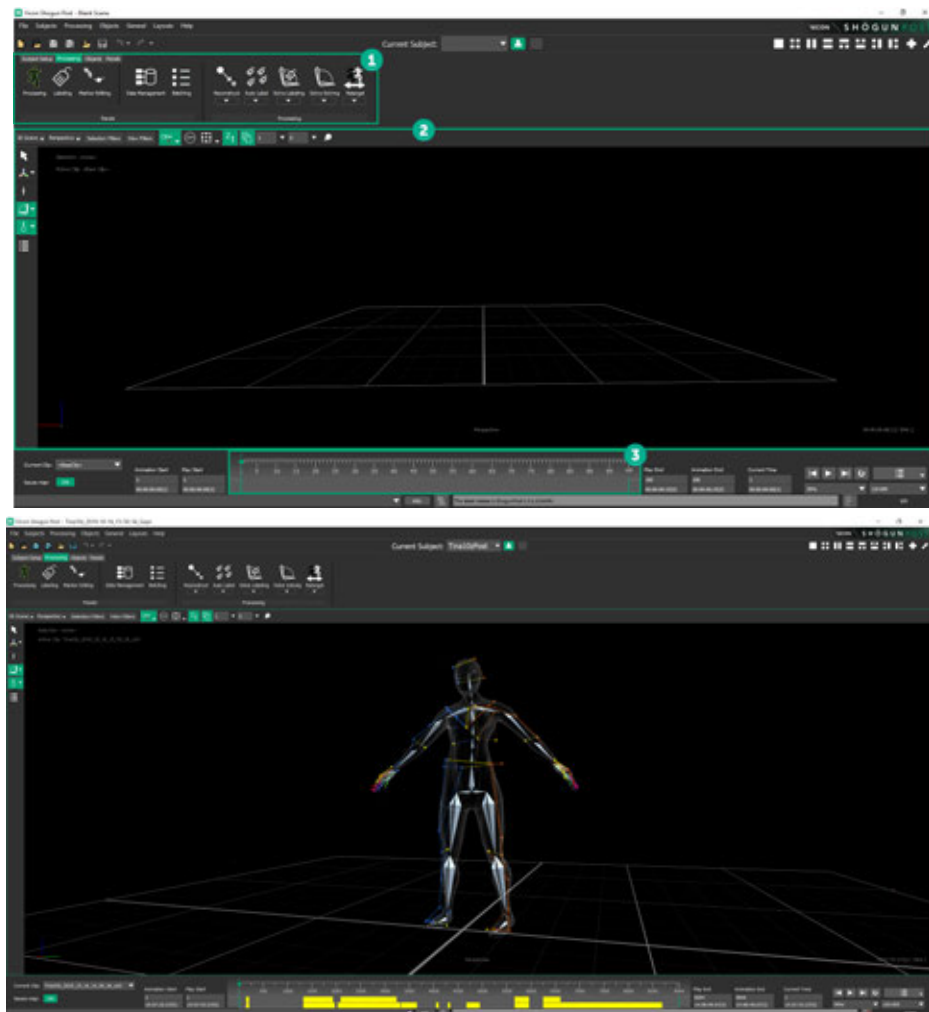
Post - Customize views

The default Shogun Post window is arranged to view and process a capture.

The Processing tab **1** is displayed on the ribbon. On the ribbon, the links to the panels are displayed in the order you are likely to want to use them (from left to right) and within each panel, the sections are arranged in order of a typical workflow.

Below the ribbon, a 3D Scene (Perspective) view **2** is displayed.

The default time bar **3**, which displays an issues heat map (colored horizontal bars that indicate gaps in your data) when you load a mocap file, is displayed at the bottom of the window.



Introducing Vicon Shogun

To find out more about loading data into Shogun Post and using the time bar issues map, see [Load mocap data files into Shogun Post \(page 154\)](#) and [Get an overview with the time bar Issues map \(page 166\)](#).

For more information about how you can change the view pane in Shogun Post, see:

- [About the 3D Scene view \(page 26\)](#)
- [Change the display in the view pane \(page 27\)](#)
- [Move the camera view \(page 28\)](#)
- [Change the view type \(page 29\)](#)

Introducing Vicon Shogun

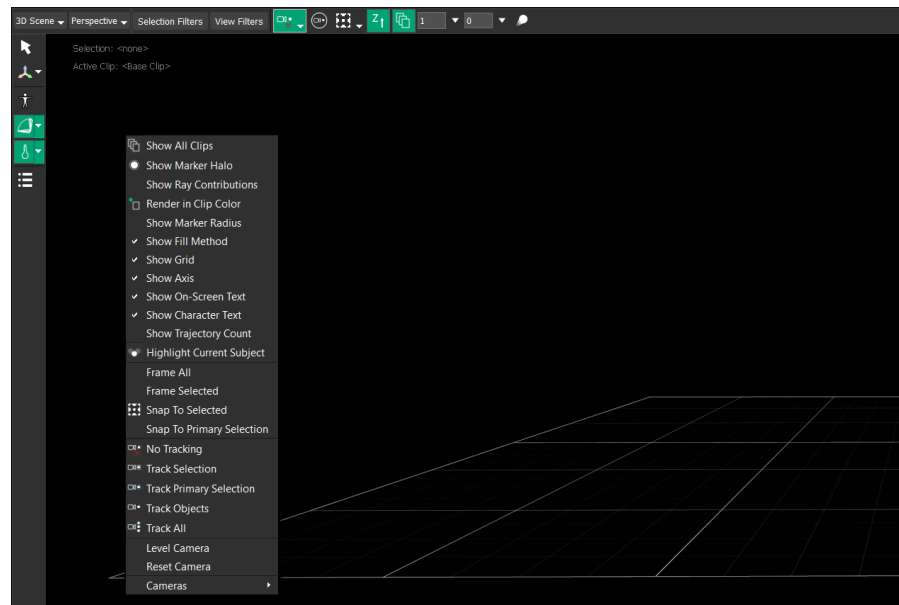
About the 3D Scene view

The default view in Shogun Post is the 3D Scene view, which displays reconstructed motion capture data from all active Vicon cameras in 3D perspective.

The 3D Scene view consists of a view pane and a toolbar (along the top). The toolbar contains buttons and menus to help you to manage the way 3D reconstructed data is displayed in the view pane.



A context menu (ALT+right-click) provides additional options that are not available from the toolbar.



To select a layout for the view, click a button at the top right of the quick access toolbar.

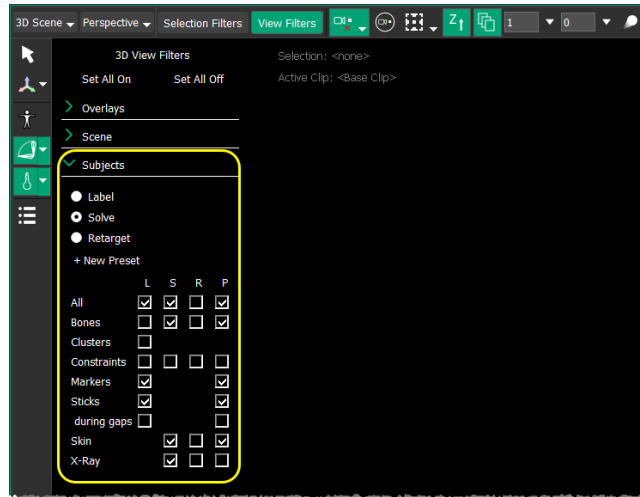


Introducing Vicon Shogun

Change the display in the view pane

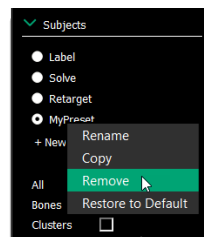
To change the type of data that is displayed in the view pane:

1. At the top of the view pane, click **View Filters**.
In the **Subjects** section, the view options are displayed in a matrix, with columns for Labeling, Solving, Retargeting and Props.
2. Choose a view configuration that suits your current task.



The default view filter sets are for labeling, solving, retargeting, and props, but you can add your own filter sets by clicking **New Preset**.

3. To rename, copy, remove or restore any filter set to its default value, right-click on a filter set and then click the required option.



Your settings, including any custom presets, are automatically saved, so that you can easily re-use them for different workflows.

Introducing Vicon Shogun

Move the camera view

In **Perspective** view panes, you can move the camera view in respect to the objects in the scene in the following ways:

To	Do this
Rotate (move the camera viewpoint around the focal point)	Click and drag
Translate (move the camera viewpoint along a horizontal or vertical axis)	Left- and right-click and drag
Zoom (move the camera viewpoint closer to or further away from the focal point)	Right-click and drag

The cursor changes shape for the intended navigation.

As you navigate the view pane, when the cursor reaches the edge of the pane, it wraps around to the other side to maintain a continuous movement, so you can keep dragging in one direction without having to release the mouse button.

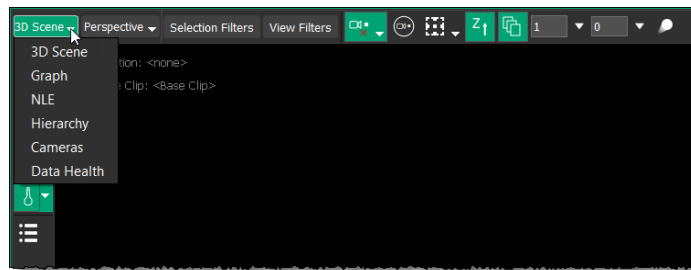
Introducing Vicon Shogun

Change the view type

In the view pane, you can change the type of data that is displayed, as well as the way in which the view is split, enabling you to view different types of data simultaneously. To save time, you can save and reload frequently used layouts.

To change the view type:

1. To select a different type of view, click the view type button at the top left of the view pane.



2. Select the required view from the list.

- **3D Scene:** 3D reconstructions of Vicon camera data.

To select options that affect what is displayed in the 3D Scene, click **View Filters** (see [Change the display in the view pane \(page 27\)](#)).

✓ Tips

- To view markers and bones through the skin, select the **X-Ray** view option.
- To pre-select (ie highlight) objects, giving you an indication of what is about to be selected, hover the mouse pointer over objects in the workspace.

When you choose the **3D Scene** view, you can also select a **Perspective** view, or orthogonal views:

- **Perspective** 3D view of data in the view pane
- **Front, Back, Right, Left, Top, or Bottom:** Orthogonal views of 3D data
- **Graph:** Manage keys which control the position of one or more markers on one or more frames

Introducing Vicon Shogun

- **NLE (Non Linear Editor):** Clips of multiple markers from multiple takes, or subsets from a single session
 - **Hierarchy:** Hierarchical view of objects in a scene, including markers, bones, actors and rigid bodies, showing the relationships between the objects.
 - **Video:** Digital video data from video cameras
 - **Cameras:** 2D optical data from Vicon cameras
 - **Data Health:** Enables you to identify gaps (represented by gray bars) in trajectory labeling for the currently selected markers
3. To select a layout for the view pane, click the required button at the right of the Shogun Post toolbar.



You can display a different view in each pane; for example, a 3D Scene view in one and a **Cameras** view in the other.

4. To save a favorite layout, on the **Layouts** menu, click **Export Custom Layout**. By default, custom layouts (*.hsl files) are saved to C:\Users\Public\Documents\Vicon\ShogunPost1.x\Layouts.

✓ **Tip**
If you want to return to the default layout, re-start Shogun Post and select the option **Reset workspace to default layout**.

For information on changing the layout and visibility of the panels, see [Post - Work with panels \(page 31\)](#).

Introducing Vicon Shogun

Post - Work with panels

All the panels that you use for working with data in Vicon Shogun Post are available from the ribbon at the top of the default layout.

When you first open Post, the **Processing** tab is selected, but you can view all the panels by clicking on the **Panels** tab.



On the ribbon, the panels are grouped into tabs that represent an area of activity. Each tab contains related panels and commands.

The tabs and the panels on them are arranged in the order you are likely to want to use them, from left to right.

To perform a task, on the ribbon, click the button that displays the required panel name, or click the equivalent command on the Vicon Post menu bar (above the quick access bar).

Note

The buttons toggle the display of the panels, so if you click on the button for a panel that is already open, the panel closes.

To find out more about working with panels in Shogun Post, see:

- [Rearrange panels \(page 32\)](#)
- [Hide/Display panels \(page 33\)](#)
- [Expand and collapse panel sections \(page 34\)](#)

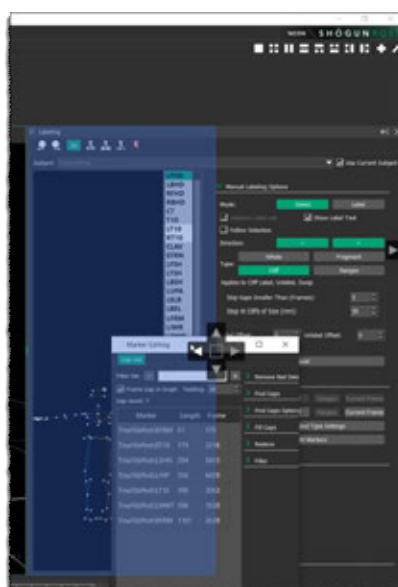
Introducing Vicon Shogun

Rearrange panels

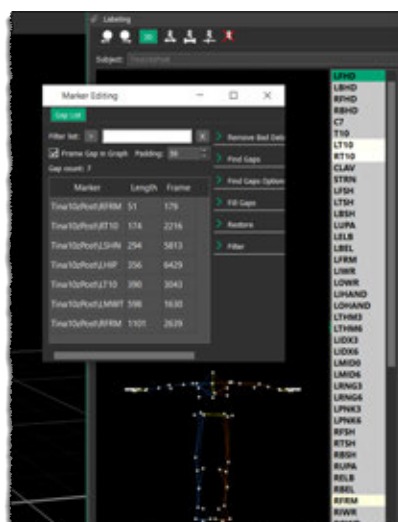
You can re-position and hide or display the panels to suit your way of working.

To re-position the panels:

Drag the panels by their title bars and drop them into place using the guides that overlay the main window:



If you prefer, instead of docking the panels as described above, you can leave panels floating in an independent window.



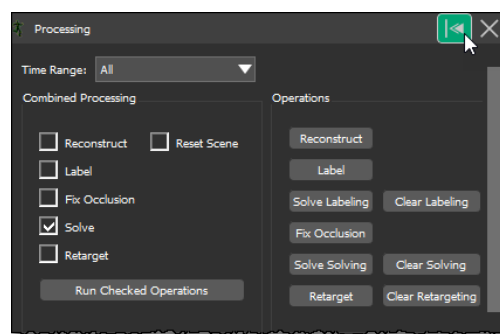
Introducing Vicon Shogun

You can also hide panels, to give you more space in which to work.

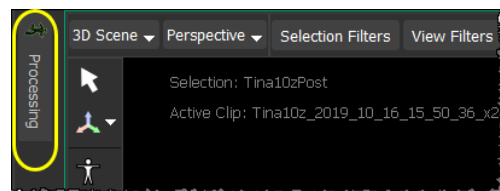
Hide/Display panels

To auto hide/redisplay a panel:

- On the title bar of a docked panel, click the Pin button.



The panel is hidden as a vertical tab along an edge of the main window.



If you auto hide multiple panels, they are tabbed vertically along the edge of the main window.




To re-display a pinned panel:

1. Click the required tab on the edge of the main window.
The panel is displayed in a floating window.
2. To dock it again, click its Pin button.

Introducing Vicon Shogun

Expand and collapse panel sections

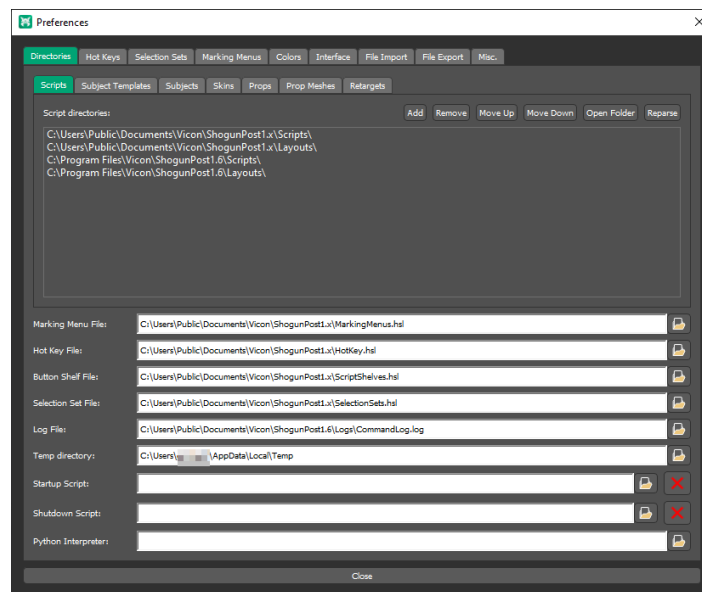
Within each panel, you can expand and collapse sections, to make it easier to access the controls you want to use.

Action	Mouse
Expand section	Click the right-pointing arrow 
Collapse section	Click the downward-pointing arrow 
Show/hide further options	Click the ellipsis 

Introducing Vicon Shogun

Post - Set preferences

To access and change preferences such as folder locations, hot keys and default import and export options, as well as how you interact with the Shogun Post interface, you use the Preferences dialog box.



These topics introduce some of the ways you can customize Post.

- [Change Shogun Post folders \(page 36\)](#)
- [Set script folder locations \(page 37\)](#)
- [Set file names and folder locations \(page 39\)](#)
- [Set pre-selection options \(page 40\)](#)
- [Set a custom folder for saving subjects \(page 41\)](#)
- [Scale missing markers \(page 41\)](#)
- [Hold Ctrl to use the Manipulator \(page 42\)](#)

Introducing Vicon Shogun

Change Shogun Post folders

You set the location of Shogun Post folders and files on the **Directories** tab in the **Preferences** dialog box.

To open the **Preferences** dialog box:

1. On the **General** menu click **Preferences**.
2. In the **Preferences** dialog box click the **Directories** tab.

The **Directories** tab contains fields that enable you to specify the location of:

- Scripts folders. For more information, see [Set script folder locations \(page 37\)](#) .
- Marking Menu file, Hot key file, Button shelf file, Selection set file, Log file, Temp directory, Startup script, Shutdown script, Python interpreter. For more information, see [Set file names and folder locations \(page 39\)](#) .



Tip

The Marking Menu, Hot Key, Button Shelf, and Selection Set files are saved as Shogun scripts (.hsl files). These default Shogun .hsl files are stored in the Shogun Post folder (by default, C:\Users\Public\Documents\Vicon\ShogunPost#\#). You might find it useful to create different .hsl files to store particular categories of these files and/or to create your own folder for storing any of these files that you create or customize. You can specify the location of this folder in the appropriate fields on the **Directories** tab.

Introducing Vicon Shogun

Set script folder locations

The Shogun Post *Scripts* folder contains the default scripts supplied with Shogun Post, organized by category into sub-folders. By default, the *Scripts* folder is installed under the main Shogun Post program folder (*C:\Program Files\Vicon\ShogunPost#\Scripts*). Scripts in this folder can be selected from the **Pipelines** panel and the **Script Viewer** dialog box (available from the **Script Editor** toolbar and the Shogun Post status bar).

You can specify more than one *Scripts* folder on the **Directories** tab, but Shogun executes the first version of a given script file that it finds. That means that if you have two script files named *greatScript.hsl*, Shogun will execute the first one it finds as it searches the specified script folders in the order in which they appear in this field. You can use this search order to control when customized scripts are used over standard Shogun scripts.

Review the default scripts in the *Scripts* folder and all its sub-folders because they may save you time. Each script supplied with Shogun is documented, so you can quickly determine its function and modify its commands to meet your own needs. Most Shogun Post users find that these scripts can streamline many standard operations as written, and they also can be customized to meet other needs as required. For more information on using scripts, see the HSL scripting with Vicon Shogun.

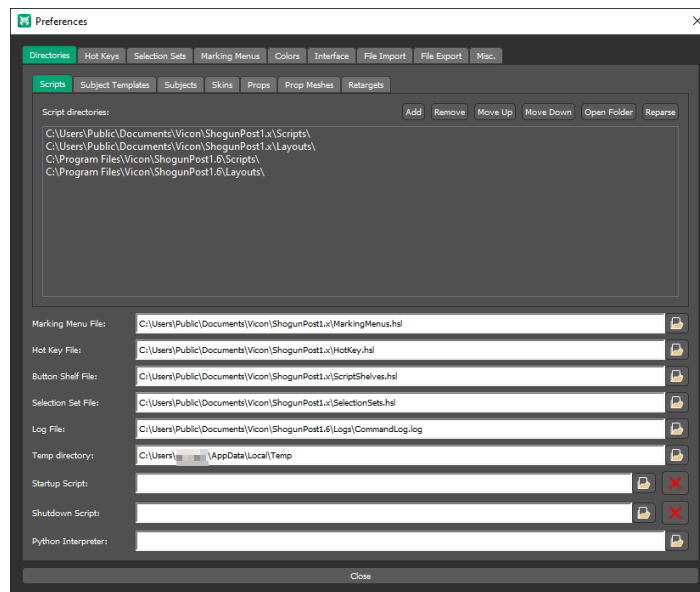
 **Important**

Ensure you save a custom version of a Shogun script under a new file name. This ensures that if your script doesn't work, you still have the original.

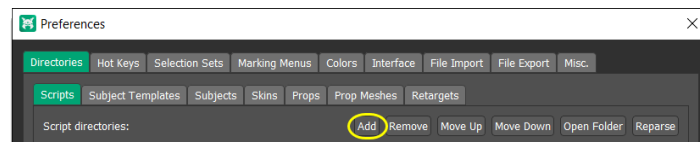
Introducing Vicon Shogun

To specify additional script file locations:

1. On the **General** menu click **Preferences**.
2. In the **Preferences** dialog box, click the **Directories** tab and view the **Script** directories section.



3. For each folder that you want to add, in the **Script** directories mini toolbar, click the **Add** button.



4. In the **Select folder** dialog box, enter or browse to the desired location.

You can also perform the following operations:

- Remove a selected script directory from the **Script** directories list.
- If you have specified multiple directories, use the **Move selected script up** and **Move selected script down** buttons to arrange the directories in the desired order.
- To view folder contents, select a folder in the list and click the **Open Folder** button on the toolbar.
- To update the contents of the selected folder, click the **Reparse** button.

Introducing Vicon Shogun

Set file names and folder locations

As well as specifying the location of scripts (see [Set script folder locations](#) (page 37)), you can specify a different location for the following files (and temp folder) on the Directories tab in the Preferences dialog box (General menu > Preferences).

Field	Description	Default location	Default file
Marking Menu file	Default marking menus.	C: \Users\Public\Documents\ Vicon\ShogunPost#.#\	MarkingMenus .hsl
Hot key file	Hot key mappings.	C: \Users\Public\Documents\ Vicon\ShogunPost#.#\	HotKey.hsl
Button shelf file	Script used by Shogun Post to build the Button Shelf interface. The button shelf tabs are displayed as custom tabs on the ribbon.	C: \Users\Public\Documents\ Vicon\ShogunPost#.#\	ScriptShelves. hsl
Selection set file	Script used by Shogun Post to store selection set settings.	C: \Users\Public\Documents\ Vicon\ShogunPost#.#\	SelectionSets. hsl
Log file	Multi-session text log file that contains the data displayed in the Log window.	C: \Users\Public\Documents\ Vicon\ShogunPost#.#\Logs	CommandLog. log
Temp directory	Contains files that may be used by Vicon Support	C: \Users\ <i><UserName></i> \AppD ata\Local\Temp	NA
Startup script	Script that runs when you start Shogun Post.	User-specified	User-specified
Shutdown script	Script that runs when you exit Shogun Post.	User-specified	User-specified

Introducing Vicon Shogun

Field	Description	Default location	Default file
Python interpreter	64-bit version of Python used by Shogun Post. For more information, see HSL scripting with Vicon Shogun.	C:\Program Files\Vicon\ShogunPost#\Python\	python.exe

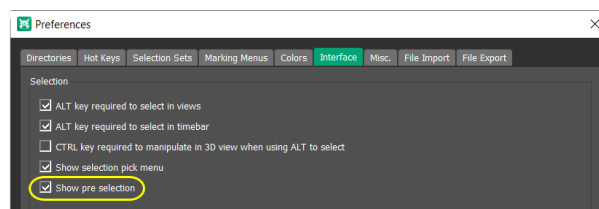
You may find it useful to create your own folder and/or filename for storing any files you create or customize.

To specify a custom location:

1. Open the **Preferences** dialog box (see [Specify Vicon Shogun Post folders](#) (page 36)).
2. Click the **Directories** tab, and view the relevant field.
3. To the right of the field, click the **Open** button.
4. In the dialog box, enter or navigate to and select the appropriate file or folder that Shogun Post is to use and click **Open**.
You can click this **Open** button to open any previously saved *.hsl* files at any time during a Shogun Post session.

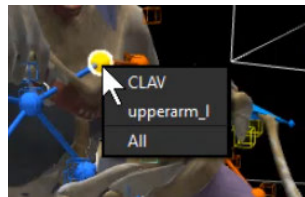
Set pre-selection options

While pre-selection (the highlighting of the marker or object that the mouse pointer is currently hovering over) is useful in some circumstances, in others it may be distracting. In the **Preferences** dialog box (**General > Preferences**), an option on the **Interface** tab enables you to choose whether to show pre-selection in the 3D Scene view.



Introducing Vicon Shogun

A related option, **Show selection pick menu**, enables you to choose whether to display the menu that is displayed when you hover the mouse pointer over several markers or objects that are on top of each other. When selected, you can quickly choose from a list of markers or objects, without having to use the Selection filters.



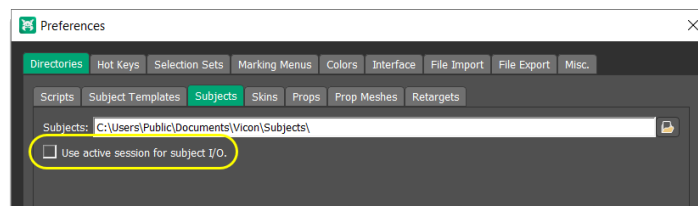
When cleared, no menu is displayed and you can select only the object that is directly under the mouse pointer.

 See also [Vicon Shogun 1.3 Post Tutorial - Selection Toggles⁶](https://youtu.be/i04aVAvYZ8w) on YouTube.

Set a custom folder for saving subjects

To change the default folder to which to save subjects, in the **Preferences** dialog box, click the **Subjects** tab, where you can browse or specify the required folder.

You can also specify that the current Eclipse session is used by selecting **Use active session for subject I/O**.



Scale missing markers

To scale the displayed size of missing markers, in the **Preferences** dialog box, click the **Interface** tab and at the bottom, change the value of the **Missing Marker Size Multiplier** (the default is 2.50).

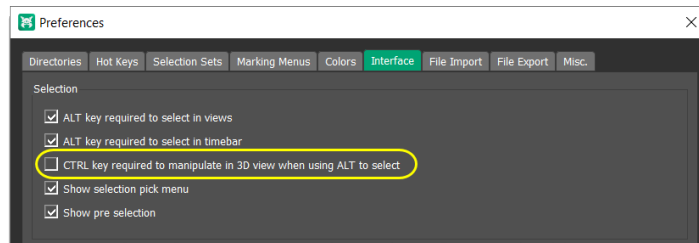
⁶ <https://youtu.be/i04aVAvYZ8w>

Introducing Vicon Shogun

Hold Ctrl to use the Manipulator

To avoid accidentally manipulating objects when using the Alt key to select, you can turn on the requirement for the Ctrl key be held down to manipulate objects in the 3D Scene view by selecting this option on the **Interface** tab of the **Preferences** dialog box.

By default, the option is set to off.



Introducing Vicon Shogun

Post - File types

The following tables list the different types of file that may be used in Shogun:

- [Shogun Post export file types \(page 44\)](#)
- [Shogun Post import file types \(page 45\)](#)
- [Shogun Post internal file types \(page 46\)](#)

Introducing Vicon Shogun

Shogun export file types

This table lists file types that you can export from Shogun Post.

File extension	Description
BVH	BioVision Hierarchy file
C3D	Binary motion file
CSM	Character Studio Motion file
FBX	FBX motion file
MCP	Vicon motion capture file
TRC	Motion Analysis Trajectory file (marker data)
USD	Pixar USD file
VSK	Vicon Labeling Setup file
VSR	Vicon Retargeting Setup file
VSS	Vicon Solving Setup file
VST	Vicon Labeling Setup file
XCP	Vicon Extended Camera Parameter file

Introducing Vicon Shogun

Shogun import file types

This table lists file types that you can import into Shogun Post.

File extension	Description
AMC	Acclaim Motion file
ASF	Acclaim Skeleton File
BVH	BioVision Hierarchy file
C3D	Binary motion file
CP	Legacy (Vicon iQ) Vicon Camera Parameterization file
CSM	Character Studio file
FBX	FBX file
HCD	Compressed Display file
HDF	Blade Data File
HTR	Motion Analysis Skeleton file
MCP	Real-time data recorded with Vicon Shogun Live
MKR	Marker Set file
OBJ	Wavefront Object file
TRC	Motion Analysis Trajectory file
TXT	Camera Track file
USD	Pixar USD file
VDF	Shogun Post Data file
VSK	Vicon Labeling Setup file
VSR	Vicon Retargeting Setup file
VSS	Vicon Solving Setup file

Introducing Vicon Shogun

File extension	Description
VST	Vicon Labeling Setup file
WAV	Wave Audio file
X2D	Vicon Video Data file
XCP	Vicon Extended Camera Parameter file

Shogun Post internal file types

This table lists file types and files that are created and used within Shogun Post:

File name	Description
*.hbc	Batch configuration file
*.history	Lists all commands executed since Shogun Post was opened. Located in same folder as CommandLog.log.
*.hsl	HSL script file
*.plf	Pipeline file
CommandLog.log	Log file. Located in the folder specified on the Directories tab (by default, C:\Users\Public\Documents\Vicon\ShogunPost#\#\Logs). For more information, see Post - Set preferences (page 36).
HardwareSettings.xml	Hardware settings for each take. Can be loaded into Shogun Post.
LatestCalibration.xcp	Data about the last calibration. You may be asked for this by Vicon Support to aid troubleshooting.

Introducing Vicon Shogun

Post - Hot keys and shortcuts



Tip

To see a list of all current hot keys, on the **General** menu, click **Preferences** and then click the **Hot Keys** tab.

To create your own hot keys, in the **Command/Script** column, double-click the required command or script and in the **Set Hot Key** dialog box, specify the hot keys.

The following topics list commonly used shortcuts and explain working with objects, selection, and the context-sensitive menus.

- [Set hot keys in Post \(page 48\)](#)
- [Preserve your hot keys \(page 49\)](#)
- [3D Scene view shortcuts \(page 50\)](#)
- [Data Health view shortcuts \(page 51\)](#)
- [Graph view shortcuts \(page 52\)](#)
- [Work with objects \(page 53\)](#)
- [Work with the ALT key \(page 53\)](#)
- [Selecting and context-sensitive menus \(page 54\)](#)

Introducing Vicon Shogun

Set hot keys in Post

If you want to change what happens when you press a particular key or combination of keys, you can assign or un-assign commands to hot keys. The following instructions describe how to set or clear hot key for displaying the marking menu, but can be applied to any command for which you want to set a hot key.

To assign or clear hot keys:

1. Open the Preferences dialog box (**General > Preferences**).
2. Click the **Hot Keys** tab.

✔ **Tip**

If you are clearing a hot key, you can save time by showing only the commands or scripts that have hot keys assigned to them. To do this, at the top, select **Show hot keyed only**.

3. Click the required command, for example **showMarkingMenu** to select it and then double-click to display the **Set hot key** dialog box, where you can set or clear the hot key for it.
4. Close the Preferences dialog box.

Introducing Vicon Shogun

Preserve your hot keys

When you install Shogun Post, the latest hot key file (*HotKey.hsl*) is installed in:

`C:\Program Files\Vicon\ShogunPost1.#\DefaultConfiguration`

However, the hot key file (*HotKey.hsl*) that Post uses by default is in:

`C:\Users\Public\Documents\Vicon\ShogunPost1.x`

To preserve any hot keys that you may have added, this file isn't modified by the installation. Post only recreates the hot key file from `\DefaultConfiguration` if a hot key file doesn't exist.

Update a hot key file

To install a later version of Post that includes updates to the hot key file:

1. Before installing the new hot key file as described in Step 2, save any hot keys that you have added by copying to another location the hot key file (*HotKey.hsl*) in:

`C:\Users\Public\Documents\Vicon\ShogunPost1.x`

2. Install the new hot key file in either of these ways:

- Before installing the latest version of Shogun Post, to force Post to use the new hot key file, delete *HotKey.hsl* in:

`C:\Users\Public\Documents\Vicon\ShogunPost1.x`

or

- After installing the latest version of Shogun Post, copy *HotKey.hsl* from:

`C:\Program Files\Vicon\ShogunPost1.#\DefaultConfiguration`

over the old hot key file in:

`C:\Users\Public\Documents\Vicon\ShogunPost1.x`

3. To restore your custom hot keys, open the file you saved in Step 1 and manually copy your custom hot keys to the new *HotKey.hsl* file.

Introducing Vicon Shogun

3D Scene view shortcuts

Action	Mouse/Hot key
Rotate	Click and drag
Zoom	Right-click and drag
Translate	Left- and right-click and drag
Snap the 3D view to selected object(s) without tracking	C
Track the selected object(s) and enable you to change the selection without stopping tracking the originally selected object.	X To stop tracking, click C.
Scale the manipulator	Press + (scale up) or - (scale down)
Switch between Label and Select modes when labeling a subject	L
Create a retargeting constraint between the selected solving and retargeting bones, or a solving constraint between the selected solving bone and marker. (In either case, the order of selection doesn't matter.)	CTRL+T
Create a retargeting rotation constraint between the selected solving and retargeting bones. (The order of selection doesn't matter.)	CTRL+R
In Labeling mode (in the Labeling panel, in the Manual Labeling Options, select Label), with the mouse in the view pane and the Labeling panel open, move up and down the list of labels.	Shift+click to go up through the list Shift+right-click to go down through the list

Introducing Vicon Shogun

Data Health view shortcuts

Action	Mouse/Hot key
Move current time indicator	Middle mouse button and drag*
Step through time	Middle mouse button (wheel) scroll
Zoom timeline	Right-click and drag
Pan (horizontally and vertically)	Click and drag or left- and right-click and drag
Select a time range	ALT+drag
Add time ranges to selection	CTRL+ALT+drag
De-select within selected range	SHIFT+ALT+drag
Select a gap (and marker)	Double-click on a gap
Select a gap (and marker) in addition to the currently selected gap	CTRL+double-click on a gap
De-select gap and marker	SHIFT+double-click selected gap
Select/deselect whole play range	ALT+double-click
Sort markers	ALT+right-click, then select required sorting method

*Also scrubs timeline in **Cameras** view

Introducing Vicon Shogun

Use the following key combinations to select markers in the marker list at the left of the Data Health view.

Action	Mouse/Hot key
Select one or more markers	ALT+click (drag to multi-select)
Add further markers to selected markers	CTRL+ALT+click
De-select a selected marker	SHIFT+ALT+click
De-select all markers	ALT+double-click

Graph view shortcuts

Use the following key combinations to scrub and resize the graph axes:

Action	Mouse/Hot key
Horizontal zoom (expand or collapse the graph's time axis)	Right-click+drag left or right
Vertical zoom (expand or collapse the graph's value axis)	Right-click+drag forward or backward
Translate right/left (scrub along the graph's time axis)	Click+drag left or right
Translate up/down (scrub along the graph's value axis)	Click+drag forward or backward

Introducing Vicon Shogun

Work with objects

Use the following key combinations to work with Shogun Post objects.

Action	Mouse
Select	Click on single object, CTRL+click and SHIFT+click on multiple objects. You can also drag to select (or if ALT key to select in views is selected (see below), ALT+drag)
Add to/Remove from selection	CTRL+click or SHIFT+click on multiple objects.
Manipulate object	Click manipulator handle and drag
Duplicate objects	Select object and press Ctrl+D
Select all child objects	Right-click (or ALT+right-click) on an object and then click Select Branch to select all its child objects

Work with the ALT key

To change the behavior of the ALT key:

1. On the **General** menu, click **Preferences** and in the **Preferences** dialog box, click the **Interface** tab.
2. In the **Selection** area, clear or select **ALT key to select in views**.
This sets the ALT key as required when selecting.

When **ALT key to select in views** is cleared, the default behavior is selection without the ALT key.

Introducing Vicon Shogun

Selecting and context-sensitive menus

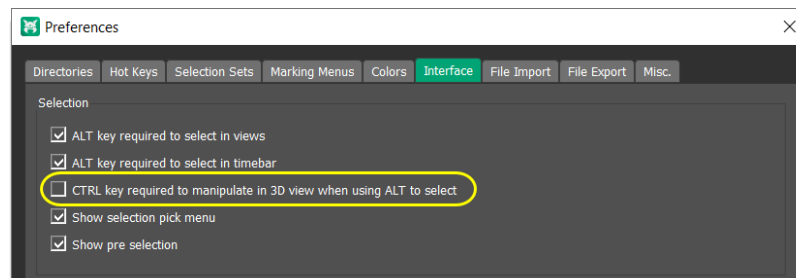
The context-sensitive menus in the **Perspective** and **Graph** views are sensitive to selection. When objects are selected, the menu may list commands based on the options available for the selected object. The list of available commands may also depend on factors such as the state or condition of the data in a selected object. For example, commands to fill a gap on a marker are displayed in a context menu only if there is a gap at the current frame.

To access selection-sensitive context menus:

- When **ALT key to select in views** is selected in the **Preferences** dialog box, use ALT+CTRL+ right-click.
- When **ALT key to select in views** is cleared in the **Preferences** dialog box, use ALT+ right-click.

To avoid accidentally manipulating objects when using the ALT key to select:

You can turn on the requirement for the CTRL key be held down to manipulate objects in the 3D Scene view by selecting this option on the **Interface** tab of the **Preferences** dialog box. By default, the option is cleared (off).



Prepare your Vicon system

Prepare your Vicon system

It is assumed that your Vicon system hardware (including the Vicon cameras, Vicon connectivity units, and any supported third-party devices) has been set up and connected and that Shogun is installed and licensed.

If you're installing your Vicon system yourself, see the Vicon documentation that was supplied with your hardware and Installing and licensing Vicon Shogun, together with any relevant videos (see the video links below). If you need further help with setting up your Vicon system, please contact [Vicon Support](#)⁷.

Important

When you start Shogun Live or connect Vicon devices into your system, Shogun checks to see whether the firmware for all your devices is up-to-date. If your devices aren't using the latest firmware, Shogun displays an icon in the toolbar to let you know that a more up-to-date version of the firmware is available. To benefit from the latest enhancements and bug fixes for your Vicon system, click the icon and update your firmware. (The Vicon Firmware Update Utility is installed with the latest version of Shogun. If you don't have the Vicon Firmware Update Utility, download it from the [Vicon website](#)⁸.)

To prepare your Vicon system for motion capture with Vicon Shogun Live, you'll need to complete these procedures in this order:

- [Create a folder hierarchy to store takes](#) (page 57)
- [Position the cameras and markers](#) (page 59)
- [Check the coverage of the capture volume](#) (page 60)
- [Adjust the focus and aperture](#) (page 61)
- [Optimize camera settings](#) (page 65)
- [Set timecode \(optional step\)](#) (page 67)
- [Prepare video cameras \(optional step\)](#) (page 71)

⁷ <mailto:support@vicon.com>

⁸ <https://www.vicon.com/software/camera-firmware/>

Prepare your Vicon system

You can watch a Vicon video: [2 - Shogun Live - System Setup](#)⁹, which shows these steps. (If your system includes Vicon video cameras, see also [3 - Shogun Live - Setting up Vue video camera](#)¹⁰.)




⁹ <https://vimeo.com/218944963>
¹⁰ <https://vimeo.com/218944968>

Prepare your Vicon system

Create a folder hierarchy to store takes

Before you begin motion capture with Vicon Shogun Live, you must create a hierarchy of folders in which to store the files associated with your motion capture takes. You can do this either in Vicon Shogun Post or in Vicon Eclipse running as a standalone application.

To create the folder hierarchy to store your takes:

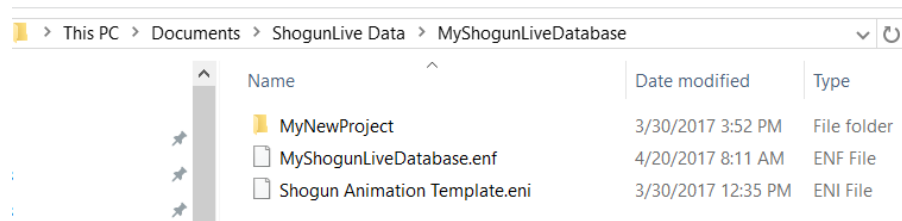
1. Start Vicon Shogun Post  or Vicon Eclipse .
2. If you are using Shogun Post, open the **Data Management** panel (press F2, or on the **Panels** tab on the ribbon, click **Data Management**).
3. In the **Data Management** panel or in Eclipse, click the **Create a new database** button . (Note that the the Eclipse buttons are slightly different from the Data Management ones, but their function is the same.)
4. In the **New Database** dialog box:
 - a. In the **Location** field, browse to or enter the required location. This can be anywhere where you normally save data, for example in your **Documents** folder.
 - b. In the **Name** field, supply a name and (if required) a description in the **Description** field.
 - c. In the **Based on** list, click **Shogun Animation Template.eni**.
5. Click **Create** and in the next dialog box, ensure your new database is selected and click **Open**.

Prepare your Vicon system

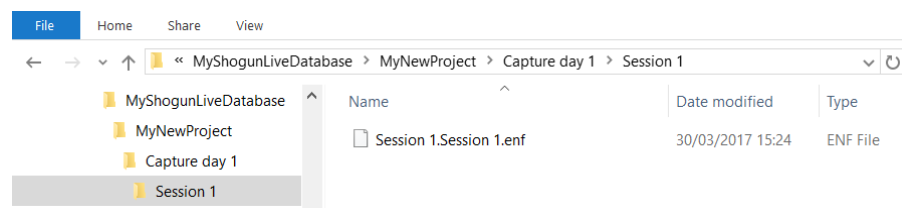
6. In the Data Management pane, create the structure in which Shogun Live will store your take:
 - a. Right-click in the window, point to **New** and then click **Project** and supply a suitable name for your project.
 - b. Click in the **Project** line you just created, then right-click, point to **New** and click **Capture day**.
 - c. Click in the new **Capture day** node, right-click, point to **New** and then click **Session**.

	DATE	CHILDCOUNT(TRIAL)	LASTCALIBRATIONFILE	LASTMASKFILE	LASTTHRESHOLDTABLEFILE	DESCRIPTION	NOTES
MyNewProject							
Capture day 1		1 Session					
Session 1	17/02/2017	? Takes					

7. Open Windows Explorer and view the folder structure you just created.



Note that the `.enf` file has the name you gave to your database. It contains the file structure instructions to Eclipse that tells it which is the main folder and which are the subfolders for this database. The subfolder structure reflects the Project, Capture day and Session that you specified. Each subfolder contains an `.enf` file that indicates to Eclipse where it belongs in the hierarchy.



You now have an active session, ready to store your Shogun Live takes.

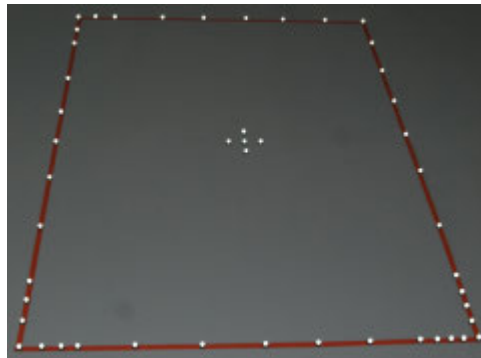
Before you begin capturing, to save your captured takes into the newly created folder hierarchy, you will specify the path to it in Shogun Live, as described in [Capture a take \(page 132\)](#).

Prepare your Vicon system

Position the cameras and markers

With your Vicon system set up, installed and licensed, the first task in setting up your capture space is to position the cameras and markers.

1. Position your cameras around the capture volume, ensuring that two or more cameras can see every point in the volume in which you intend to capture motion.
2. Place Vicon retroreflective markers around the floor to outline your capture volume.



✔ Tip

You may find it helpful to create an asymmetrical pattern along the perimeter, as shown above, to help orient your view. For example, for a rectangular volume, place a different number of markers at each corner. For an elliptical volume, vary the spacing between markers as you place them around the perimeter.

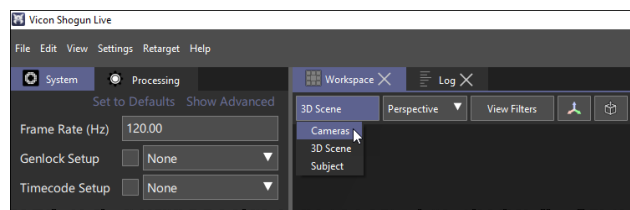
3. Place five markers in a cross shape to identify the volume origin.

Prepare your Vicon system

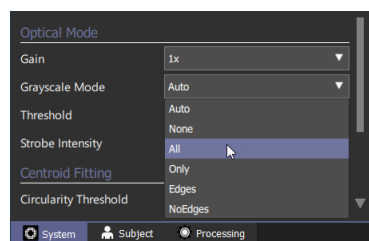
Check the coverage of the capture volume

After you have positioned cameras and markers in the capture volume, the next task is to ensure that the cameras can see the whole of the volume.

1. Ensure your cameras are physically connected to the system (for details, see the hardware documentation supplied with your Vicon system).
2. Switch on your Vicon system and start Vicon Shogun Live.
3. In the **System** panel (by default located on the left of the Shogun Live window), SHIFT+click to select all the cameras or, for a large number of cameras, right-click and click the relevant **Select All** option.
4. In the **Workspace** ensure that the **Cameras** view is selected.



5. Keeping all the cameras selected, in the **Optical Mode** section below, change **Grayscale Mode** to **All**.



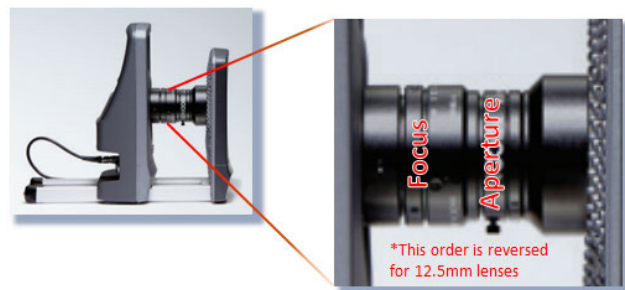
6. Using the default lens settings on each camera, ensure that:
 - You can see 2D marker images from each connected optical camera.
 - Two or more cameras can see every point in the volume in which you intend to capture motion.

Prepare your Vicon system

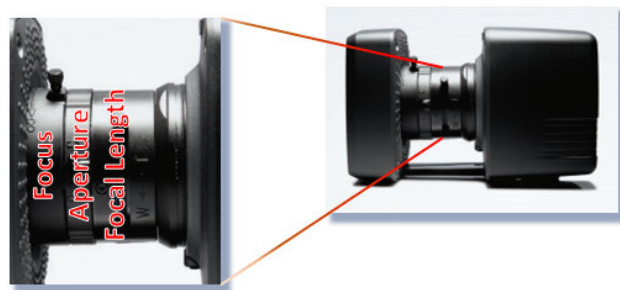
Adjust the focus and aperture

To achieve a good marker image you may need to adjust the camera lens. Depending on your Vicon camera model, you may find two or three adjustment rings on the lens. These control the focus and aperture, and if the camera has an additional ring, the focal length.

Vicon MX T-Series:



Vicon Bonita:



Vicon Vantage:



For Vantage cameras (as with T-Series cameras), for 8.5 and 12.5 mm lenses, the order of the aperture and focus rings is the reverse of that shown.

Prepare your Vicon system

Vicon Vero:



Vicon Viper:



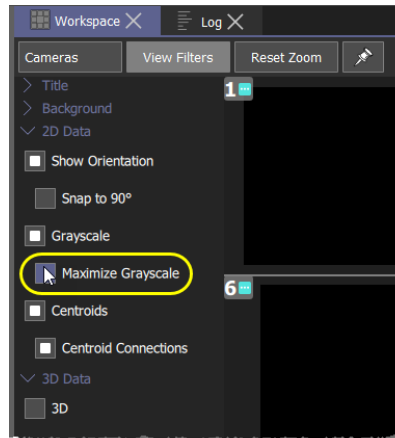
Vicon ViperX:



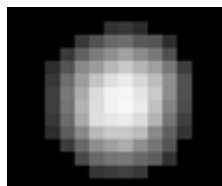
Prepare your Vicon system

To focus a camera:

1. To make focusing easier, in the **View Filters**, go to the **2D Data** options and select **Maximize Grayscale**, which zooms the view into any visible markers.

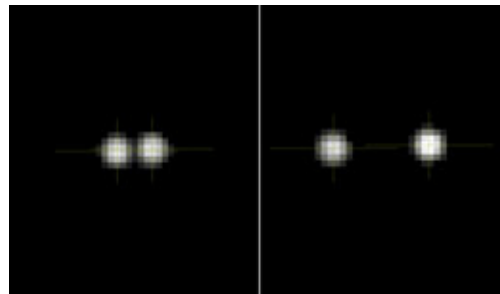


2. Fully open the Aperture ring.
3. Adjust the Focus ring so that the markers become round and clear. As you rotate the focus ring, notice the marker images get smaller and then at some point will begin to get larger again. Good focus is when the marker is at its smallest size. Leaving this setting at infinity ∞ is normally suitable. Aim for a marker image similar to the following:



Prepare your Vicon system

4. Close the **Aperture** ring so that as much background noise as possible is removed without compromising the quality of the marker image. Try to obtain good, clear images of markers even when they are close together, as shown in the following image, where the markers on the left are touching. The markers should not be too small, and the center should be just off-white (not fully saturated) when viewed from the middle of the volume.



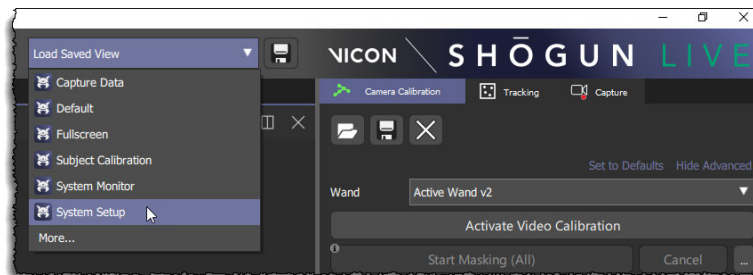
Prepare your Vicon system

Optimize camera settings

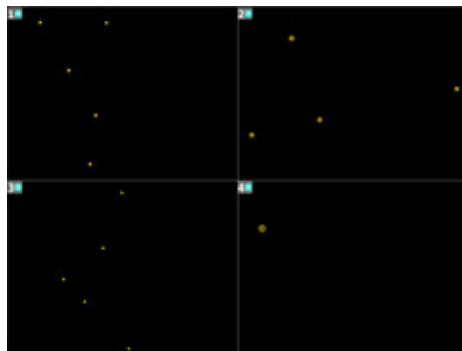
To ensure optimum marker recognition, you adjust the camera settings in Shogun Live.

To optimize camera settings:

1. In Vicon Shogun Live, make sure you are viewing 2D data from your cameras in one or more **Cameras** views. (To display the necessary layout, you can click the **Load saved view** list in the menu bar near the top of the Shogun window, then click **System Setup**.)



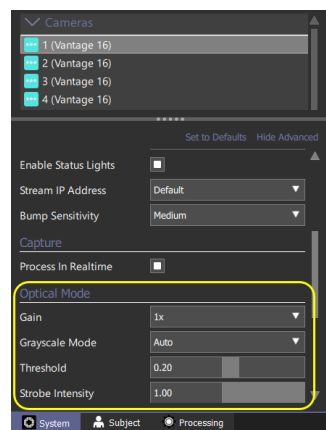
2. Have someone wave the calibration device around in the capture volume and ensure you can see marker images moving in each **Cameras** view.



Prepare your Vicon system

3. In the **System** panel, SHIFT+click to select all the cameras, go to the **Optical Mode** section below and adjust the following camera settings as necessary:
 - **Gain:** To start with, leave the setting at the default of 1x to ensure 2D marker images are bright enough to see clearly. If the markers appear too faint or if the cameras have trouble distinguishing them, adjust this setting.
 - **Threshold:** A good starting value is 0.2 to 0.3. This setting determines the minimum value at which data is registered by pixels on the camera sensor and considered for circle fitting. As this setting acts like a high-pass filter, reducing this value increases the data that can pass through the sensor.
 - **Strobe Intensity:** Adjust this setting to increase the effective brightness of the strobe and therefore the distance at which and clarity with which it is likely to illuminate. A good starting value is 1.0 (100%), which is why this is the default setting.

If you need to further adjust any of the above settings for individual cameras, in the **System** panel, click the name of the relevant camera and change the required setting(s) in the **Optical Mode** section.



When you have finished focusing and optimizing the cameras, with all cameras selected, in the **Optical Mode** section change **Grayscale Mode** back to **Auto**.

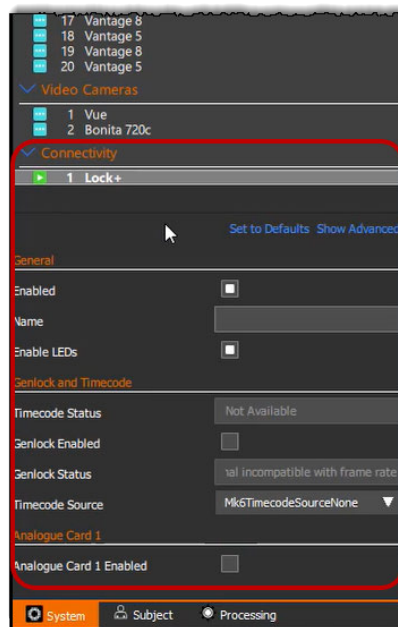
Prepare your Vicon system

Set timecode (optional step)

If your system includes an external timecode generator, before you calibrate the cameras, you must set the required timecode in Shogun Live.

To set the timecode:

1. In the **System** panel, in the **Connectivity** section, click on your device to view its current settings.



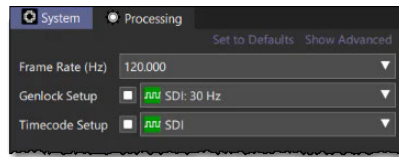
2. At the top of the **System** panel, view the system settings.
3. In the **Frame Rate (Hz)** list, select the required frame rate.

✔ If you're tracking fast-moving props, for best results, choose a reasonably high frame rate (100–120 Hz) and ensure the rate of dropped frames is minimal.

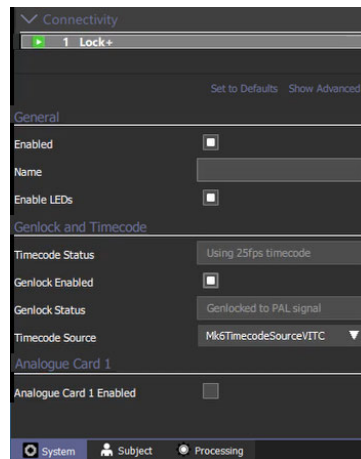
(For information about using High Speed mode, which enables you to run Vicon Vantage cameras at higher frames rates while maintaining the FOV, see [Use High Speed mode to run Vantage cameras at higher frame rates](#) (page 69).)

Prepare your Vicon system

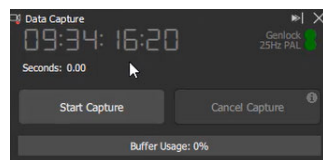
- To use a genlock standard, ensure the **Genlock Setup** option is selected and from the **Genlock Setup** list, select the standard you want to use. Similarly, if required, enable the **Timecode Setup** option and select a timecode standard from the **Timecode Setup** list. The following example shows the SDI standard and a frame rate of 120 selected:



- In the **Genlock and Timecode** section for the selected connectivity device, to enable genlock, select the **Genlock Enabled** check box.
- In the **Timecode Source** list, select the required option.



- In the **Data Capture** panel (by default displayed at the bottom of the **Camera Calibration** panel, on the right of the **Shogun Live** window), the timecode is now displayed.



Prepare your Vicon system

It is also shown as part of the information displayed at the bottom of the Workspace.



Use High Speed mode to run Vantage cameras at higher frame rates

Shogun 1.5 and later supports the use of the Vantage+ firmware upgrade (Firmware 725 and later), enabling you to use **High Speed** mode with your Vantage cameras without having to change the field of view (FOV) or lens. When you capture optical data, subsampling (selectively reducing the pixel count) enables you to run at high camera frame rates without reducing the FOV (frame size). You can change frame rates during capture and you don't need to set up your cameras again when you increase the frame rate, as the FOV is unchanged.

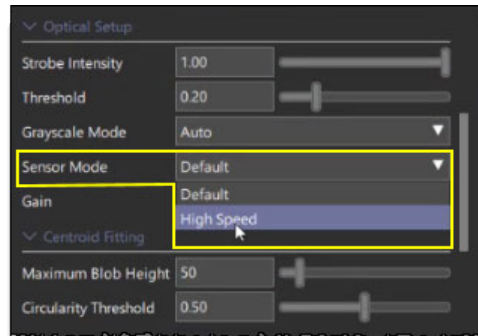
Note that because the higher speeds are achieved through subsampling (removing some pixels from the frames), some reduction in resolution is incurred. For details, see High-speed mode in the *Vicon Vantage Reference Guide*.

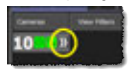
To select high-speed mode:

1. In Vicon Shogun Live, in the **System** panel, click in the **Frame Rate** list and set the system frame rate to the speed you want to use in **High Speed** mode. A warning may temporarily be displayed, alerting you to the discrepancy between the requested frame rate and the actual system frame rate, until you select high speed mode for all the relevant cameras, as explained next.
2. In the **System** panel, select one or more cameras.

Prepare your Vicon system

3. In the camera properties below, ensure the **Advanced** properties are displayed and in the **Optical Setup** section, click the **Sensor Mode** menu and select **High Speed**.



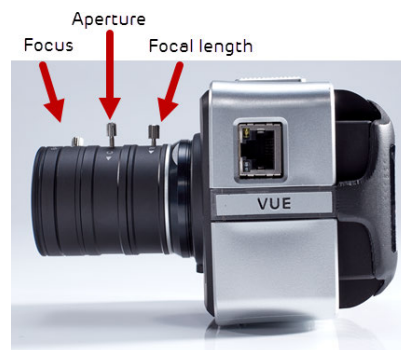
In the **Cameras** view pane, notice that the **High Speed** mode icon is displayed in the top left corner of the view, next to the other camera details .

Prepare your Vicon system

Prepare video cameras (optional step)

Vicon Vue and Vicon Bonita Video cameras can be calibrated as part of a Vicon system, enabling you to see an accurate video overlay both during a live shoot and offline.

If your Vicon system includes supported video cameras, ensure you have set up your PC to work with the video cameras, physically connected the video cameras to your Shogun system, and set an IP address for each video camera as described in the Vicon video: [3 - Shogun Live - Setting up Vue video camera¹¹](#).



Set up aliases for video capture

Shogun Live enables you to provides an alias and specify the location to which to capture video. By having a dedicated disk (normally an SSD) for each video camera, you avoid any impact on the main system resources.

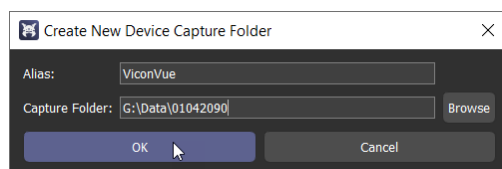
Before you begin a capture that includes video, ensure you have specified the required location for video capture, as described in the following steps.

¹¹ <https://vimeo.com/218944968>

Prepare your Vicon system

To specify the location to which to capture video:

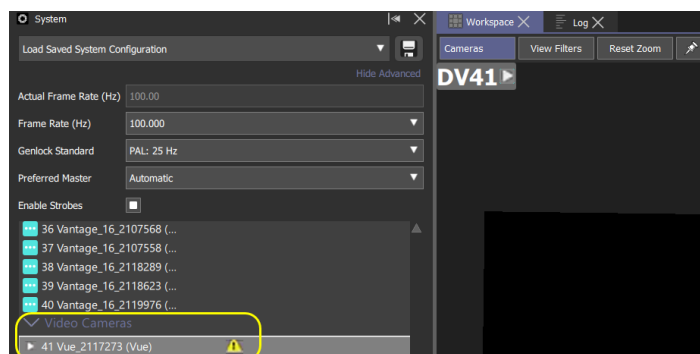
1. On the **Settings** menu, click **Show Preferences** (or press SHIFT+P).
2. In the **Preferences** dialog box, set up a different alias for each video camera in your system, each pointing to a different SSD as follows:
 - a. On the **System Preferences** tab, click **New**.
 - b. In the **Create New Device Capture Folder** dialog box, in the **Alias** field enter a name for the folder and in the **Capture Folder** field, enter or browse to the required location and click **OK**.



3. When you have finished, click **Save Changes**.
4. In the **System** panel, in the **Video Cameras** section, for each video camera, ensure that the correct alias is selected from the **Capture Directory** list.

Configure video cameras in Shogun Live

After you initially connect your Vicon video camera(s), set up IP addresses and open Shogun Live, icons that represent the cameras are displayed in the **System** panel. However, when you click on a video camera, nothing is displayed in the **Cameras** view. The yellow warning icon next to the video camera name indicates that you need to configure the video camera.



Prepare your Vicon system

To configure video cameras:

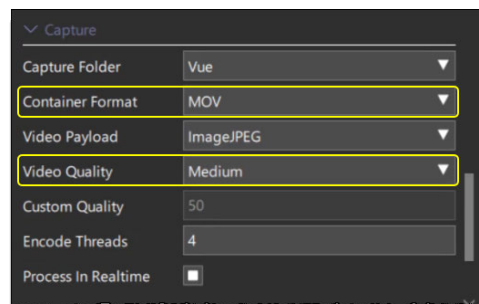
In the **System** panel, select a video camera, and then set the following attributes:

1. In the **General** section, ensure **Enabled** is selected and set the **Stream IP Address** for the selected video camera. This must be the address that was set for this video camera in the Windows Network and Sharing Center, as shown in the Vicon video: *Vicon Vue Configuration* (see above). Ensure the camera's IP address is not the same as that used by any other optical or video camera, or any other device. As the address ending in 192.168.10.1 is always reserved for the system, normally video cameras take the next available IP addresses (for example, 192.168.10.2, 192.168.10.3, etc).
The video stream is now displayed in the **Cameras** view of the selected video camera.
You can now calibrate the video camera, along with the other cameras (see [Calibrate cameras \(page 75\)](#)).
2. To configure the capture settings:
 - a. Note that for the best performance and to avoid running out of disk space, in the **Capture** section, set the **Capture Directory** to a drive that is different from that used by the Data Management or Eclipse database. If possible, specify a different drive for each video camera, as described in [Set up aliases for video capture \(page 71\)](#). If not, at least divide the video cameras into separate groups, depending on the drive speed, and allocate a separate drive to each group.
The folder structure created by setting the **Capture Directory** duplicates the structure of the **Data Management** capture path.
 - b. To change the sampling rate for video cameras, in the **System** panel, in the **Video cameras** section, click to select the required video camera and in the **General** section select the required option from the **Sub Sampling Divisor** list.
 - c. If you need to adjust the saturation, click **Show Advanced** and change the relevant setting in the **Video Mode** section.

Prepare your Vicon system

Realtime video compression

In Shogun Live 1.5 and later, you can capture direct to .mov file format, using one of five preset quality settings, enabling you to balance the file size against the required quality.



To select .mov format for capture:

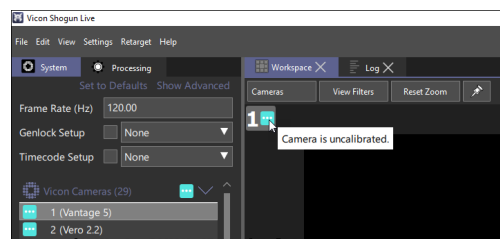
1. In the **System** panel, ensure the relevant video camera is selected (both Vue and SDI are supported) and in the **Capture** section, click in the **Container Format** list and select MOV.
2. To change the default quality setting, click in the **Video Format** list and select one of:
 - **Lowest** (lowest quality very small file)
 - **Low** (low quality, small file)
 - **Medium** (medium quality, medium size file)
 - **High** (high quality, large file)
 - **Best** (best quality, very large file)

File sizes can be much smaller, depending on the chosen quality setting.

Calibrate cameras

Calibrate cameras

When you first connect up your Vicon system and start Vicon Shogun Live, notice that in both the **System** panel and in the **Cameras** view, icons give you feedback on the current status of the cameras. The cyan icons indicate that although the cameras are connected, they are not yet calibrated.



Tip

To make it easy to tell when cameras have been disconnected, camera views for disconnected cameras display a red border.

To calibrate your Vicon cameras, complete these procedures in this order:


- [Mask cameras \(page 77\)](#)
- [Capture a wand wave \(page 81\)](#)
- [Set the volume origin \(page 84\)](#)
- [Set the floor plane \(page 91\)](#)
- [Auto number cameras \(page 94\)](#)

With Shogun Live 1.6 and later, to avoid having to recalibrate the whole system when you make changes such as adding or moving some of the cameras, you can [Calibrate or recalibrate selected cameras \(page 95\)](#).

See also the Vicon video: [4 - Shogun Live - System Calibration](#)¹².

¹² <https://vimeo.com/218944974>

Calibrate cameras

-  **Important** - Before you begin camera calibration, ensure that:
- Cameras have fully warmed up to a stable operating temperature. Vicon recommends a minimum 30–60 minute warm-up period. To ensure strobe activity, which can accelerate the warm-up period, connect up the Vicon system and run Vicon Shogun Live.
 - The **Grayscale Mode** for all cameras is set to **Auto**. To do this, in the **System** panel, click and drag or right-click to select all cameras and in the **Optical Mode** section below, change **Grayscale Mode** to **Auto**.

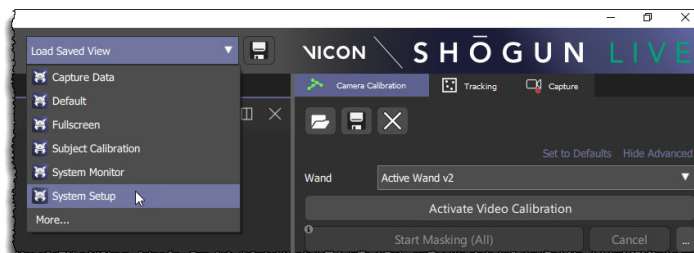
Calibrate cameras

Mask cameras

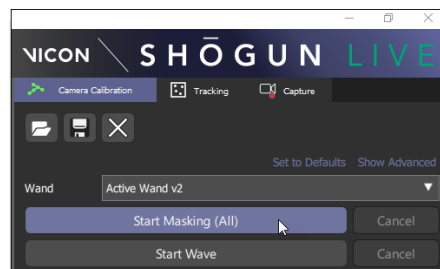
You mask cameras, including supported video cameras, during camera calibration to eliminate any unwanted reflections in the capture volume, so that they are not mistaken for markers by the cameras. Before you start masking, you can see these reflections represented by light pixels in the Camera views. During masking, blue pixels are drawn in the Cameras views, enabling you to see how much of the view is masked.

To mask reflections:

1. Ensure you have removed any objects likely to cause reflections, such as the calibration device or markers, from the capture volume.
2. To display the required panels, in the Load Saved View list, click **System Setup**.

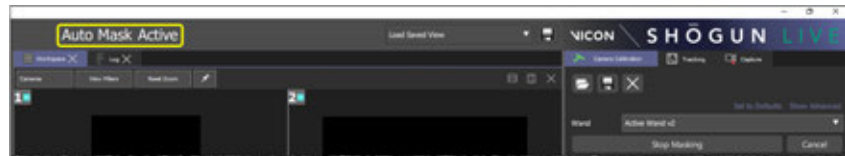


3. In the **System** panel, SHIFT+click or drag to ensure all the cameras are selected, including any video cameras in your Vicon system.
4. On the **Camera Calibration** tab, click **Start Masking (All)**.



Calibrate cameras

The button displays **Stop Masking** and at the top of the workspace, **Auto Mask Active** is displayed.



In the **Cameras** views, any video cameras are displayed as black, blank screens.

Shogun Live starts recording the data visible to each of the connected cameras. Any camera masks created are displayed as blue cells in the **Cameras** views for affected cameras. If no data is visible to a particular camera, Shogun Live does not create any masks for it. Both optical and video cameras are masked.

5. After about 5–10 seconds, click **Stop Masking**.
6. In the **Cameras** view for each camera, ensure that any unwanted reflections are eliminated. (Each view should either be completely blank or should contain some blue pixels.)

When you've masked all the reflections, you can [capture a wand wave \(page 81\)](#).

If you need to add equipment or make other changes after you've finished masking, see [Change masking \(page 79\)](#).

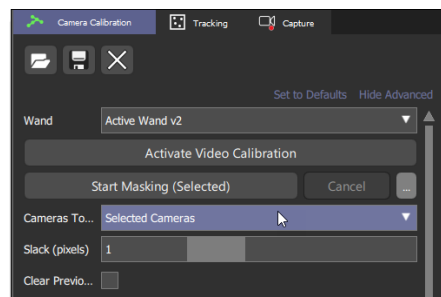
Calibrate cameras

Change masking

If you add equipment or markers into the volume after you've finished auto-masking, or if you have an issue with specific camera(s), you'll need to add to any masking that you've already completed. To do this, you can keep your original masking and use further auto-masking to add to it and/or manually paint out any additional reflections.

To add to existing auto-masking:

1. To display the required panels, in the **Load Saved View** list, click **System Setup**.
2. If you want to apply additional masking to only some cameras, make sure you've selected the relevant cameras.
3. On the **Camera Calibration** tab, ensure the Advanced options are displayed and clear the **Clear Previous Masks** check box. This prevents your original masking from being overwritten.
4. If you want to add the new masking to selected cameras only, in the **Cameras To Mask** list, ensure **Selected Cameras Only** is selected.
5. Click **Start Masking**.



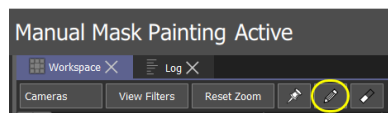
Auto Mask Active is displayed at the top of the Workspace.

6. When masking is complete, click **Stop Masking**.
In the Cameras views, observe the additional masking, which is displayed as blue cells.

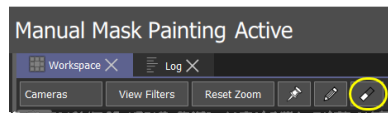
Calibrate cameras

To manually add masking:

1. To display the required panels, in the **Load Saved View** list, click **System Setup**.
2. On the **Camera Calibration** tab, click **Start Manual Mask Paint**. **Manual Mask Painting Active** is displayed at the top of the Workspace.
3. Use the following shortcuts to select and mask:
 - To select an area: Alt+click and drag
 - To apply masking: Click on the pencil icon next to the pin button or use the shortcut Alt+E.



- To erase masking: Select the masked area (see above) and click the eraser or use the shortcut Alt+R.



4. When you have finished manual masking, click **Stop Manual Mask Paint**.

When you've masked all the reflections, you can [capture a wand wave](#) (page 81).

Calibrate cameras

Capture a wand wave

During camera calibration, after you have masked any reflections, you calibrate the cameras by waving a wand (the calibration device) throughout the volume to enable the cameras to capture movements over the whole area.

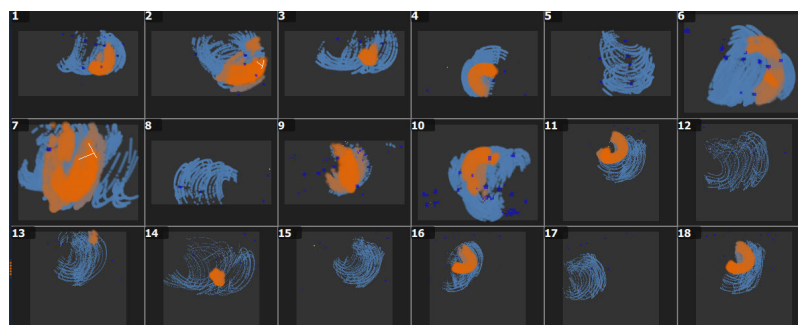
⚠ Important

- If you are calibrating one or more supported video cameras, the calibration device must be an Active Wand.
- The minimum frame rate supported by the Active Wand is 50 Hz.

To capture a wand wave:

1. At the top of the **Camera Calibration** tab, in the **Wand** list, ensure the option for the type of wand that you are using is selected (this will normally be one of the Active Wand options).
2. To start collecting wand data, click **Start Wave**.
The button displays **Stop Wave** and in the menu bar, the text **Camera Calibration Active** is displayed, next to a flashing red circle.
3. Have someone wave the wand throughout the capture volume, covering depth as well as height, while you watch the **Cameras** views for all cameras to ensure you get full coverage. Ensure that the markers (LEDs) on the wand remain visible to all the cameras as much as possible while the wand is moved throughout the volume.

As an indication that sufficient wand wave data has been collected for a particular camera, the display in the each view changes from orange to blue.



Calibrate cameras

- In the table in the bottom half of the **Camera Calibration** tab, notice that the **Wand Count** column changes from red to green as sufficient data per camera is captured. This helps you concentrate on waving the wand for cameras that need more data.

Tip

By default, camera calibration stops automatically when each camera has seen enough of the wand to ensure calibration. To adjust this or turn it off, at the top right of the **Camera Calibration** tab, click **Show Advanced** and then click the ellipsis (...) to the right of the **Start Wave** button.

- In the **Image Error** column, in addition to displaying the values, Shogun Live grades the status of each camera between red (poor) and green (excellent), depending on how much the cameras see the wand.

In the volume, the display on Vicon optical cameras changes to indicate their calibration status:

- Vantage, Vero, Viper and ViperX cameras:** The status lights turn magenta and blink during calibration, becoming green and then blue when fully calibrated. On the OLED display (Vantage cameras only), a pie chart indicates the fraction of the required wand data that has been received from the camera.
- MX T-Series cameras:** The status light on the front blink while you are performing the wand wave, and then go solid blue when enough data has been collected to calibrate the camera.

- When enough data has been collected, Shogun Live starts processing the wand wave data. Depending on the number of cameras and the length of your wand wave capture, this may take a few minutes. The progress bar indicates the calibration progress, and table below indicates the calibration results.

Camera	Wand Count	Image Error
1 Vero 2.2	2317	0.108
2 Vero 2.2	2825	0.157
3 Vero 2.2	2213	0.232
4 Vero 2.2	4106	0.092

Calibrate cameras

In the Log, you are warned if your wand wave has insufficient spread across cameras to give a good calibration. The warning displays both the camera User ID (the number you can provide for the camera in the camera's properties, and URN (the Device ID, found in the camera's Advanced properties).

Time	Level	Category	Text
2021.07.08 11:27:26.701 +1	Warn	Camera.Calibration	Camera ID=1 (URN=mx2107565) has connectivity frames count = 212. This is below the recommended minimum (500), and
2021.07.08 11:27:26.701 +1	Warn	Camera.Calibration	Camera ID=3 (URN=mx2107579) has wand count = 250. This is below the recommended minimum (1000).
2021.07.08 11:27:26.701 +1	Warn	Camera.Calibration	Camera ID=3 (URN=mx2107579) has connectivity frames count = 115. This is below the recommended minimum (500), and
2021.07.08 11:27:26.701 +1	Warn	Camera.Calibration	Camera ID=13 (URN=mx2107587) has wand count = 164. This is below the recommended minimum (1000).
2021.07.08 11:27:26.701 +1	Warn	Camera.Calibration	Camera ID=13 (URN=mx2107587) has connectivity frames count = 145. This is below the recommended minimum (500), and
2021.07.08 11:27:26.701 +1	Warn	Camera.Calibration	Camera ID=24 (URN=mx2109393) has wand count = 117. This is below the recommended minimum (1000).

7. When the wand wave is finished, an `.xcp` and an `.x2d` file is created in `C:\ProgramData\Vicon\Calibrations`. If your calibration included Vicon video cameras, two `x2d` files are created. The files are:

- `LatestCalibration.x2d`, which contains the wand wave without any Vicon video cameras
- `LatestCalibration_withVideo.x2d`, which contains the wand wave including Vicon video cameras.

Note

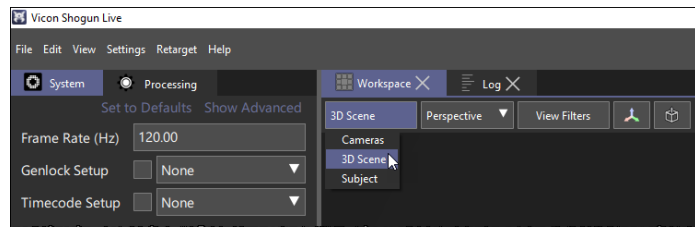
After a wand wave, Vicon video cameras do not produce video files as they are not needed for calibration.

Calibrate cameras

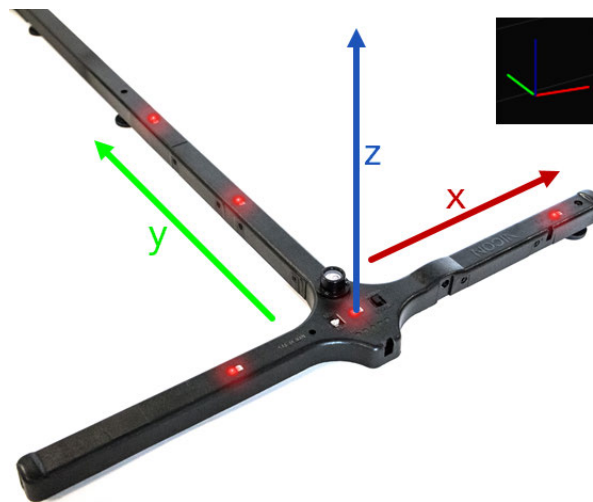
Set the volume origin

After you have captured a wand wave, you set the volume origin and axes so the cameras and volume in Shogun Live reflect the actual positions of the cameras in relation to the capture volume, as well as to each other.

1. To enable you to see the axes in relation to the volume, on the **Workspace** tab, change the view to **3D Scene**.



2. Place the calibration device on the capture volume floor in the position you want the volume origin to be and in the orientation you want the axes to be (reflected in the axes displayed in the 3D Scene view).



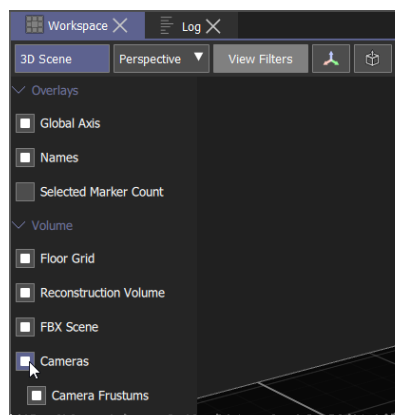
- X: red line
- Y: green line
- Z: blue line

Calibrate cameras

3. At the top of the Camera Calibration tab, in the Wand list, ensure the appropriate Active Wand is selected.

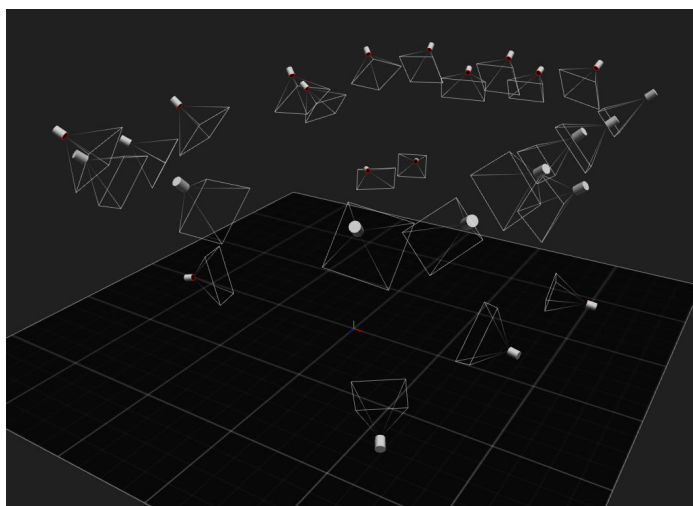
✔ **Tip**
 If you're using a Y-up wand, display the **Advanced** properties and in the **Set Volume Origin** section, select **Legacy Y-Up Scene Orientation**.

4. Click **Start Set Origin**.
The button displays **Set Origin**.
5. After a few seconds, click **Set Origin**.
6. In the **3D Scene**, display the **View Filters** options and under the **Volume** options, ensure that **Cameras** is selected.



Calibrate cameras

7. In the 3D Scene, Perspective view, all of the cameras shift as a group, so the origin of the capture volume is aligned with the wand.



Calibrate cameras

Set the origin with a custom L-frame

To improve calibration stability and consistency over time, you can use a custom L-frame to set the origin of your system.

As described in [Set the volume origin \(page 84\)](#), you can use a Vicon Active Wand to set up your volume coordinate system quickly and easily. However, using a larger, custom calibration object (in this case, markers embedded in the volume floor and/or wall) can improve calibration stability and consistency over time.

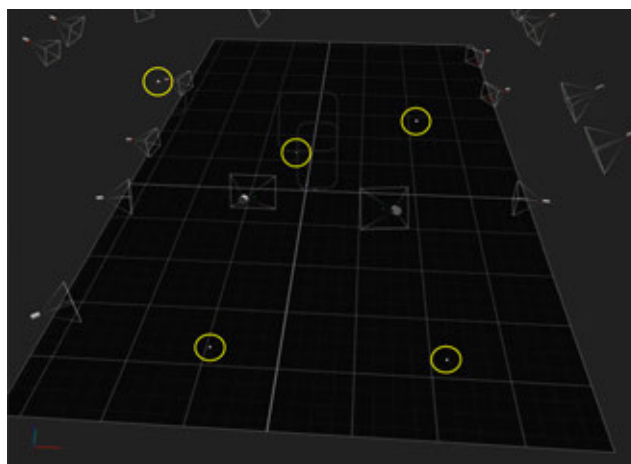
A typical way to use a custom L-frame would be to keep markers on wall, hidden during camera masking, then when you're ready to set the coordinate system for your volume, make the markers visible and use the custom L-Frame as described below.

See also:

 [Vicon Shogun 1.3 Live Tutorial - Custom L-Frame Workflow](#)¹³ on YouTube.

To create a custom L-frame:

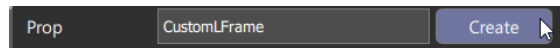
1. With the system calibrated, set the origin as normal (see [Set the volume origin \(page 84\)](#)), including setting the floor offset (see [Set the floor plane \(page 91\)](#)), as required.
2. Position a number of markers on the edge of the volume and select them.



¹³ <https://youtu.be/l4-zV9253ho>

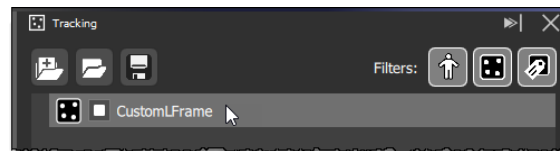
Calibrate cameras

3. On the **Tracking** tab (right), in the **Prop** field, enter a name for the custom L-frame and click **Create**.

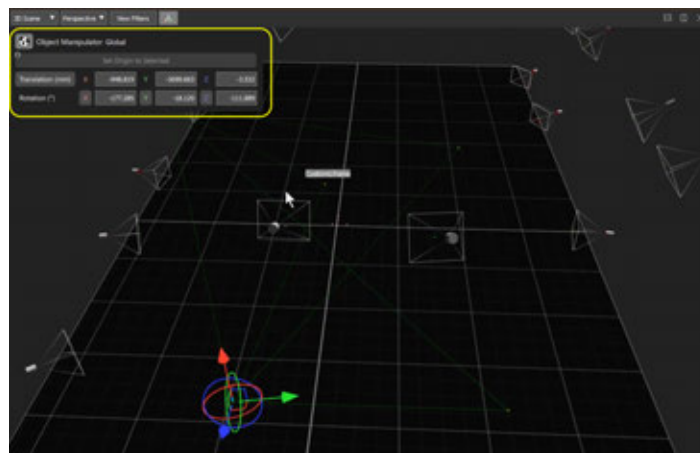


The new custom L-frame prop is displayed in the 3D Scene view.

4. Pause the real time and in the **Tracking** panel on the right, select the prop you just created.

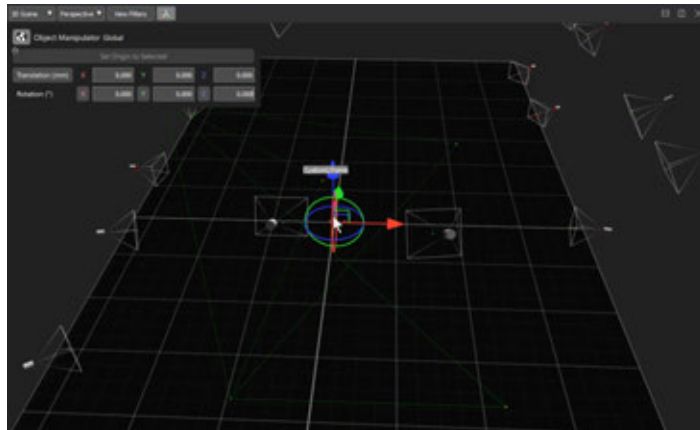


5. To display the Object Manipulator, press M. (For more information on the Object Manipulator, see [Move props \(page 128\)](#).)
In the Workspace (3D Scene view), the Object Manipulator is displayed.

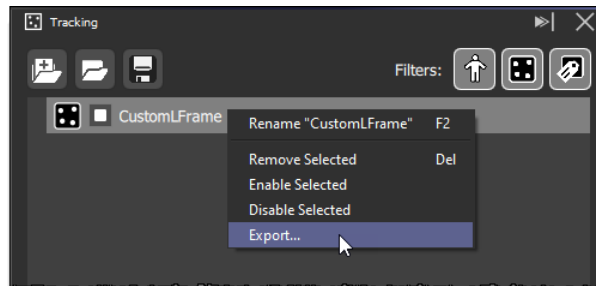


Calibrate cameras

- In the Tracking panel on the right, ensure that the custom L-frame is still selected, and with the Object Manipulator set to Global, change all the values to zero, so the origin matches that of the L-frame.



- In the Tracking panel, with the custom L-Frame selected, right-click and then click Export.

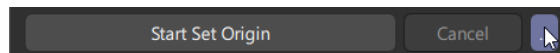


- Navigate to *Users\Public\Documents\Vicon\CalibrationObjects* and click Select Folder. The custom L-frame is automatically saved as a VSK.

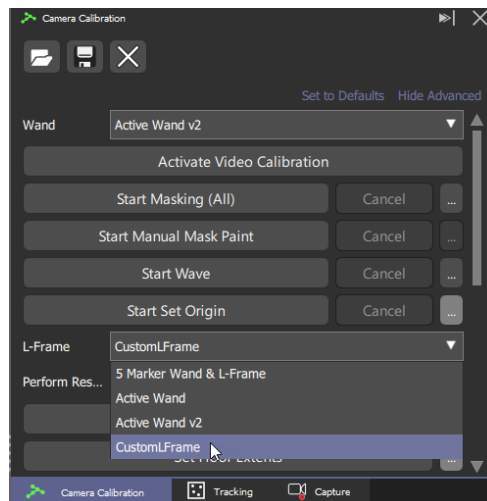
Calibrate cameras

To use the custom L-frame:

1. Click Play to resume the real time.
2. On the **Camera Calibration** tab (right), ensure the Advanced options are displayed (if not, click **Show Advanced**, top right).
3. To the right of **Start Set Origin**, click the button for additional options.



4. In the L-Frame list, select the new custom L-frame.



5. Click **Start Set Origin**.
The new custom L-frame is used to set the origin.
6. When done, click **Complete Set Origin**.

Calibrate cameras

Set the floor plane

The final stage in calibrating your Vicon cameras is to set the floor plane, using markers in the volume to automatically define it.

The position of the virtual floor that is derived during setting the origin is extrapolated from the position of the wand in relation to floor of the volume. As the wand is a small object compared with the size of the volume, any slight discrepancy from the wand being level has a large effect over the rest of the volume when you set the origin. To account for any discrepancy, you set a floor plane, which takes a much larger area into account, so that the virtual floor lines up correctly with the actual floor plane.

To set the floor plane:

1. Ensure you have completed the rest of the camera calibration procedure and set the origin (see [Set the volume origin \(page 84\)](#)).
2. Turn off the calibration object or remove it from the volume.
3. Place a minimum of four 14 mm Vicon markers across the floor of your capture volume.
(If you are not using 14 mm markers or have changed the default 7 mm floor plane setting, see [Adjust the Set Floor Plane settings \(page 93\)](#).)
4. On the **Camera Calibration** tab, click **Start Set Floor Plane**.
The button displays **Set Floor Plane**.
5. After a few seconds, click **Set Floor Plane**.
6. In the **3D Scene**, display the **View Filters** options and under the **Volume** options, ensure that **Cameras** is selected
In the **Perspective** view, note that the cameras shift as a group slightly along one or more rotation axes to better reflect an average of the markers scattered across the floor, taking into account any offsets that you specified. In *C:\ProgramData\Vicon\Calibrations*, the *LatestCalibration.xcp* file is updated. This file is automatically used for every subsequent capture.

✓ **Tip**

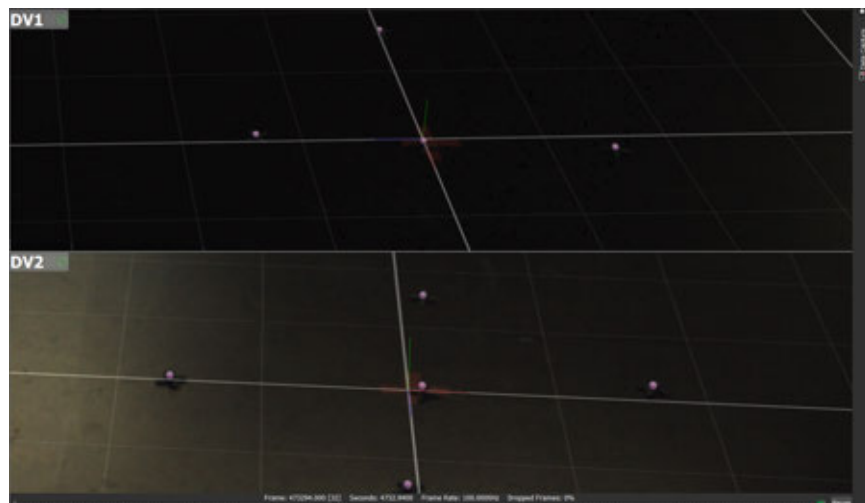
To more accurately visualize the size of your volume in Shogun Live, you can change the size and shape of the floor grid. To do this, on the **Camera Calibration** tab, click the ellipsis (...) next to **Set Floor Extents** and change the values (in mm) to give the required result.

Calibrate cameras

If your system includes supported video cameras, you can now check that your video calibration is accurate by viewing a video overlay.

To check a video overlay:

1. In the **System** panel, expand the **Video Cameras** section and click on one or more video cameras.
The **Cameras** view displays the video data for the selected video camera(s).
2. In the **Cameras** view, click **View Filters** and in the **3D Data** section, select the **3D** option.
In the view pane, a 3D overlay is displayed. Because this displays a flat overlay on a **3D Scene**, the edges appear distorted.
3. To remove the distorted appearance, select **Distort 3D**.
The 3D perspective is flattened to match the video.



4. Check that the video of the markers and the 3D perspective line up accurately.



Tip

To check your calibration, from the **View Filters** options, select **Camera Rays**. If you select one or more cameras, this displays lines (rays) to everything the selected camera(s) can see. If you select one or more markers, this option displays lines from all cameras that can see the selected marker(s).

Calibrate cameras

Your Vicon cameras are now calibrated and ready to capture data.

Adjust the Set Floor Plane settings

If you are not using 14 mm markers, to enable you to set the floor plane accurately, click **Show Advanced**, click the ellipsis next to **Start Set Floor Plane**, and change the **Height offset** value to an appropriate value. The **Height offset** is the amount (in mm) by which to adjust the floor plane (the default is 7 mm). Because Shogun finds the centers of the markers, set a **Height offset** that accounts for the size of the markers (for example, for 14 mm markers, the **Height offset** is 7 mm). If the markers include a base, take this into account in your calculations.

Calibrate cameras

Auto number cameras

The **Auto Number Cameras** feature numbers the currently connected Vicon cameras in ascending order, according to their position in the capture volume. You may want to do this after you calibrate your Vicon system, so that your cameras are logically numbered before you begin capture.

Automatic numbering starts with the camera that is furthest from the volume origin. The cameras are then numbered in a clockwise direction around the volume. If your cameras are positioned at different levels, the cameras in the level that contains the most cameras are numbered first.

To automatically number Vicon cameras:

1. Ensure that the cameras are positioned as required, and that you have calibrated the cameras and set the volume origin.
2. To enable you to check the camera numbering for all cameras, in the **System** panel, ensure that you can see the list of Vicon cameras.
3. In the **Camera Calibration** panel, click **Auto Number Cameras**.
The cameras are automatically numbered in ascending order, according to their position in the volume.
In *C:\ProgramData\Vicon\Calibrations*, the *LatestCalibration.xcp* file is updated.
4. In the volume, check that the cameras are now numbered as required.

Calibrate cameras

Calibrate selected cameras

With Shogun 1.6 and later, you can mask and calibrate or recalibrate multiple selected Vicon optical cameras or Vicon video cameras, as well as SDI cameras, without having to completely re-calibrate the whole system.

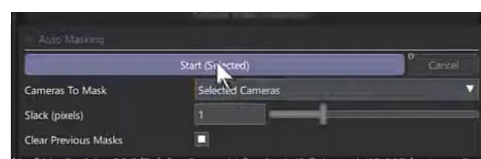
Any cameras that are not selected are locked, so that any existing calibration is unaffected, and the global co-ordinate system is maintained.

To add new cameras to a calibration:

1. Connect the new cameras into the Vicon Shogun system that contains the calibrated cameras.
2. In the **System** panel, select the new cameras that are not yet calibrated (indicated by a cyan icon).



3. Instead of masking all the cameras, on the **Camera Calibration** tab, ensure the **Advanced** options are displayed and in the **Auto Masking** section, change **Cameras To Mask** to **Selected Cameras** and then click **Start (Selected)**.



4. When the cameras are masked, click **Stop**.
5. In the same way, with the new cameras still selected, in the **Calibration Wave** section, click **Selected** and, with **Auto Stop** selected, wave the wand for just the selected cameras and wait for the calibration to finish.

You don't need to re-set the origin as the world co-ordinate system remains valid.

Calibrate cameras

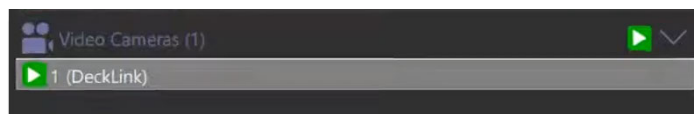
SDI lens calibration example

You can use Shogun Live's ability to calibrate selected cameras to add an SDI camera to your system.

With Shogun Live, you can obtain the camera extrinsics (the camera position relative to the world) and the intrinsics (information about the lens, such as its focal length and radial lens distortion). As this enables you to accurately overlay 3D data onto the 2D data, it provides a quick way to assess the quality of the calibration.

To add an SDI camera to a calibration:

1. Connect the SDI camera into a Blackmagic Decklink card on the PC that is part of a Vicon Shogun system.
It is displayed as Decklink in the **Video Cameras** section of the **System** panel.



2. Click **Decklink** to display the video stream.
3. As in [Calibrate selected cameras \(page 95\)](#), mask the selected additional camera and complete a wand wave for it.

 **Tip**

When waving the wand for the new video camera, bear in mind that you also need several other optical cameras to be able to gain enough information from the wand wave to be able to position the additional camera within 3D space successfully. You may find that holding the wand at an angle may give a better result.

When the wand wave is complete, the SDI video camera is calibrated and added into the existing calibration. It is displayed in the 3D Scene view.

Calibrate cameras

Because the calibration has provided extrinsics as well as intrinsic data about the camera, you can accurately overlay 3D data on top of the 2D data. This gives a quick way of assessing the quality of the calibration as, using the 3D Opacity control in the View Filters, you can see how closely the 3D image matches the 2D data beneath.



Because this process is so fast and consistent, you can make changes the lens (eg, use a different focal distance) or even swap it entirely and produce a new calibration very quickly.

Create subjects

Create subjects

After you have calibrated your Vicon cameras, you are ready to create and calibrate subjects and any props that you need.

To create and calibrate subjects, complete the following procedures as required:

- [Choose a marker set \(page 100\)](#)
- [Add labeling clusters to the datastore \(optional step\) \(page 101\)](#)
- [Place markers on a performer \(page 103\)](#)
- [Create and calibrate a subject \(page 109\)](#)
- [Load a retargeting setup \(page 118\)](#)

In addition to the following information, see also the Vicon video [6 - Shogun Live - Subject Calibration](#)¹⁴, which demonstrates how to place markers on a performer and how to calibrate a subject using a T-pose and ROM. (Note that the latest version of Shogun uses an A-pose for subject calibration, and includes a cluster-picker to help with subject booting when using the high-density finger marker sets.)

¹⁴ <https://vimeo.com/218944987>

Create subjects

Load subjects and props via .mcp file

For an easy way to quickly load subjects and props from an existing scene, you can load an *.mcp* file directly into Shogun Live.

To quickly load subjects and props from an *.mcp*:

1. At the top of the Tracking panel, click the Load tracking configuration button



2. From the Load Tracking Configuration dialog box, select or browse to the required *.mcp* file.

The subjects and props are displayed in the Tracking panel as normal.

Create subjects

Choose a marker set

Choose a marker set, depending on your requirements. Templates (labeling and solving) for the following marker sets are supplied with the latest release of Shogun:

Marker set	Description
FrontWaist	Standard 53-marker set
FrontWaist10Fingers	Standard marker set plus 10 finger-markers
FrontWaist3Fingers	Standard marker set plus three finger-markers
FrontWaist5Fingers	Standard marker set plus five finger-markers
Production	Production marker set, which helps with marker occlusion and includes extra markers for the back and top of the shoulders to help with gap-filling and solving
Production10Fingers	Production marker set plus 10 finger-markers
Production3Fingers	Production marker set plus three finger-markers
Production5Fingers	Production marker set plus five finger-markers
SideWaist	Alternative standard marker set, which avoids front waist marker occlusion (useful if, for example, the front waist marker is likely to be occluded due to a performer's hands obstructing it or the performer bending forwards)
SideWaist10Fingers	Standard marker set with side waist markers plus 10 finger-markers
SideWaist3Fingers	Standard marker set with side waist markers plus three finger-markers
SideWaist5Fingers	Standard marker set with side waist markers plus five finger-markers

For the most realistic finger animation, the 10 finger-marker set is recommended.

It is assumed that you are using one of Shogun's default labeling templates. If you are using a different template, please contact [Vicon Support](#)¹⁵.

¹⁵ <mailto:support@vicon.com>

Create subjects

Add labeling clusters to the datastore (optional step)



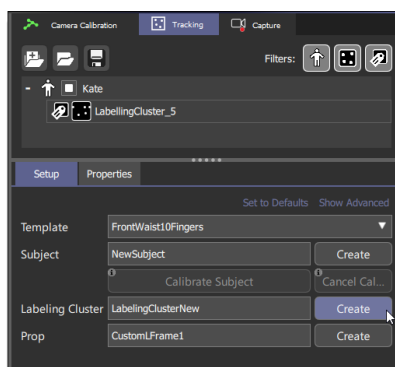
To help Shogun Live in booting the labeling setup and to uniquely identify performers, you can use labeling clusters. Labeling clusters are particularly useful in scenes with multiple performers.

Place one or more labeling clusters on each performer, with each cluster containing five or more markers. Ensure labeling clusters are unique by varying the position of the markers in each cluster.

Before you can use the labeling clusters for motion capture, you must add them to the Shogun Live datastore, to enable Shogun Live to recognize them.

To create labeling clusters:

1. To save clusters, you can either use the default folder (C:\Users\Public\Documents\Vicon\Clusters), or to change the default location, in the **Preferences** dialog box (Shift+P), on the **User** tab, go to the **Folders** section and on the **Labeling Clusters** line, enter or browse to the required folder.
2. Place the labeling cluster(s) in the volume and ensure all the markers are visible to the cameras.
3. In the **3D Scene**, ALT+drag to select a minimum of five markers for the new cluster.
4. In the **Tracking** panel, ensure the **Setup** tab is selected and in the **Labeling Cluster** field, enter a name for the new cluster and then click the adjacent **Create** button.



A labeling cluster is created from the selected markers and a .vsk file (with the same name as the labeling cluster) is created in the folder specified in Step 1.

Create subjects



Tip

To help you to identify a labeling cluster, in the tree at the top of the Tracking panel, hover the mouse pointer over the cluster's icon. An enlarged view of the cluster is displayed.

5. If you need to rename, detach, delete, or export a cluster, at the top of the Tracking panel, right-click the cluster and from the menu, select the required option. To rename you can also double-click the required cluster and then enter the new name.

Create subjects

Place markers on a performer

To place markers on a performer:

1. Place your chosen marker set on the performer(s).
The following images show the standard Vicon FrontWaist 53-marker set, and also show the placement of a cluster.



Create subjects

These images show the placement of markers for the Production marker set (with 10 finger-markers):



Create subjects

If you're using side waist markers, place the waist marker(s) at the sides of the performer's waist:



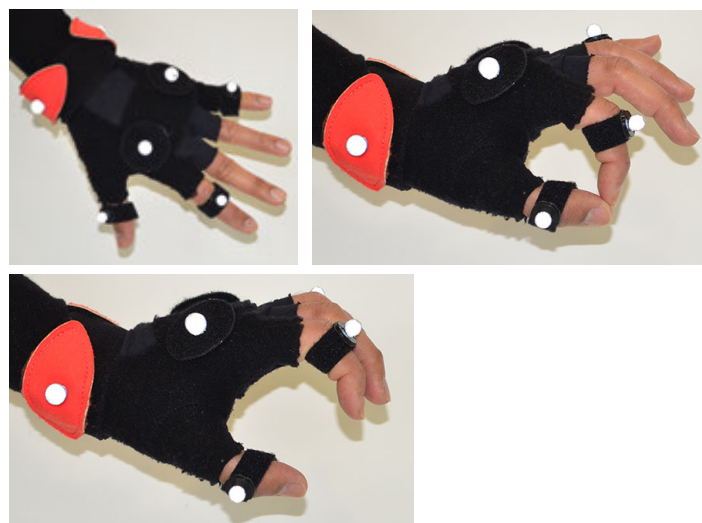
2. Ensure that the foot markers are placed so that the toe marker is as far forward as possible on the foot while still facing upward. Also ensure that the three other markers (the heel marker and the two markers on either side of the front of the foot) are in the same plane, and are as low (ie near to the floor), as possible.



Create subjects

3. If you're using finger markers, place them on the hands. Follow these guidelines to ensure that the finger markers produce an accurate solve:
 - **Wrists:** The wrist marker placement is important because the foundation of a good finger solve is a correctly solved wrist. Place the wrist markers on either side of the wrist so that both markers are the same distance down the arm and as close to the joint center as possible.
 - **Hands:** Place the hand markers just before the knuckle of the index and pinky finger.
 - **Fingers:** For 3 finger-marker setups, place a marker just before the first joint of the index, pinky, and thumb, so that it is not affected by rotation of the second joint (see the photo of the [3 finger marker set \(page 106\)](#)). For 5 finger-marker setups, place the markers at the end of each of the five fingers (see the photo of the [5 finger-marker set \(page 107\)](#)). For 10 finger-marker setups, place the markers at the end of each finger, and mid markers on the second phalange apart from the mid (see the photo of the [10 finger-marker set \(page 107\)](#)).
 - **Upper arms and legs:** To help with calibration, place offset markers on the upper arms and legs.

These images show placement of the wrist, hand, and finger markers in a three-finger setup:



Create subjects

This image shows placement of the wrist, hand, and finger markers in a 5 finger-marker set:



This image shows placement of the wrist, hand, and finger markers in a 10 finger-marker set:

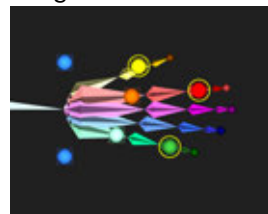


Placement for all the finger marker sets, as displayed in Shogun, is shown below:

10 finger-marker set



3 finger-marker set



5 finger-marker set



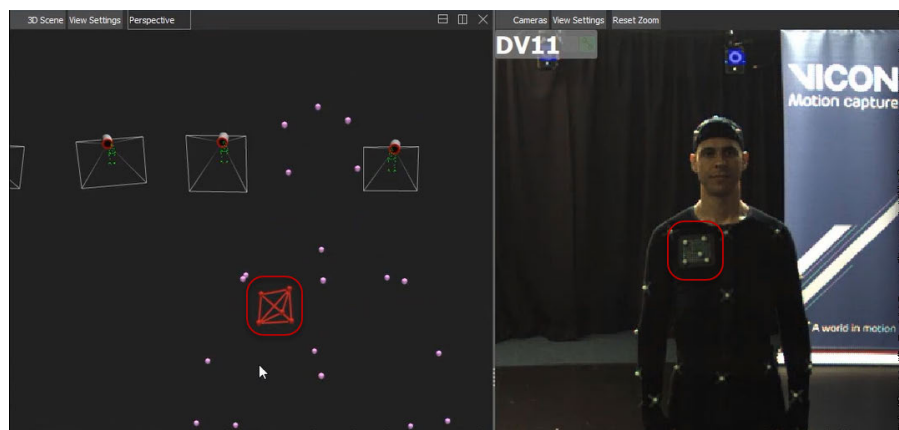
Create subjects

✓ Finger marker size

For a successful calibration, choose the correct size of markers for the hands, fingers and wrists:

- **Hand markers.** Marker size is critical for the wrist rotation in the A-pose. If you use large markers, this can cause an upward rotation of the the wrist and downward rotation of the knuckles. For the best results, we recommend that the markers' centers are about 10 mm from the joint axis.
- **Finger markers.** Marker size is also important for calibration. For the best results, we recommend that the markers' centers are about 5 mm from the joint axis.
- **Wrist markers.** Marker size does not affect calibration, so you can use normal body-size markers or finger-size markers.

4. If you're using clusters (see [Add clusters to the Shogun Live datastore \(page 101\)](#)), if you haven't already done so, place them on the performer(s). Normally, a good location for the cluster is on the torso, but not too close to other markers. This can be on the front, as shown in the following image, or on the back, as shown in the illustrations in Step 1.



Create subjects

Create and calibrate a subject

Calibrating a subject involves having a performer wearing the required marker set stand in an A-pose and then perform a Range of Motion (ROM) in the capture volume. During the ROM, ensure that the performer goes through a full range of movement for every limb and joint that is to be captured.

Before you begin, to give the clearest view of the subject, at the top of the 3D Scene view, ensure **View Filters** is selected, then under the **Volume** options, clear **Cameras**. In the **Subjects** section, select **Solve** and in the options matrix, in the **S** column, ensure **Skin** is selected (in addition to any other options that you may want to use).

i Note

Live occlusion-fixing occurs by default. This ensures the skeleton continues to behave correctly while markers are occluded. To ensure occlusion fixing is displayed, display the **View Filters**, and in the **Data** section, ensure **Missing Markers** is selected. In the **Subjects** section, select **Solve**, and in the options matrix, in the **S** column, ensure **Skin** is selected. Occlusion fixing is indicated by the red color and is also visible when **X-Ray** is selected.

To turn off occlusion fixing, at the top of the **Processing** panel, click **Show Advanced** and in the **General** section, clear **Occlusion Fixing**.

If you want to set aside a part of your volume for subject calibration, to avoid having to clear the volume each time you have to calibrate or re-calibrate a subject, see *Create a subject calibration hotspot* in *Getting more from Vicon Shogun*.

Create subjects

High fidelity fingers marker sets

If you're using a marker set that includes markers for high fidelity fingers, note that labeling also makes use of this feature. To help the calibration, ensure you have placed offset markers on the upper arms and legs.

 **Note**

Because the high-density marker set results in a greater demands on processing, you may experience dropped frames, especially when using more than one actor. Ideally, test first with a single actor on a high-spec, multi-core machine.

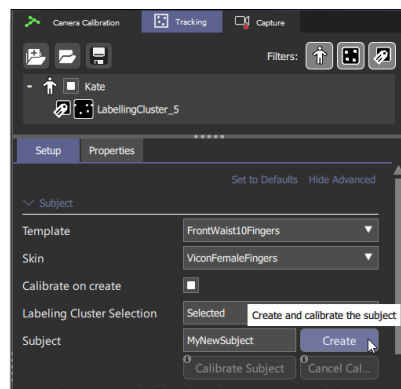
To improve processing, you can run reconstruction, labeling, solving and/or retargeting over multiple machines. For information, see Run Shogun processing on multiple machines in *Getting more from Vicon Shogun*.

To perform live subject calibration:

1. In the **Tracking** panel, on the **Setup** tab, in the **Template** field, choose the appropriate template for your subject.
If you're using side waist markers and/or finger markers, make sure you choose the templates that include side waist markers and/or fingers (indicated by their names).
2. To choose a mesh, ensure the **Advanced** properties are displayed (if they aren't, click **Show Advanced** at the top right of the **Setup** tab) and from the **Skin** list, select the mesh that is to be used for the solving skeleton.

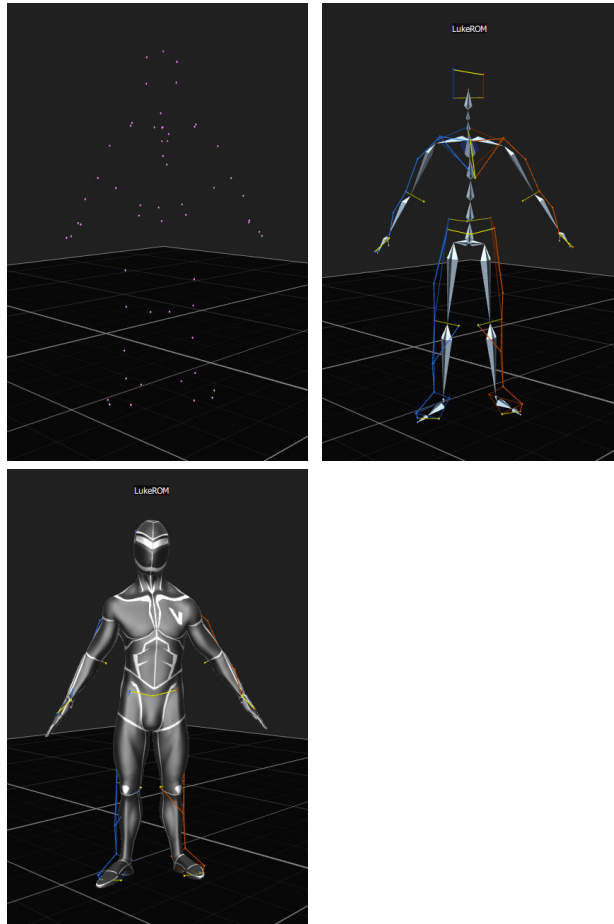
Create subjects

3. To select a labeling cluster, for example, for a subject who is wearing a high density marker set (ie finger markers or any other high density set), ensure the Advanced properties are displayed and in the **Labeling Cluster Selection** field, make the required selection:
 - **All** Any currently unattached labeling cluster will be attached to the subject.
 - **Selected** Only the cluster(s) selected at the start of calibration will be attached to the subject.
 - **None** No labeling clusters are used for calibration.
4. In the **Subject** field, enter a name for the new subject and click **Create**.



Create subjects

5. Have the performer wearing the correct marker set (see [Place markers on a performer \(page 103\)](#)) enter the volume and stand in an A-pose, with the hands flat.



If you're using a template that includes fingers, also ensure that:

- The wrists are straight, not bent to either side or up or down.
- The fingers are straight, with a natural spread, and no bend.
- The thumb is held tight against the index finger. Ensure that the thumb and the fingers all point in the same direction.

Create subjects

6. On the menu bar, above the workspace, **Subject Calibration Active** and a flashing red circle is displayed.
In the **3D Scene** view, the markers are labeled, and the labeling and solving skeleton is displayed.
Look for feedback in top right of view pane, which shows the number of markers found and the number of markers required, as well as other calibration feedback.



Create subjects

7. Visually check that all the markers have been labeled and everything looks OK.



Tip

To quickly check that all the required markers have been placed on the performer, ensure the subject is selected and check the Marker Selection counter (bottom right of the view pane). For more information, see [Check the marker count on the current selection \(page 116\)](#).

8. After waiting until you're happy with the position of the joints, on the **Setup** tab below the **Subject** field, click **Accept A-Pose**.



Tip

If, despite using offset and left and right markers (see the [guidance on marker placement \(page 106\)](#) for finger marker sets), you still experience problems with subject booting, in the Tracking panel, ensure the **Setup** tab is selected with Advanced options displayed, and in the **Capture** section, select **Capture Canceled Calibrations**. (This enables Support to troubleshoot your issue.)

Create subjects

9. Get the performer to perform a ROM (Range Of Motion) that includes all the required movement. If you're using one of the high-fidelity fingers templates, include some finger movements as part of this process. Include bending and spreading the fingers as well as poses of the hand that will be useful for checking the accuracy of the labeling.

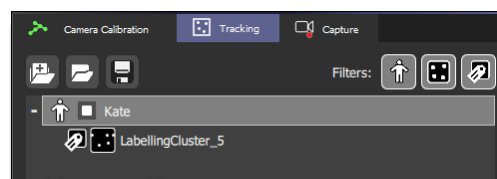
Include the following in your ROM:

- Fists
- Wiggle the fingers
- Touch the tip of the thumb against the tip of each digit of the same hand:
 - Thumb to index finger
 - Thumb to middle finger
 - Thumb to ring finger
 - Thumb to pinkie

10. When the ROM is complete, click **Stop Calibrating**.

In the **3D Scene**, you can see the mesh and solving skeleton of the subject (if you need to change the display, at the top left of the workspace, click **View Filters** and choose the required options).

At the top of the **Tracking** panel, a subject with the name you supplied in Step 1 above is displayed, together with a node representing its labeling cluster (if any).



The subject is now fully calibrated and can be used in captures as required (for example, if you're using it for retargeting, see [Load retargeting setup](#) (page 118)).

If you have difficulty with calibrating your subject satisfactorily, see [Troubleshoot subject calibration](#) (page 119).

i An alternative to live solving subject calibration

In Shogun 1.6 and later, if you find that after Live calibration the solve requires much tweaking, for a post-processed alternative, try Auto-Skeleton in Shogun Post. For information, see *Use Auto-Skeleton in Getting more from Vicon Shogun*.

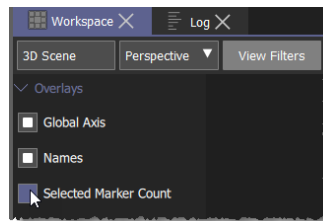
Create subjects

Check the marker count of the current selection

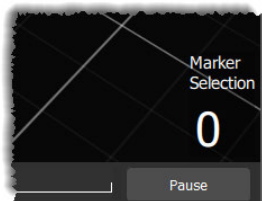
The **Marker Selection** counter enables you to easily check the number of markers currently selected. This is useful during subject calibration, if you need to check that the required number of markers have all been placed on a subject, or within a particular set of markers (for example, facial markers).

To display the number of selected markers:

1. In the 3D Scene view, ensure **View Filters** is selected and in the **Overlays** section, select the **Selected Marker Count** option.

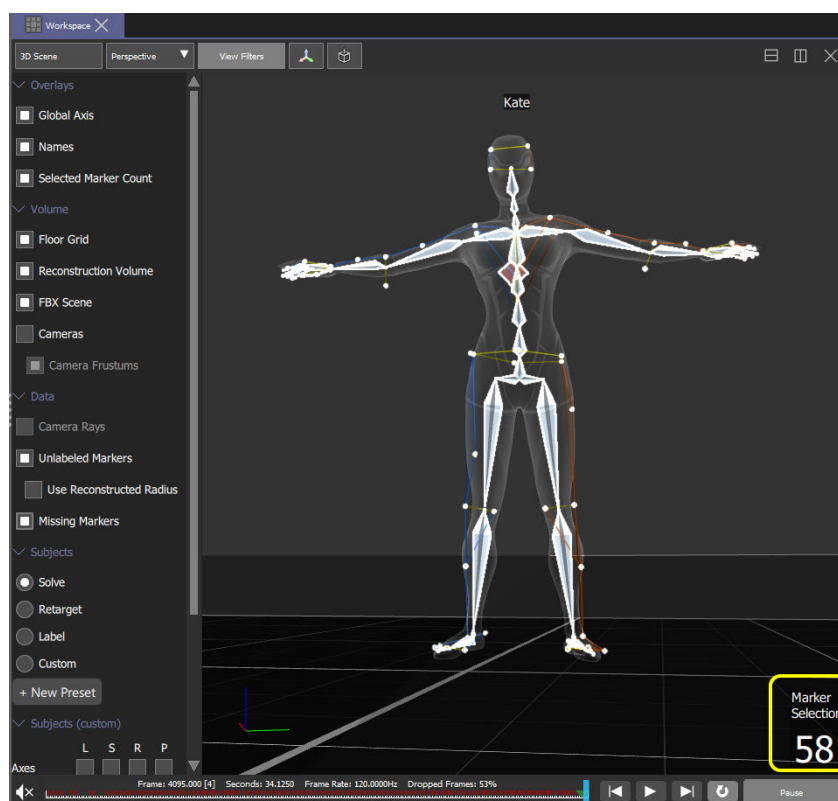


2. At the bottom right of the view pane, the **Marker Selection** count is displayed. If no markers are currently selected, a zero is displayed.



Create subjects

3. As you select markers in the view pane, the Marker Selection counter changes to display the number of selected markers.

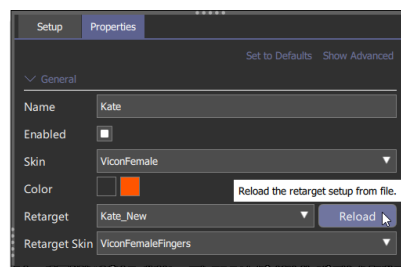


Create subjects

Load a retargeting setup

If you're retargeting your fully calibrated subject onto a target FBX, you can now load the retargeting setup file (VSR) and link it to your subject.

1. Ensure the retargeting setup files (.vsr) and skins (.fbx) that you want to use are located in the relevant folders:
 - VSR: C:\Users\Public\Documents\Vicon\Retargets
 - FBX: C:\Users\Public\Documents\Vicon\Skins
2. To turn on retargeting in Shogun Live, in the Processing pane, go to the General section and set the Processing Output Level to Retarget.
3. In the Tracking panel, ensure the relevant subject is selected and then click on the Properties tab.
4. In Retarget field, select the required VSR file(s) and then click Reload .



Your character is now retargeted in the 3D workspace.

5. To select or change a skin for the retargeting, click the Retarget Skin field and select the required skin.
6. If you notice discrepancies between the retargeted character and the performer driving it, you will need to modify the retargeting. For information on creating and modifying retargets, see [Retarget with Shogun Post \(page 206\)](#).

Troubleshoot subject calibration

This troubleshooting section covers the following aspects of creating and calibrating a subject in Shogun Live:

- [A-pose booting \(page 119\)](#)
- [Subject calibration \(page 120\)](#)

A-pose booting

- [My subject doesn't pass the A-pose detection stage. \(page 119\)](#)
- [The system says "Awaiting boot". \(page 120\)](#)

[My subject doesn't pass the A-pose detection stage.](#)

Look in the log for an explanation as to why the A-pose cannot be detected or why it has been rejected.

- Are any markers reported as missing? If yes:
 - Is the correct skeleton template being used?
 - Are all the required markers attached to the subject?
 - Does the subject calibration volume include all the reconstructions?
- Does the subject also seem to have labeling issues? If yes:
 - If labeling clusters are attached to the subject, have you created them in Shogun? Have you verified that the labeling clusters you have created are selected?
 - Is the subject standing in a valid A-pose? A valid A-pose assumes that the subject:
 - Stands straight
 - Has their feet pointing forward (ie, the feet are not splayed)
 - Has their palms pointing to the floor
 - Poses their arms at an angle of 45 degrees from the trunk
 - Poses their arms in such a way that they lie in the plane of the torso.

Create subjects

- Are there any joints reported as out-of-range? If yes:
 - Is the A-pose valid (see the above criteria)?
- Is the A-pose still rejected after you've completed all the previous checks? If yes:
 - On the Tracking panel, go to the Subject Calibration section and increase the value for **A-Pose Joint Range Threshold** (default value: 1.25) to 1.75 and check if this solves the issue.
Note that subjects who cannot stand in an A-pose as well as small subjects usually require the higher threshold. If you don't need a higher threshold, use the default value.

The system says "Awaiting boot".

This message means that the A-pose has been detected and successfully sent to the tracker subsystem. However the tracker subsystem is unable to label the subject from the current pre-calibrated skeleton.

- Is the subject standing in a valid A-pose?
- Does the subject calibration volume correctly exclude marker reconstructions that are not related to the subject under consideration?

Subject calibration

- [Calibration of the solving skeleton is jittery. \(page 120\)](#)
- [The result of the solving skeleton calibration looks bad. \(page 121\)](#)
- [The labeling clusters won't attach to the subject. \(page 121\)](#)
- [During subject re-calibration, the labeling clusters were detached from the subject. \(page 121\)](#)

Calibration of the solving skeleton is jittery.

During live subject calibration, jittery refinements of the solving skeleton may occur with some subjects.

Jittery refinements are unimportant as long as the subject obtained at the end of the calibration process is correct.

Create subjects

The result of the solving skeleton calibration looks bad.

Capture a new ROM and ask the subject to:

- Spend more time moving the legs, waist and arms first. Make sure that the motion includes all the joint capabilities. For example, lunging is not sufficient to calibrate the legs. Think of side motion as well and, if possible, intermediate poses obtained by rotating the thigh joints.
- Remember that the more time that is spent on these limbs, the more frames the optimization process receives.
- Avoid a ROM where legs are constantly static and only move in a limited way at the end of the ROM.

Still observing issues?

- Report the problem to [Vicon Support](#)¹⁶, with relevant data. In addition to helping to find a solution to your issue, your input also helps to improve solving skeleton calibration in future releases.
- Use Shogun Post's Auto-Skeleton feature to obtain a new solving skeleton. Issues with the solving skeleton do not affect the labeling process during live subject calibration, so you can directly re-use the labeled ROM from Shogun Live for Auto-Skeleton.

The labeling clusters won't attach to the subject.

Ensure at least 10 calibration frames are collected. Shogun only collects these frames if the ROM includes some motion.

During subject re-calibration, the labeling clusters were detached from the subject.

This is expected behavior at the start of the re-calibration process. At least 10 calibration frames must be collected before labeling clusters are re-attached to the subject. This is not possible unless the ROM includes some motion.

¹⁶ <mailto:support@vicon.com>

Create props

Create props

In Shogun Live, you can create simple, single-segment (and therefore rigid) props.

For information on working with props, see:

- [Place markers on props \(page 124\)](#)
- [Move props \(page 128\)](#)
- [Work with static meshes \(page 130\)](#)

For information on creating a prop as a custom L-frame, see [Set the origin with a custom L-frame \(page 87\)](#).

Create props

Load subjects and props via .mcp file

For an easy way to quickly load subjects and props from an existing scene, you can load an *.mcp* file directly into Shogun Live.

To quickly load subjects and props from an *.mcp*:

1. At the top of the Tracking panel, click the Load tracking configuration button



2. From the Load Tracking Configuration dialog box, select or browse to the required *.mcp* file.

The subjects and props are displayed in the Tracking panel as normal.

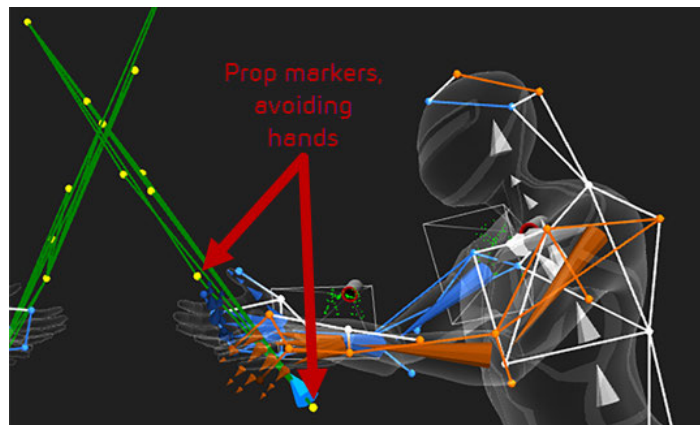
Create props

Place markers on props

When placing markers on props, note that minimum of four markers is recommended for each prop. Be sure to:

- Place the markers across the prop object to reach the extremities as far as possible.
- Avoid placing markers in a straight line and/or on the same plane.
- Avoid placing markers symmetrically.
- Prevent marker swaps by avoiding placing prop markers too close to the hands or where the actor will interact with the prop.

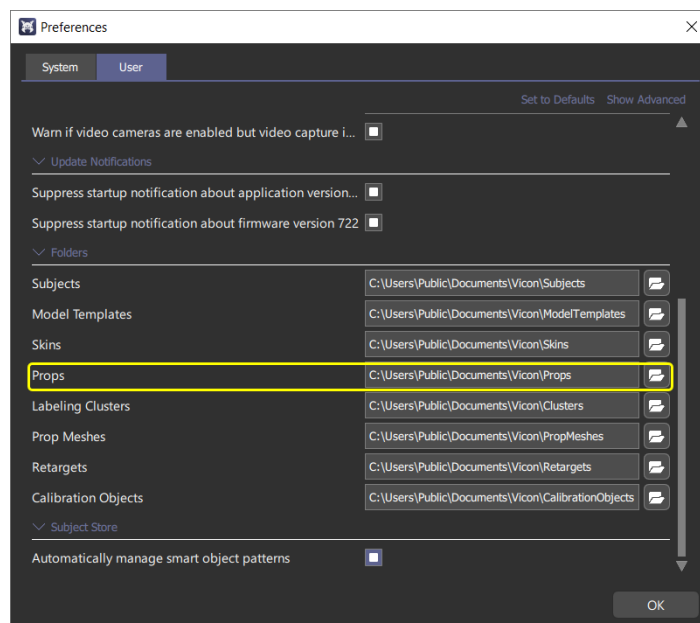
For example, if a performer will interact with a prop, place markers at the extremities of the prop, but not directly in the location where the interaction occurs, as shown below, where a performer holds a sword:



Create props

To create a single-segment prop:

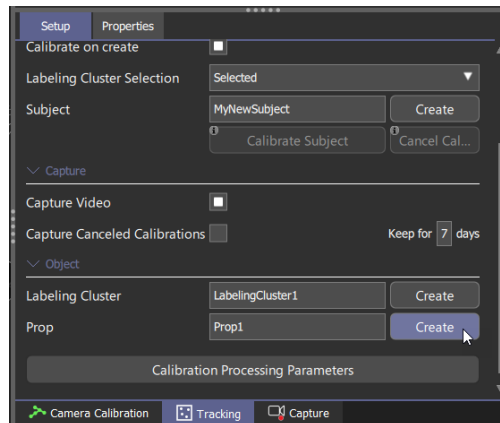
1. Ensure the markers are positioned on the prop as described above.
2. Place the prop in the volume.
3. In Shogun Live, in the **Settings** menu, click **Preferences** (or press SHIFT+P).
4. In the **Preferences** dialog box, on the **User** tab, go to the **Folders** section and ensure that the **Props** folder is as required, or if not, click the button to the right of the Props line to specify the appropriate folder.



5. In the **3D Scene**, select a minimum of four reconstructed markers. To ensure that Shogun Live places the bone logically within the prop, select (CTRL+click) the markers in the following order:
 - The first selected marker defines the origin (base) of the prop bone.
 - The second selected marker defines the end of the prop bone.
 - Any other markers can be selected in any order.

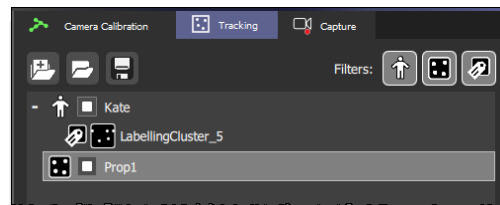
Create props

- In the Tracking panel, in the Prop field, enter a name for the prop and click Create.



A single-segment prop is created from the selected markers and appears in the 3D Scene in the orientation defined by the order in which you selected the markers in the previous step.

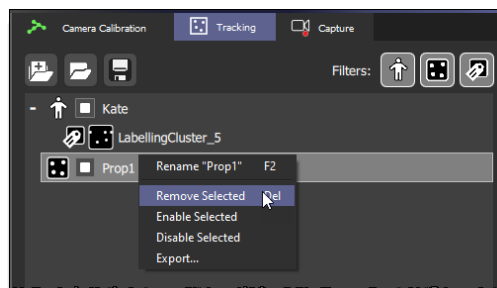
The prop is displayed as a node on the Tracking panel on the right of the Shogun Live window, under Props.



The prop's .mcp file is saved to the location specified in step 4 above.

Create props

7. If required, to select a mesh for the prop, or to change its color, ensure that the prop is selected in the Tracking panel and then choose a mesh and/or color on the **Properties** tab. Prop meshes are FBX files, by default stored in: *C:\Users\Public\Documents\Vicon\PropMeshes*.
8. To rename or to remove a prop from the current scene, in the Tracking panel, right-click the prop and then click the relevant option. (You can also double-click on the prop to rename it.)



After you have saved props, you can import them into subsequent takes as required.

Note that in addition to creating simple, single-segment props, you can also import both simple props and more complex, multi-segment props by clicking the **Import Subject** button at the top of the Tracking panel.

Tip

An efficient way to evaluate filter performance to ensure the smoothest possible tracking for selected objects is to create object presets with different values for the filtering properties. You can then apply them to selected objects using the saved object presets. For more information, see *Create and apply object presets in Getting more from Vicon Shogun*.

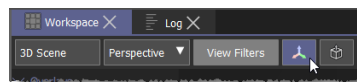
Create props

Move props

To move props in Shogun Live, you use the Object Manipulator, at the top of the 3D Scene view.

To use the Object Manipulator:

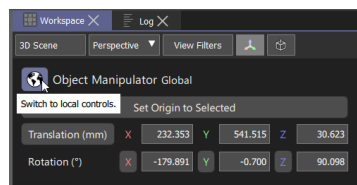
1. Pause the real time (press the spacebar or click the Pause button or the Play/ Stop button) and in the Tracking panel on the right, select the object that you want to move.
2. If the Object Manipulator isn't displayed, click the Object Manipulator button or press M



Tip

To scale the manipulator, press the + or - keys.

3. Drag to move the prop in the 3D Scene view or enter the required values in the Object Manipulator fields.
4. To change between global and local values, click the Object Manipulator symbol:

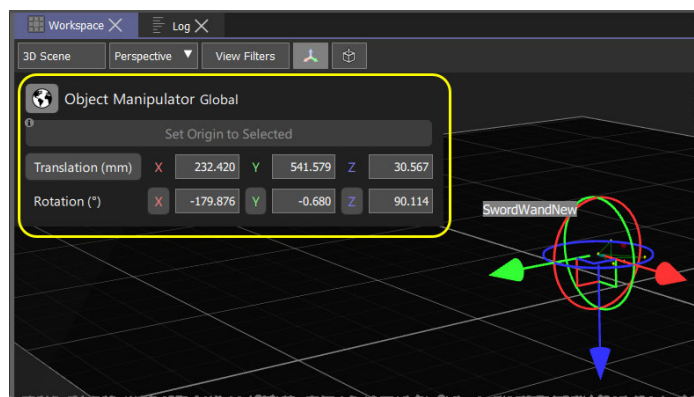


Create props

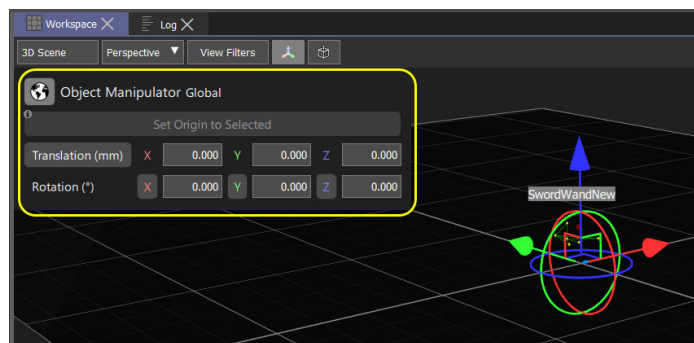
You can use the manipulator to quickly align a prop to the world axis.

To align a prop to the world axis:

1. Pause the real time and in the Tracking panel on the right, select the prop you want to align and press M to display the Object Manipulator. In the Workspace (3D Scene view), the Object Manipulator is displayed. By clicking on the Object Manipulator symbol (top left), you can set it to Local (values at zero) or Global (values relative to the scene origin).



2. To align the selected prop to the scene origin, ensure the Object Manipulator is set Global and change all the values to zero.




Create props

Work with static meshes

With Shogun Live 1.6 and later, you can import objects (FBX files) that represent set pieces and LED display walls into Shogun Live and manipulate them within your scene. This is useful when setting up your 3D environment, enabling you to:

- Calculate the positions of scenery and LED display walls within the tracked space.
- Position actors within the tracked space.
- Approximately place cameras ahead of a shoot.

To import a static mesh into your scene:

- In Shogun Live, at the top of the **Tracking** panel, click the **Import Mesh** button , locate the required FBX file, and click **Open**.
When meshes are imported, for convenience they are copied to `C:\Users\Public\Documents\Vicon\SceneMeshes`.

To change the mesh to a previously imported mesh:

- In the **Tracking** panel, select the object and on the **Properties** tab, click the **Mesh** list and select the required mesh from the list.

You can translate and rotate the object mesh in the same way as you manipulate other props (see [Move props \(page 128\)](#)).

After you have finished capturing your scene that contains a static mesh, you can load the resulting MCP file into Shogun Post. For information, see [Load static meshes into Shogun Post \(page 131\)](#).

Note

To manipulate a static mesh, first pause the real time by pressing the space bar or clicking **Pause**. Also note that after you move or remove static meshes, the change is not displayed until you press the space bar or click **Pause** again.

Create props

Load static meshes into Shogun Post

In Shogun Post 1.6 and later, you can load an MCP file that was captured in Live and contains a static mesh. When you load the MCP file into Post, the static mesh is displayed as an object whose default translation and rotation values are those that you specified in Shogun Live.

The default path to which static meshes are saved is:

- *C:\Users\Public\Documents\Vicon\SceneMesh*
As with other default locations, you can change the path by editing it in the **Preferences** dialog box (on the **General** menu, click **Preferences** and on the right of the **Directories** tab, click **Scene Meshes**).

Capture a take

Capture a take

Vicon Shogun Live enables you to go straight from live capture to post processing. Data is saved as a mocap file (.mcp), which contains a copy of the current calibration, active subject, and real-time data, along with paths to the .x2d (an XML file, which contains 2D camera data) and any video cameras in the system. As soon as you've captured takes (.mcp files), you can replay and review them without leaving Live. For cleanup, you open the .mcp file in Shogun Post.

In addition to the following information about capturing with Shogun Live, see also the Vicon video:

[7 - Shogun Live - Capture Direct to Disk and Realtime Settings](#)¹⁷

To find out about streaming real-time data from Shogun Live into Autodesk MotionBuilder, Unity, or Unreal Engine 4, see the Vicon video:

[8 - Shogun Live - Streaming to Game Engines](#)¹⁸

i Note

If cameras are bumped after they have been calibrated, or if any other issue with your system is detected, Shogun displays warning icons. For more information, see [Understand the system health icons](#) (page 143).

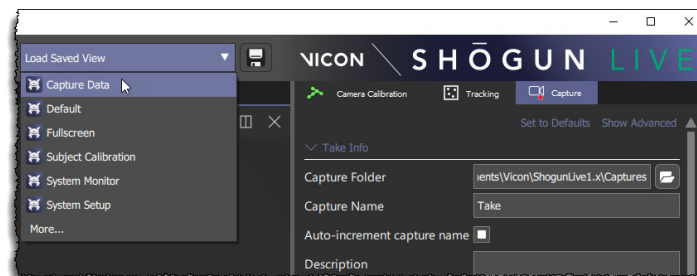
¹⁷ <https://vimeo.com/218944993>

¹⁸ <https://vimeo.com/218944997>

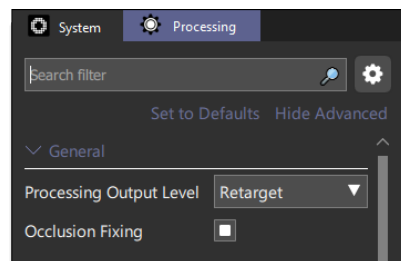
Capture a take

To capture a take:

Note that for capturing takes, you may find it easiest to use the **Capture Data** layout to display the views and panels that you will use for motion capture. To do this, in the **Load Saved View** list at the top right of the menu bar, click **Capture Data**.



1. Ensure you have completed the necessary preparations, described in [Create subjects \(page 98\)](#) and [Create props \(page 122\)](#).
2. At the top of the **Processing** panel, in the **General** section, make sure that the **Processing Output** level is set to **Retargeting** (the default) or **Solve**, depending on your requirements, and that **Occlusion Fixing** is selected.

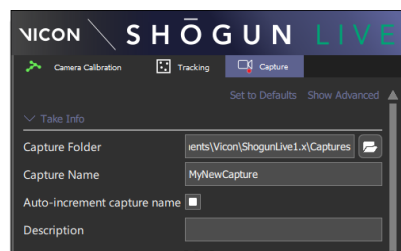


✔ Important

To ensure you record the required data, always check the **Processing Output** level before capturing. Normally, make sure it is set to **Retargeting** (the default) or **Solve**. If you set it to **Reconstruct**, the system will save only reconstructed data, and you will not see any labels or a solving skeleton when you open the data in Shogun Post. Similarly, if you select **Label**, you will not see a solving skeleton in Post.

Capture a take

3. On the right of the Shogun Live window, ensure the **Capture** tab is selected.
4. In the **Take Info** section, click the folder icon to the right of the **Capture Folder** field and select the **Session** folder that you created as described in [Create a folder hierarchy to store takes](#) (page 57). Anything you capture from now on will be saved inside the database you created.
5. In the **Capture Name** field, enter a suitable name that will enable you to identify the take.



6. If you will be capturing multiple takes, to append a number at the end of the capture name for each take in the sequence, ensure **Auto-increment capture name** is selected.
7. If required, add text to the **Description** field. Note that if preferred, you can add comments after capture in the Eclipse database (also accessible in Shogun Post in the **Data Management** panel).
8. In the **Capture** section, note the options to capture processed data and video data. The option selected by default is **Capture Processed Data**. If the **Solve** option is selected in Step 2 above, this includes 3D labels and solving bones. To capture video from Vicon video cameras, select **Capture Video**. This lets you view a video overlay to check your 3D data in Shogun Post.



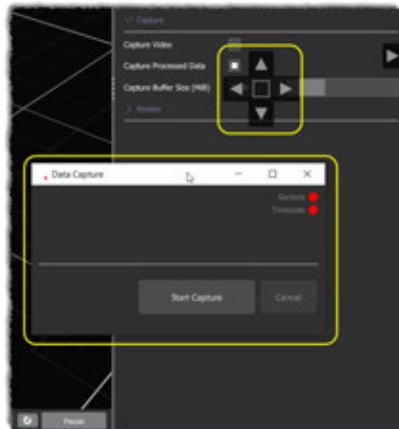
Tip

A fast SSD is required to capture large datasets to disk. If you're using live video, a second SSD is recommended.

The **Capture Buffer Size** is also displayed. This represents the amount of memory allocated to Shogun Live's capture. By default, this is set to 2 GB, which should be enough for most situations. For multiple video cameras, you may need to set it higher. You are recommended to always record your data onto a fast SSD drive.

Capture a take

9. Before capturing any data, you may want to reposition and/or resize the **Data Capture** panel as required (to move it, drag its title bar).



10. In the **Data Capture** panel (by default at the bottom right of the Shogun Live window), click **Start Capture**.
In both the panel and in the menu bar at the top of the view pane, a flashing red circle and **Capture Active** are displayed.

✔ **Tip**
If possible, begin and end each take with the performer(s) in an A-pose. This can help with labeling and retargeting.

Data is captured to disk at your source frame rate.
If you are using an external timecode generator, in the **Data Capture** panel you can see the current timecode being received, and green icons, indicating that the system is running at genlock at the specified standard. This panel also displays any issues with the capture.

Capture a take

The bar at the bottom of the **Workspace** displays red marks when the real-time system cannot keep up with the target frame rate and has to drop a frame. The percentage of dropped frames is also shown. Unless this number becomes very high (above 30%), you can continue to capture. If it is above 30%, this normally indicates that your system is out of calibration, and can't keep up with amount of data currently being processed. In this case, you may need to re-calibrate or even upgrade your PC.

The *.x2d* data from the cameras is also recorded. When you load the *.mcp* file in Post, *.x2d* data can be used to fix dropped frames (for more information, see [Load mocap data files into Shogun Post \(page 154\)](#)).

11. When you have captured the required take, click **Stop Capture**. Shogun Live saves the necessary files to the folder specified in the **Take Info** section (see Step 4 above).
12. Depending on whether you want to remain in Shogun Live to continue capturing or move to Shogun Post for cleanup and further processing, you can now do one of the following:
 - Capture another take, as described above.
 - Review the last take (or other recent takes) while remaining in Shogun Live. (For more information, see [MCP review in Shogun Live \(page 138\)](#)); or
 - Load the data into Shogun Post. For information, see [Load mocap data files into Shogun Post \(page 154\)](#).

i **An alternative to live solving subject calibration**
 In Shogun 1.6 and later, if you find that after Live calibration the solve requires much tweaking, for a post-processed alternative, try Auto-Skeleton in Shogun Post. For information, see *Use Auto-Skeleton in Getting more from Vicon Shogun*.

Capture a take

Load subjects and props via .mcp file

For an easy way to quickly load subjects and props from an existing scene, you can load an *.mcp* file directly into Shogun Live.

To quickly load subjects and props from an *.mcp*:

1. At the top of the Tracking panel, click the Load tracking configuration button



2. From the Load Tracking Configuration dialog box, select or browse to the required *.mcp* file.

The subjects and props are displayed in the Tracking panel as normal.

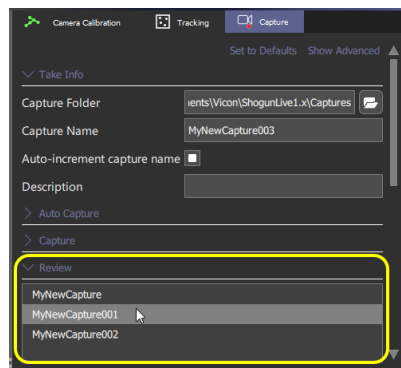
Capture a take

MCP review in Shogun Live

Shogun Live enables you to replay takes as soon as you've captured them. MCP review enables you to review a take (.mcp file), update your notes on a take, or investigate technical issues, all without having to leave Live. When you've finished reviewing the take, you can immediately resume capturing.

To review takes in Live:

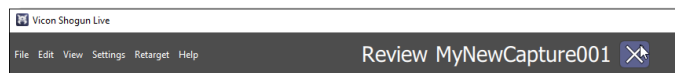
1. Ensure that you have at least one take in the Session folder (see [Capture a take \(page 132\)](#)).
2. On the **Capture** panel, in the **Review** section, click the required row.



3. If required, you can change the **Description** and **Notes** fields at the bottom of the Review section.
4. To review the selected take, double-click the row.
At the top of the Shogun Live window, in the center of the menu bar, the word **Review** is displayed, followed by the title of the selected take.
At the bottom of the screen a time bar displays information about the selected take. It shows you the current frame, current timecode and duration.

Capture a take

5. To play through the take, you can use the Play/Stop button and the Go to beginning and Go to end buttons to the right of the time bar. You can also press the default A and S hot keys to scrub back and forward one frame at a time (to change hot keys, click **Manage Hot Keys** on the **User Preferences** tab (Shift+P)).
6. To close review mode and return to capturing, click the exit button to the right of the take title in the menu bar.



Note

Shogun Live is either in capture mode (ie live) or in review mode for a single take. You cannot view both live and captured data simultaneously, or compare two takes.

For more information, see:

- [Streaming via Vicon DataStream SDK \(page 140\)](#)
- [MCP review via Shogun Live SDK \(page 141\)](#)
- [Review Vicon Video and SDI video files \(page 141\)](#)
- [Review raw camera data \(page 142\)](#)

Capture a take

Streaming via Vicon DataStream SDK

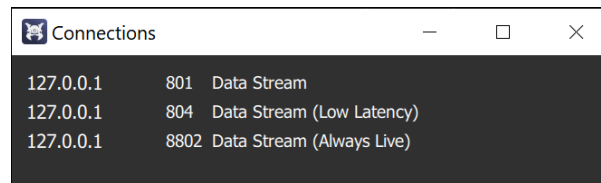
The current data in Shogun Live is served to Vicon DataStream SDK clients over port 801, so that MotionBuilder and Unreal show the reviewed clip when Shogun Live is not capturing.

For clients that require uninterrupted live, an additional DataStream SDK server sends the current live data over port 804.

Monitor datastream connections in the Connections panel

Shogun 1.6 and later enables you to display the current connections for the datastream ports. To do this:

- On the View menu, click the new **Connections** option to display the Connections panel.



Capture a take

MCP review via Shogun Live SDK

You can launch and control MCP review using the Live SDK.

For more information, see the Live SDK sample script included in the API package (by default installed in `C:\Program Files\Vicon\ShogunLive1.#\SDK\`) and the information in the supplied code.

The sample script (`playback.py`), enables you to open an MCP for review in Shogun Live by specifying a capture name, as shown in the following example, or just review live data if no name is specified.

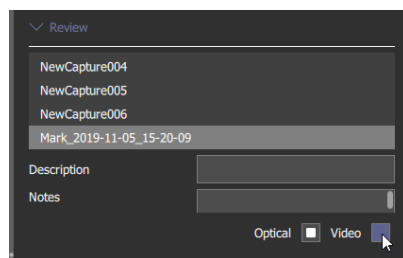
```
python playback.py --name Jack_Fin_2019-10-15_17-19-26
```

For more information on using Python with Shogun, see *Python scripting with Vicon Shogun*.

Review Vicon Video and SDI video files

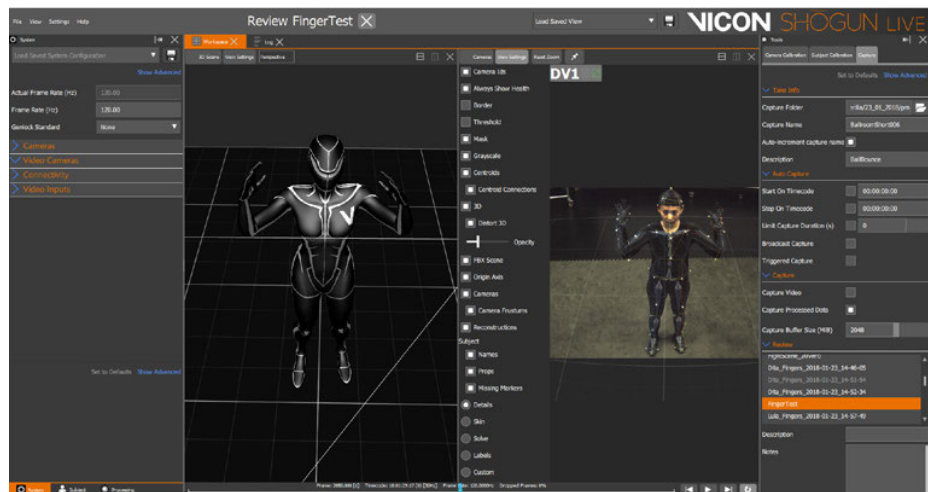
You can check your reference footage against what was captured, including any overlay of the 3D mesh. To do this:

1. Load an `.mcp` file with video data into MCP review (see [MCP Review in Shogun Live \(page 138\)](#)).
2. On the **Capture** tab, in the **Review** section, select **Video**. (Note that this option is cleared by default, as performance may be affected in files with multiple video cameras.)



Capture a take

3. Play or scrub through the review of the take, which includes data from Vue or SDI video cameras.



Review raw camera data

You can check raw data for captured takes. This can be useful when troubleshooting or investigating possible issues. To do this:

1. Load an .mcp file into MCP review (see [MCP Review in Shogun Live \(page 138\)](#)).
2. Ensure the View Filters are set as required.
3. Play or scrub through the take and review the raw data as required.

Capture a take

Understand the system health icons

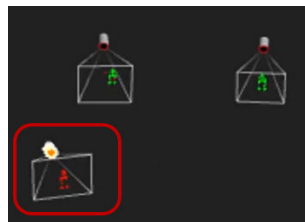
In addition to the following information, see also the Vicon video [5 - Shogun Live - System Health and Camera Fixing](#)¹⁹, which covers how to monitor and maintain the health of your Vicon Shogun system.

Throughout Shogun Live, the color red is used as a warning of possible issues, the color green is used as an indicator of good system health, while the colors between these extremes (orange, amber, yellow) are used to indicate an interim state.

For example, the color of centroids that are displayed in the **Cameras** view indicates the current state of camera calibration:

- Centroids that are not contributing are displayed in red in the **Cameras** views, indicating that the relevant camera is not well calibrated.
- Centroids from uncalibrated cameras are displayed in gold.
- Centroids from calibrated cameras are green, indicating they are now contributing.








In a **3D Scene** view, the color of the markers shown in the representations of the cameras also indicates whether or not the camera is contributing to the reconstructions. As elsewhere in Shogun, the color red indicates an issue, and helps you to identify a problematic camera.



¹⁹ <https://vimeo.com/218944981>

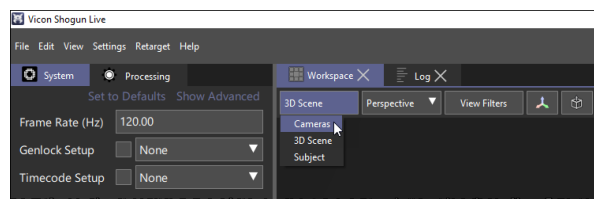
Capture a take

On the **System** tab, the camera icons give you an overall indication of the cameras' status.

Icon	Meaning
	Camera is active or connected (and calibrated)
	Camera is not calibrated
	Camera is (manually) disabled
	Camera is connected but not contributing
	Camera is disconnected
	Camera has been bumped since calibration
	General warning symbol indicating an error

To display more information about the status of a camera:

1. In the **Workspace**, select the **Cameras** view.

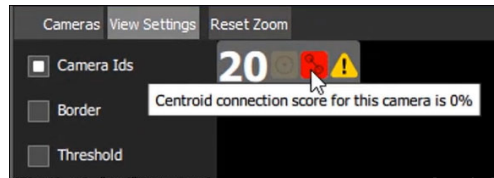


2. On the **System** tab, click a camera.
3. At the top of the **Cameras** view, hover the mouse pointer over the Centroid connection score icon:



Capture a take

Note that, as usual, the color of the icons at the top of the **Cameras** view provides an additional indication of the camera status.

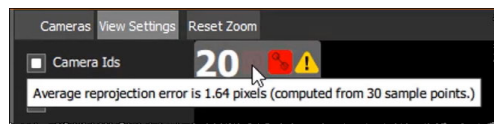


This icon represents the centroid connection score: for the selected camera, the percentage of centroids that are contributing to reconstructions. A low centroid connection score (as shown in the above example), indicates issues with the selected camera.

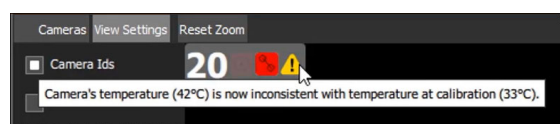
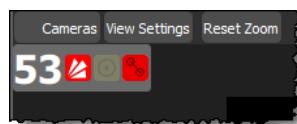
4. Hover the mouse pointer over the **Average reprojection error** icon:



This icon represents the reprojection error: the distance between the 2D image of the markers on the camera and the 3D reconstructions of those markers projected back to the camera sensor.



5. To investigate camera status further, hover the mouse pointer over any additional camera status icons to the left or right of the other two icons. These additional icons provide further information about the state of the camera: eg, a bumped camera icon and/or a camera temperature warning.



For information about bumped cameras, see [Fix bumped cameras \(page 146\)](#). If one or more camera's operating temperature is inconsistent with its temperature at calibration, re-calibration is necessary (see [Calibrate cameras \(page 75\)](#)).

Capture a take

Fix bumped cameras

In addition to the following information, see also the Vicon video: [5 - Shogun Live - System Health and Camera Fixing²⁰](#).

Vicon cameras with accelerometers (Vicon Vantage, Vero and Vue), provide a bump detection feature. On these cameras, the status indicators flash red when the camera is bumped and (on Vantage cameras only) the OLED display changes to indicate a bumped camera. In the Vicon Shogun Live **System** panel, icons are displayed to the right of the camera names to indicate a bump.



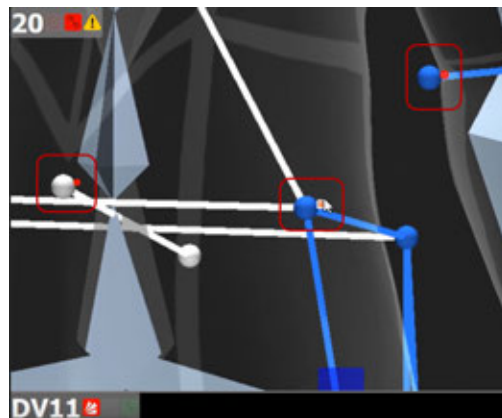
To prevent you from having to recalibrate the whole system after a camera has received a minor bump, when a calibrated subject (or prop, or wand) moves through the volume, cameras automatically detect whether further action is necessary:

- If a calibrated subject moves through the volume and the cameras have returned to their original position, the cameras' bump status indicators change from red back to blue and in the **System** panel, the bumped icons disappear.
- If you need to take further action, the status indicators continue to display an error and the bumped icons remain on the **System** panel.

²⁰ <https://vimeo.com/218944981>

Capture a take

As an additional check, in the **System** panel click the camera with the bumped icon to select it and in a **Cameras** view, zoom in on the markers. When a camera is bumped, red warning symbols are displayed, indicating the difference between where the system expects the markers to be, and where they actually are.



Shogun Live enables you to quickly correct a camera whose position has changed due to having been bumped or moved, using any labeled object in the volume – subject, prop, or wand, and the **Recover Camera Position** feature.

⚠ Important

You can use **Recover Camera Position** to recover cameras that have been either bumped or moved. This process relies on having enough cameras within a calibrated system to act as a calibration anchor. For this reason, it is recommended that it is run on only a small proportion of the cameras in a system. A single camera or a small number of affected cameras can be recovered with good results. If a larger number of cameras is affected, perform a full camera calibration instead (see [Calibrate cameras \(page 75\)](#)).

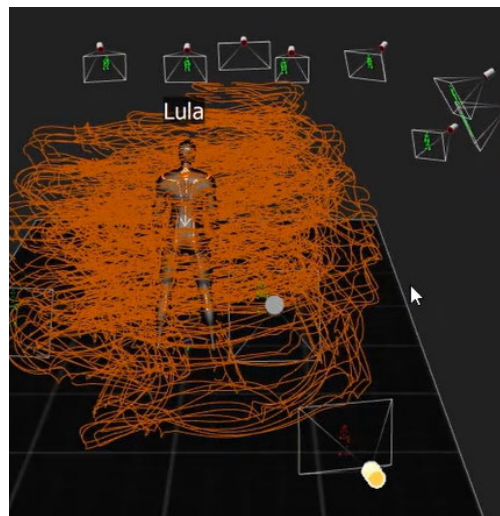
Capture a take

Correct a bumped or moved optical camera

The following procedure corrects a bumped optical camera (Vantage or Vero):
for bumped video cameras, see [Correct a bumped Vicon Vue video or SDI video camera](#) (page 149).

1. On the **System** tab, select the camera that was bumped or moved.
2. On the **Camera Calibration** tab, click **Start Recover Camera Position**.
3. In the volume, have the subject move (or move the labeled object) in front of the affected camera.

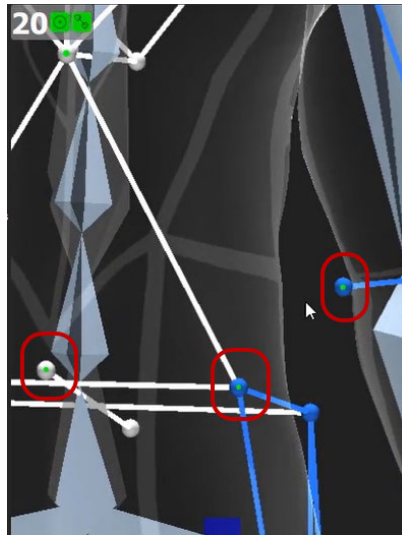
In the **3D Scene** view and **Cameras** view, you can see orange trails as the system determines the offset between the camera and the rest of the calibration.



4. When enough of the view has been covered (indicated by orange trails that thickly cover the affected camera view, as shown above), click **Stop Recover Camera Position**.

Capture a take

5. In the **Cameras** view, zoom in and check that the markers are now aligned, with no red warning symbols.



The camera is now correctly aligned with the rest of the system. Note that masking of the affected camera is not preserved, so for optimum results, you may need to mask this camera again. For information, see [Mask cameras \(page 77\)](#).

Correct a bumped or moved Vicon Vue video or SDI video camera

Note that to correct a Vue camera, you need to use active markers, so ensure you have a Vicon Active Wand to use during the procedure.

1. On the **System** tab, select the video camera(s) that are bumped, or that have been moved.
2. On the **Camera Calibration** tab, click **Show Advanced**.
3. With the video camera(s) still selected, in the **Calibration Wave** section, click **Start Wave (Selected)** and, with **Auto Stop** selected, wave the wand for just the selected cameras and wait for the calibration to finish.

Capture a take

In the 3D Scene and the Cameras view, the camera view is covered with orange trails.



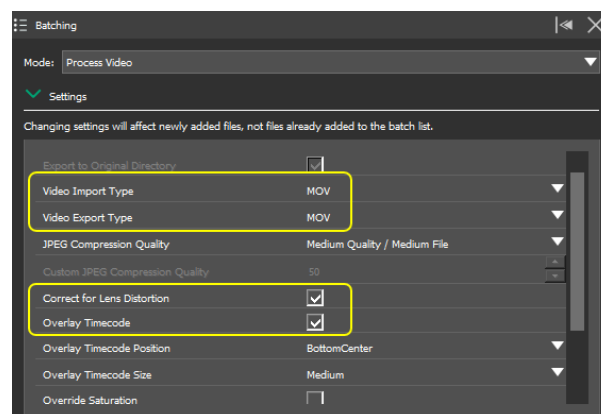
4. In the Cameras view, zoom in and check that the markers are now aligned.



Capture a take

Transcode video files

You can use Vicon Shogun Post's batch-processing feature to convert raw Vicon video files (.vvid) captured from Vicon video cameras (Bonita Video or Vue) to .mov files, using Bayer conversion. Batch transcoding to .mov produces smaller video files that can be used in third-party applications as well as within Shogun, and enables you to easily move the files to an appropriate location for use in Post. In Shogun 1.5 and later, you can also batch-process auto compressed .mov files in Post to un-distort the video and overlay the timecode.



(For information on setting up video cameras to capture directly in Shogun Live to .mov format, see [Realtime video compression \(page 74\)](#).)

The following steps provide a quick introduction to using Shogun Post to transcode video. For more information on batch processing with Shogun Post, see the Vicon video: [8 - Shogun Post - Batch Processing Data](#)²¹.

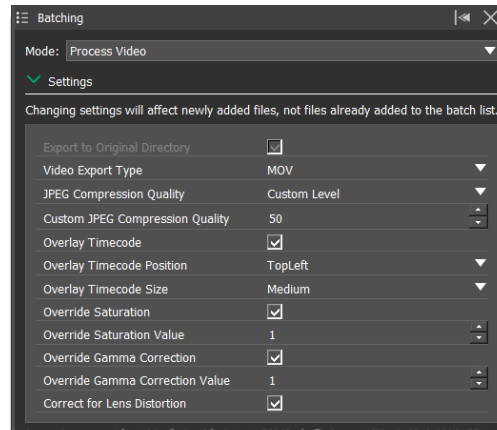
To transcode video files:

1. In Shogun Post, on the **Processing** tab of the ribbon, click **Batching**.
2. In the **Batching** panel, in the **Mode** field, select **Process Video**.
3. In the **Settings** section, ensure **Export to Original Directory** is selected (the default). When this option is selected, the converted .mov files are saved to the same location as the .x2d, whether your raw video files (.vvid) were saved to a custom location (such as an SSD) or are already in the same location as the .x2d.

²¹ <https://vimeo.com/218945109>

Capture a take

4. Ensure the Quality field is as required.



5. In the Files and Processing section, below the Batch Progress line, ensure no unwanted files remain from previous batch processes. (If you find any unwanted files, click on their names and then click the Remove button.)
6. Click the Add Files button and in the Import dialog box, select the .x2d, .vvid or .mov files that you want to transcode and click Open. (Use the .x2d option if you have multiple Vicon video cameras, as it transcodes all the related video files.)
The names of the files you added are displayed in the Files and Processing section near the bottom of the Batching panel.
7. Click Start.
8. To check that your files have been transcoded, when the Batch Progress bar turns blue and displays 100%, you can open the relevant folder (see Step 3 above) in Windows Explorer and see your transcoded file(s).

JumpOnly.x2d	4/11/2017 11:04 AM	X2D File	12,826 KB
JumpOnly.Take03	4/11/2017 11:04 AM	ENF File	1 KB
JumpOnly.mcp	4/11/2017 11:04 AM	MCP File	9,780 KB
JumpOnly.2098920_transcode	4/13/2017 10:49 AM	MOV File	983,036 KB
JumpOnly.2098920	4/12/2017 3:29 PM	Vicon Video File	727,214 KB

9. When you have checked that your files have all been transcoded and saved to the specified folder, you can delete them from their original location (for example, from an SSD).

Check data quality

Check data quality

After you have loaded your captured data files into Vicon Shogun Post, you can use its diagnostic tools to help you to identify any issues with the data. For more information, see:

- [Load mocap data files into Shogun Post \(page 154\)](#)
- [Review occlusion fixing \(page 158\)](#)
- [Check for swaps and other errors \(page 162\)](#)
- [Use video overlay to check accuracy \(page 163\)](#)
- [Get an overview with the time bar Issues map \(page 166\)](#)
- [Find issues using the Data Health view \(page 168\)](#)
- [Find issues using the Graph view \(page 171\)](#)
- [Work with time ranges \(page 173\)](#)

See also the Vicon videos:

- [2 - Shogun Post - MCP Loading²²](#)

and

- [4 - Shogun Post - Checking Data Quality²³](#)

²² <https://vimeo.com/218945087>

²³ <https://vimeo.com/218945095>

Check data quality

Load mocap data files into Shogun Post

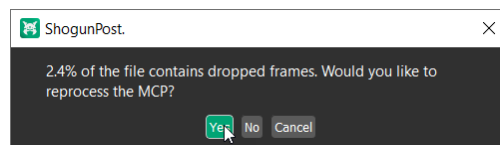
Note

Shogun Live can record processed real-time data (.mcp files) along with raw 2D camera data (.x2d files). You can use .mcp files as a starting point for processing in Shogun Post. Because the frame rate during real time can vary, .mcp files may contain missing (dropped) frames. When you open an .mcp in Shogun Post, if dropped frames are detected, a dialog box prompts you to confirm whether you want to reprocess the .mcp. The fixing operation requires an .x2d with the same name as the .mcp file to exist in the same folder.

- To load mocap data files (.mcp that contains everything captured in Shogun Live, or .vdf saved in Shogun Post) you can:
 - Open Windows Explorer, locate the files you saved and drag and drop them into the Shogun Post view pane; or
 - On the the File menu, click Open and locate your files; or
 - In the Data Management panel, locate the required file icon (an .mcp has a purple icon) and double-click it.

Although the recommended workflow is to load an .mcp file (processed real-time data), you can instead import an .x2d (raw 2D data), but in this case, you must run reconstruct, label, and occlusion-fixing operations before proceeding with any required cleanup.

If you chose an .mcp file and if dropped frames are detected, a dialog box informs you of the percentage of dropped frames in the file and asks whether you want to reprocess to fix them.



- To automatically reprocess the file to fix the dropped frames, click **Yes**. The .mcp file is opened into the scene and the entire take is reprocessed. The dropped frames are reconstructed, labeled and solved, smoothly integrating data from the related .x2d file into the existing data.

Check data quality

(If you click **No**, processing is quicker as Shogun Post just interpolates between the dropped frames, but note that no keys are created and you will still need to fix the dropped frames.)

3. You can now decide if you want to save the scene.

Fast MCP reprocessing

With Shogun 1.4 and later, you can use the following fast and easy ways to remove dropped frames from `.mcp` files in Shogun Post. This enables you to save time by reprocessing the `.mcp` files without having to load them into the scene.

- [Fast MCP reprocessing with HSL \(page 155\)](#)
- [Fast MCP reprocessing with ShogunPostCL \(page 156\)](#)
- [Fast MCP reprocessing in batch mode \(page 157\)](#)

Fast MCP reprocessing with HSL

You can use the `quickPost` command options to perform drop frame fixing directly to `.mcp` files. For details, see `quickPost` in the *HSL Scripting with Vicon Shogun*.

Check data quality

Fast MCP reprocessing with ShogunPostCL

You can also run the quickpost command to reprocess `.mcp` files directly from ShogunPostCL, for example:

1. To open ShogunPostCL, navigate to: `C:\Program Files\Vicon\ShogunPost1.7` and then double-click `ShogunPostCL.exe` to open the terminal.
2. In the ShogunPostCL terminal window, enter:

```
quickPost processingLevel -readMCP "C:\\myPath\\
\\myInputFile.mcp" -writeMCP "C:\\myPath\\myOutputFile.mcp";
```

Where:

- `processingLevel` = Any one of: `reconstruct`, `label`, `solve` or `retarget` (Note that if you specify `retarget`, the relevant retargeting setup must exist.)
- The path after `-readMCP` = The path to the `.mcp` file on which you want to run drop frame fixing. Ensure that the related `.x2d` file is located in the same folder.
- `myInputFile.mcp` = The name of the `.mcp` file on which you want to run drop frame fixing
- The path after `-writeMCP` = The path to the fully processed output `.mcp` file
- `myOutputFile.mcp` = A name for the fully processed `.mcp` file

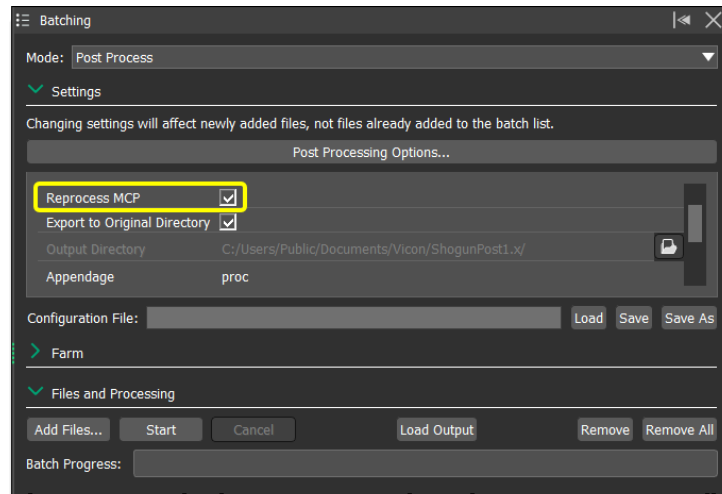
Check data quality

Fast MCP reprocessing in batch mode

If required, you can also fix dropped frames directly on multiple files in batch mode, as follows.

To directly reprocess MCP files in batch mode:

1. In the **Batching** panel, set the mode to **Post Process**.
2. In the **Settings** section, ensure **Reprocess MCP** is selected.



3. Set the required file path and naming options.
4. In the **Processing** panel, set the required processing settings.
5. In the **Batching** panel, expand the **Files and Processing** section, click **Add Files** and add the required **.mcp** files to the batch.
6. Click **Start**.
The **.mcp** files are processed without being loaded into Shogun Post. When you load the new **.mcp** file into Post, it is fully processed, with no dropped frames.

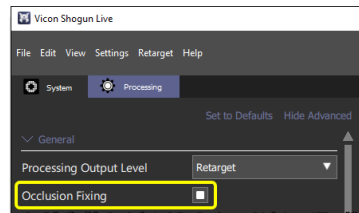
Check data quality

Review occlusion fixing

When you import an *.mcp* file or perform any processing that includes occlusion fixing, your first step is to review it to ensure that it is labeled correctly and that the automatic occlusion fixing worked well.

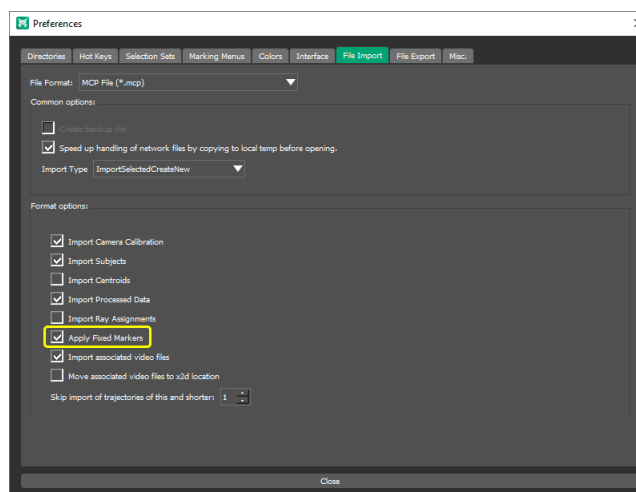
To review occlusion fixing in Shogun Post, both of the following (default) settings must be selected:

- In Shogun Live: Before capture, in the **General** section of the **Processing** panel, **Occlusion Fixing** must be selected.



This normally produces higher quality results, especially during occlusion-heavy moves such as interactions and when a subject is on the edge of the volume. Occlusion fixing is stored as a layer when the *.mcp* data is recorded.

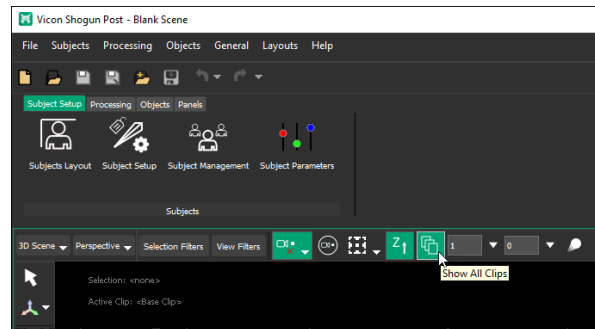
- In Shogun Post: Before importing the *.mcp* file that was captured with **Occlusion Fixing** selected as described above, in the **Preferences** dialog box (**General > Preferences**), on the **File Import** tab, in the **File Format** field, select **MCP File** and ensure **Apply Fixed Markers** is selected.



Check data quality

You can then compare the data before and after occlusion fixing in a 3D Scene view (or any other 3D view) in Post.

Note that, by default, in the 3D Scene view **Show All Clips** is selected:



This is necessary to enable you to view data from the backup clip, which contains the data before occlusion fixing, as well as the current (occlusion-fixed) clip.



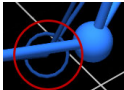
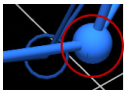


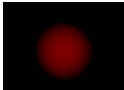
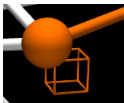
Important

If required, you can revert back to the raw data after loading the `.mcp` file into Shogun Post by using the **Restore** section of the **Marker Editing** panel.

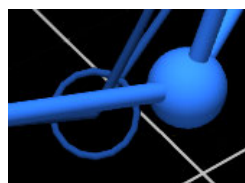
Note that the occlusion fixing algorithm affects **all** the markers on a subject. For this reason you should run occlusion fixing only once: either during capture in Shogun Live, or at the end of data processing in Shogun Post.

Check data quality

Before you start your review, ensure you can recognize the various types of data that may be displayed in the 3D Scene view, as listed below.

Symbol in 3D view	Description	Data type
	Circle	Original labeled markers from the backup clip. Displayed by default if the difference between the position of the original marker and the occlusion-fixed marker is greater than 1 cm.
	Sphere	Markers without gaps
	Sphere with a dot in the center	Markers that have been occlusion-fixed during a gap
	Sphere with a cross in the center	Markers that have had a gap manually filled
	Red sphere	Markers that are missing at the current frame
	Wireframe box	Constraint, showing expected location of marker

If circles are displayed for some markers during some time ranges, it indicates that the marker position was changed by more than 1 cm by occlusion fixing.



In this case, check the position of the occlusion-fixed marker. If it doesn't look right, the cause is likely to be either a labeling mistake or an occlusion-fixing error. To fix these problems, see [Correcting labeling mistakes \(page 161\)](#).

Check data quality

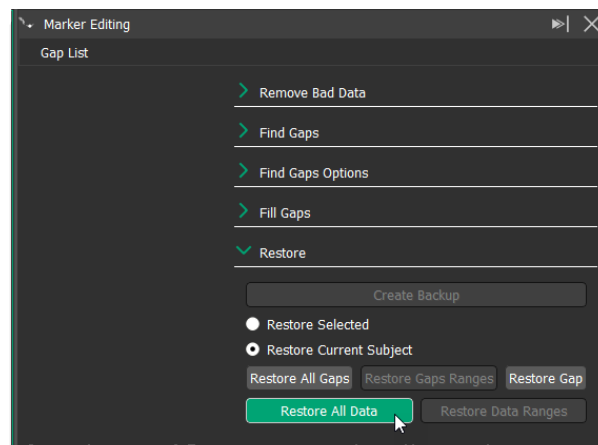
Correcting labeling mistakes

If you notice any swaps, mis-labels or other issues with marker data and the file has already been occlusion fixed, the recommended workflow is to restore the data back to its original state before it was occlusion-fixed.

You can do this on a per subject basis using the **Restore** section of the **Marker Editing** panel. Normally, restore the data across the whole take, because occlusion fixing across a range leads to jumps in the data.

The recommended workflow for dealing with problematic occlusion-fixed data is:

1. From the **Current Subject** chooser, select the required subject, or if you want to work on everything, select **All**.
2. In the **Restore** section of the **Marker Editing** panel, with selected subject active, click **Restore All Data**.



3. Fix any labeling issues that are present in your data. For more information, see [Use the Labeling panel \(page 180\)](#) and [Fix common labeling issues \(page 184\)](#).
4. Re-run occlusion fixing from the **Processing** panel.
5. Re-run **Solve Solving** to update the solving skeletons.

Check data quality

Check for swaps and other errors

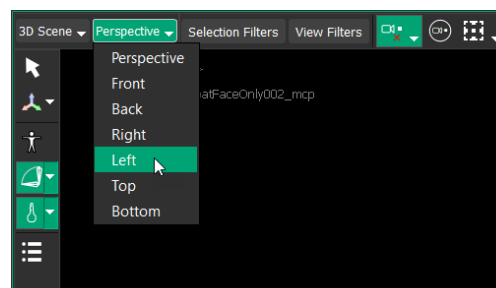


Important

Before filling gaps, you must find and fix any labeling swaps or errors in your data. Gap-filling in Shogun relies on the data before and after the gaps to predict marker location, so any labeling errors will cause gap-filling to fail.

To identify swaps and other errors, on the time bar, click the Play button to view your data in the **3D Scene** view. For a closer look, slowly scrub through the whole take (drag the current time indicator along the timeline, or for finer control, press the A or S key), carefully checking for any 'popping', unexpected movement or obvious misalignment.

For a more detailed view, use the normal mouse actions to move around the view: drag to rotate the view, right-click and drag to zoom in or out, left- and right-click and drag to pan. If you need to view the image from a different angle, you can use one of the orthogonal views.



Use the **View Filters** options in the **3D Scene** view to make it easy to recognize any issues. For more information on recognizing and correcting swaps and other errors, see [Fix common labeling issues](#) (page 184).



Tip

To snap a 3D view camera to selected object(s), press C or click the Snap button in the 3D Scene view toolbar.

Check data quality

Use video overlay to check accuracy

If your system includes Vicon video cameras, you can check your data accuracy by comparing optical capture data with supported video data. You do this by overlaying the 3D data onto the video (.vid or .mov) data.

Shogun Post supports the following types of video files:

- .vid files captured from Vicon Shogun Live using Vicon Bonita and Vicon Vue cameras
- .mov files that have been transcoded using Shogun Post or the standalone ViconVideoConverter tool (a command line tool that is installed with Vicon Video Viewer, by default to *C:\Program Files\Vicon\ViconVideoViewer*).

To overlay 3D data onto video files in Shogun Post:

1. Ensure that the video files are in the same folder as the required 3D data (.x2d or .mcp) file. If a different path was defined during capture (often an SSD per pair of cameras), use the batch transcoding feature of Shogun Post to ensure the files are moved to the correct location. For more information, see [Transcode video files \(page 151\)](#).

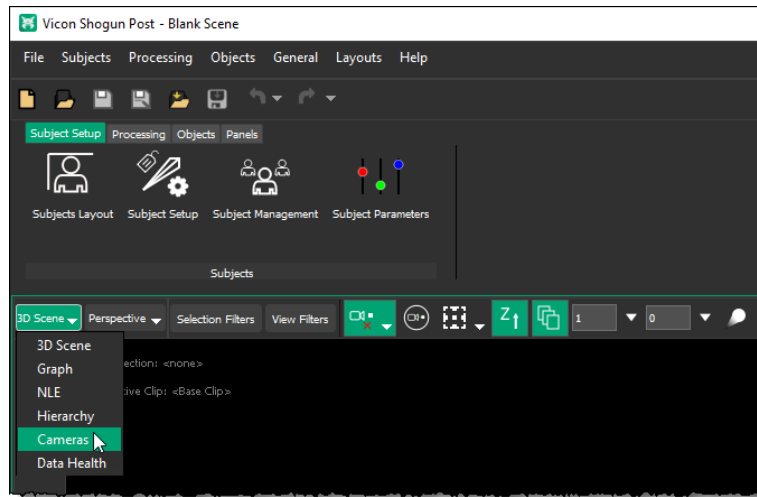
✓ Tip

If video files are kept in a different folder from the 3D data files, when you load an .x2d or .mcp file, Shogun Post warns you that the video files cannot be located. To manually specify the video file path, in the **Selection** panel (or **3D Scene** view) select the video camera, then in the **Attributes** panel, expand the **Video (Offline)** section and set its **Video_File** attribute to the path of the file. This change is saved when you save the scene in Shogun Post.

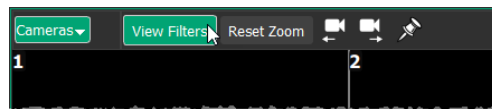
2. Open the .x2d or .mcp file (either from the **Data Management** panel, or click **Import** on the **File** menu, or drag and drop the relevant file from Windows Explorer, as described in [Load mocap data files into Shogun Post \(page 154\)](#)). The video files are automatically loaded.
3. In the **Selection** panel, expand the **System** node and click the required camera.

Check data quality

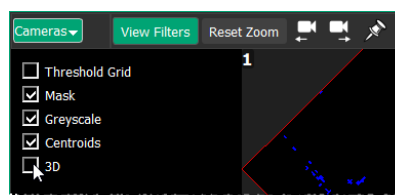
4. At the top left of the view pane, click the current View type button, and then click Cameras.



5. At the top of the Cameras view, ensure View Filters is selected.

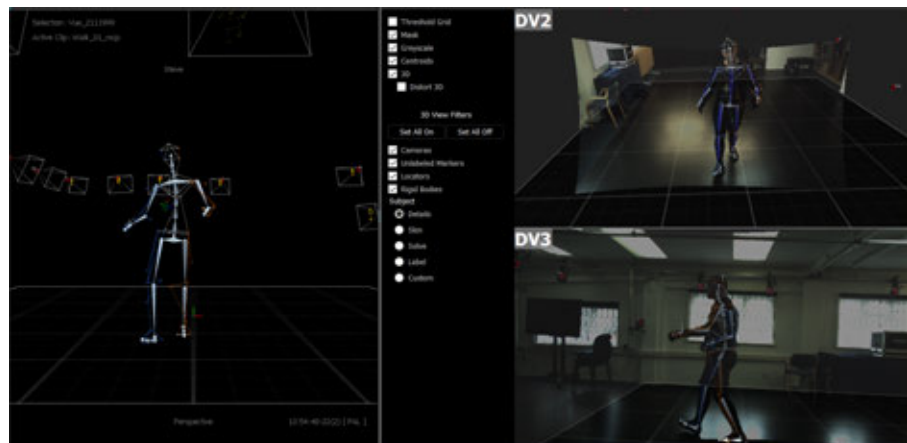


6. Select the 3D check box.

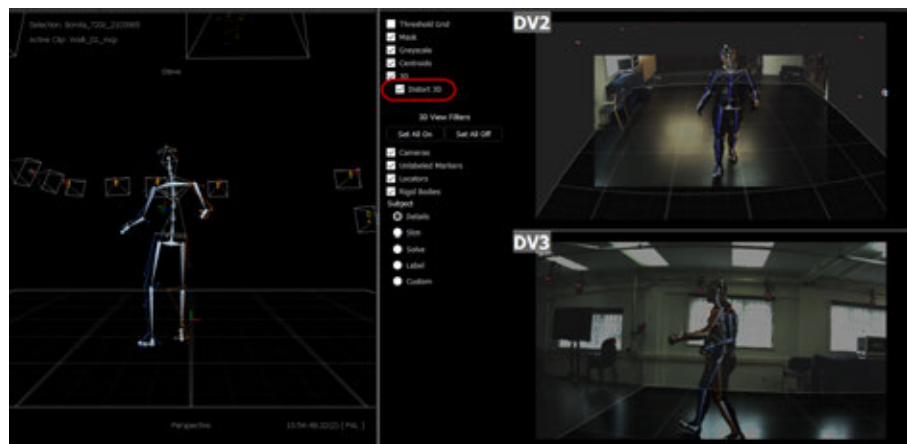


Check data quality

- The video for each Vicon video camera is displayed in a 3D overlay. Video is in black and white or color, depending on the video camera used.



- To see the image plane of the camera corrected for lens distortion, select Distort 3D.



The 3D overlay should line up with the subject in the **Cameras** view and the grid should line up with the floor.

You can zoom and pan the video using normal **Cameras** view controls.

You can select or clear the **View Filters** to control which 3D elements are displayed.

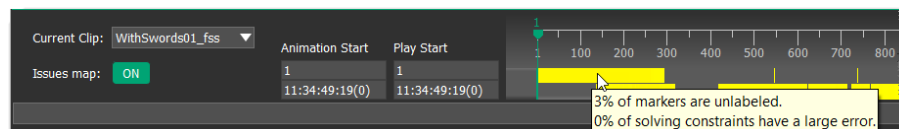
Check data quality

Get an overview with the time bar Issues map

To enable you to identify frames with issues, between the play range (green vertical) bars on the time bar, two horizontal colored bars are displayed. For each frame:

- The top bar indicates the percentage of markers that are labeled.
- As the top bar percentage may include markers that are incorrectly labeled, to help you identify issues further, the lower bar indicates the percentage of markers that have a high solving constraint error (that is, the number of markers whose solving constraint error is considered too large). This can indicate issues like mislabels, swaps, or a poor solve due to an incorrect fill, over filtering, etc.

For both bars, the color varies from yellow to red, depending on the number of markers with issues at each frame. In each bar, the longer the yellow part exists, the longer the issue exists, whereas the more red it turns, the more markers have issues. To show more information about the errors found at a particular frame, hover the mouse pointer over the relevant frame.



i Note

The issues map is all red if there is no labeled data in the current scene.

Check data quality

You can use the mouse to work with the time bar as follows:

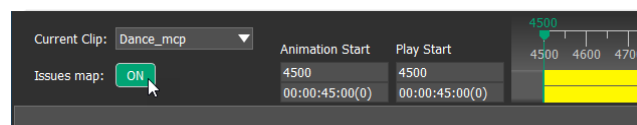
To	Do this
Show a tooltip that explains the issues that are present at this frame	Hover the mouse pointer over the frame.
Set the current time	Click on the time bar or drag the current time indicator.
Set the current time (ie select a frame), highlight the markers that are missing labels or have high constraint errors, and snap the camera to them	Using the tooltip as a guide to where to click on the time bar, double-click on it.
Select a time range	ALT+drag. See also Work with time ranges (page 173).

After you have gained an overview of your data with the time bar, you can use the **Data Health** view, the **Graph** view and/or the **Marker Editing** and **Labeling** panels to further identify and correct any issues.

To enhance system performance when working on a scene that contains very large amounts of data, you may want to turn off the **Issues map**.

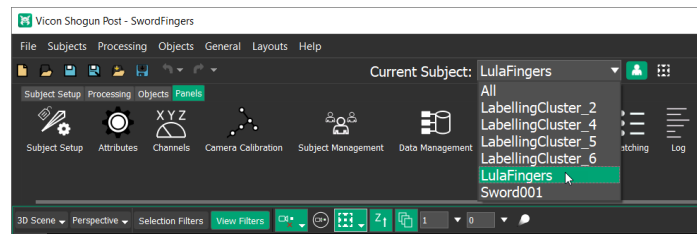
To turn the issues map on and off:


Click the **Issues map** button to the left of the time bar.



To set the issues map to show all issues or only those for a specific subject:

From the **Current Subject** list, select the required option.



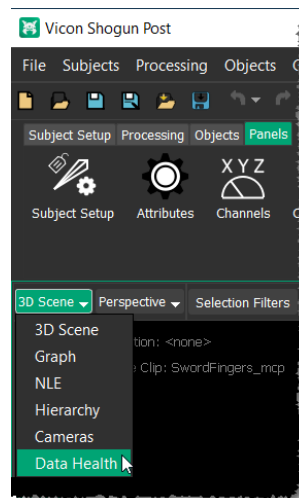
Note that you can snap the 3D view to the selected subject by clicking the **Snap 3D view** button  to the right of the **Current Subject** list.

Check data quality

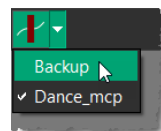
Find issues using the Data Health view

The Data Health view enables you to view detailed information about the labeling and gaps in the markers in the current scene.

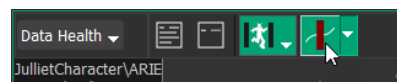
To open a Data Health view, in any view pane, click the View type button and then select Data Health.



By default, if a Backup clip exists, it is displayed, but if required, you can select a different clip by clicking the arrow on the Display Gaps button. (Clips contain keys for objects in your scene. The clip stores keys only; not markers, bones, or any other objects.)

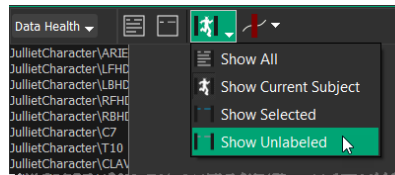


To display the time ranges for the gaps in the markers on the selected clip as gray rectangles, ensure the Display Gaps button is selected.

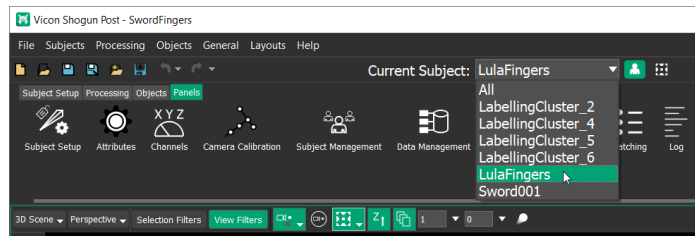


Check data quality

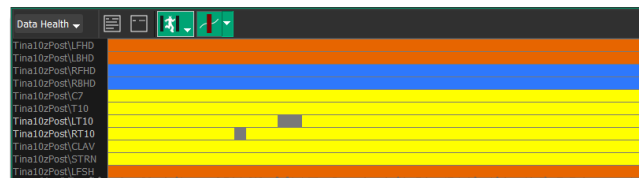
To view unlabeled markers, from the Show current subjects' markers list, select Show Unlabeled.



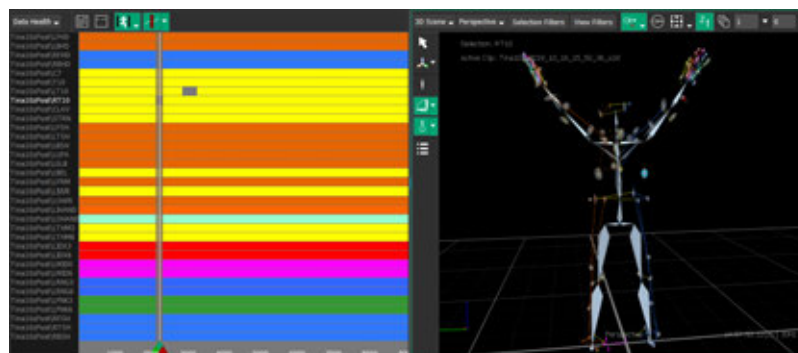
To view the labeling for a different subject, from the Current Subject list at the top of the Shogun Post window, select the required name.



Use the marker list on the left of the Data Health view to find the required marker, then follow line along to see the gray rectangles that indicate gaps.





To select the range of a gap, in the Data Health view, double-click the relevant gray rectangle. The following image shows a Data Health view and 3D Scene view of a gap selected for a marker.



Check data quality



Note

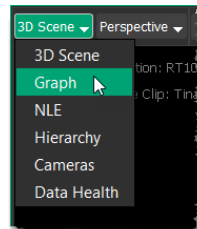
The **Show all markers** button  shows every marker in your scene. Select this option only if you need to see all markers because if, for example, someone is standing to one side but wearing a full marker set, you'll see all their markers listed, as well as the markers for the rest of the volume. Normally, it is more useful to have the **Show current subject's markers** button  selected.

Check data quality




Find issues using the Graph view

In the **Graph** view, you can see a graphical representation of the X, Y and Z positions, as well as gaps, for selected marker(s). This is useful during gap-filling, as it gives you another way of checking that the gap-filling looks reasonable for the data.

To open a **Graph** view, in a view pane, click the View type button and then select **Graph**.

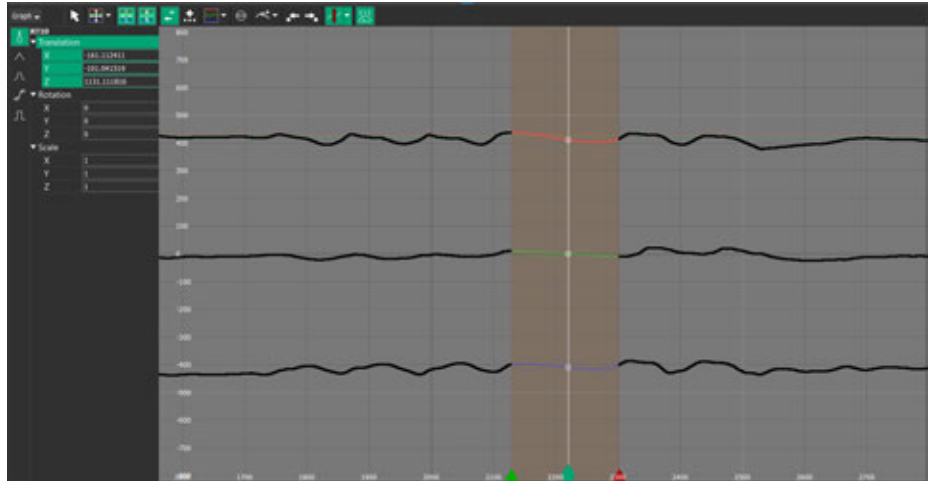


To select and fill gaps in a marker:


1. To keep the **Data Health** view open as well as a **3D Scene** view, split the screen by clicking one of the three-way split buttons at the top right of the window, such as the **Three Views Split Left** button .
2. As in the **Data Health** view, if there are multiple clips in your scene, you can select the required clip by clicking the arrow on the **Display Gaps on Specified Clip** button . To display X, Y and Z values of the selected marker at the current position of the time indicator in the graph, click the **Show Display Channels** button .
3. In the **3D Scene** view, select the marker. In the **Data Health** view, double-click a gap to select its range.

Check data quality

The Graph view now displays all the keys for the selected marker.



As in the **Data Health** view, any gaps are clearly visible.

4. Zoom in by right-click and dragging for a clearer view or by using one of the options under the Zoom button .
5. You can now use the **Labeling** panel or one of the options from the extended context menu (press CTRL+ALT and right-click in the **Graph** view pane) as required.

For further tips on using the Graph view to identify and fix data issues, see [Fix common labeling issues \(page 184\)](#).

Check data quality

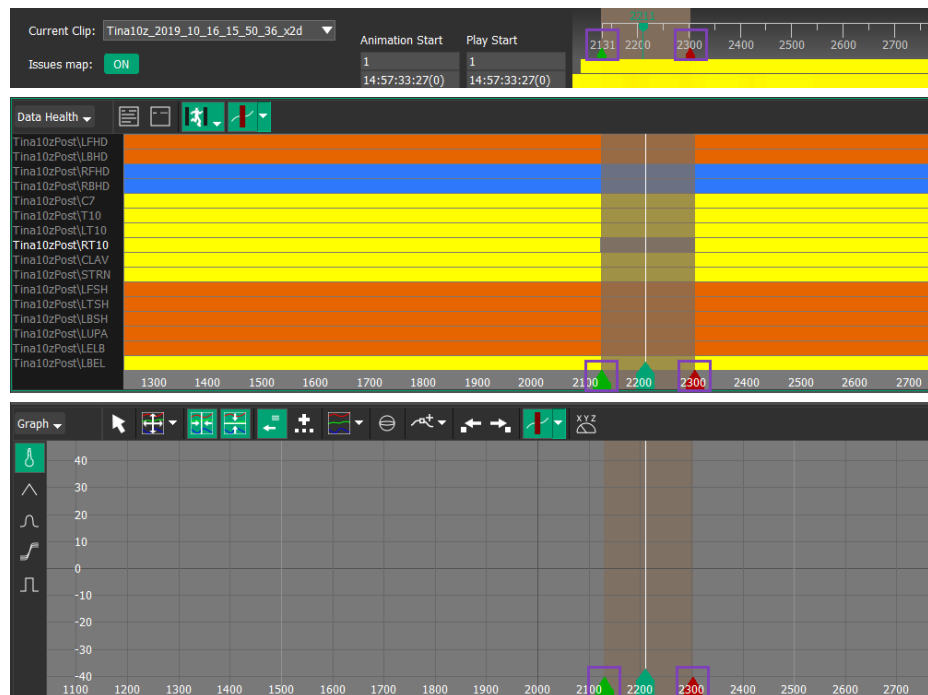
Work with time ranges

While identifying and fixing issues in your captured data, you will often need to select a particular time range on which to work.

To select and clear time ranges:

1. On the main time bar, and in the Data Health and Graph views, select a range (ALT+drag).

Green and red triangles that indicate the start and end of a selected range are displayed.



2. To adjust the start or end of the time range, on the time bar, or in the Data Health view or Graph, hover the mouse pointer over the required arrow and drag it.

Check data quality

✔ Tip
You can also update the range handles using hot keys:
 , sets the start handle
 . sets the end handle
To change these hot keys, on the **General** menu, click **Preferences**
and then click the **Hot Keys** tab.

3. To clear a selected range, ALT+double-click within the range.

Clean up data

Clean up data

If your visual assessment and Vicon Shogun Post's diagnostic tools have revealed issues with your recorded data (see [Check data quality \(page 153\)](#)), you can use its cleanup tools to correct mislabels and fill any gaps.

**Important**

Before filling gaps, you must find and fix any labeling swaps or errors in your data. Gap-filling in Shogun relies on the data before and after the gaps to predict marker location, so any labeling errors will cause gap-filling to fail.

The following topics provide an introduction to fixing data issues:

- [Find and fix bad data \(page 176\)](#)
- [Find and fix noise \(page 177\)](#)
- [Use the Labeling panel \(page 180\)](#)
- [Fix common labeling issues \(page 184\)](#)
- [Processing during cleanup \(page 200\)](#)

See also the related Vicon videos: [5 - Shogun Post – Labeling Data](#)²⁴ and [6 - Shogun Post - Marker Editing](#)²⁵.

Note that each time you finish cleaning up a range, you must check its solve (see [Solve during cleanup \(page 200\)](#)).

²⁴ <https://vimeo.com/218945101>

²⁵ <https://vimeo.com/218945104>

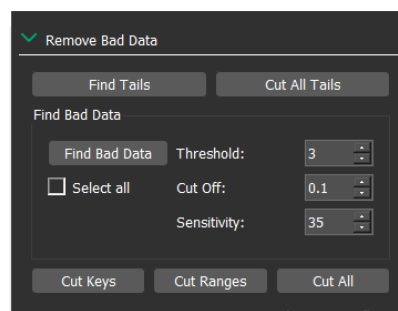
Clean up data

Find and fix bad data

To help you identify and fix bad data, you can use the **Marker Editing** panel.

To find and remove bad data:

1. To open the **Marker Editing** panel, in the **Processing** menu, click **Marker Editing** (or click **Marker Editing** on the **Processing** tab of the ribbon).
2. In the **Remove Bad Data** section, go to the **Find Bad Data** button and notice the options:
 - **Threshold Allowable deviation**
 - **Cut-Off Data filter.** Decreasing this value filters the data more heavily.
 - **Sensitivity Amplifies the effect of the Cut-Off filter.**

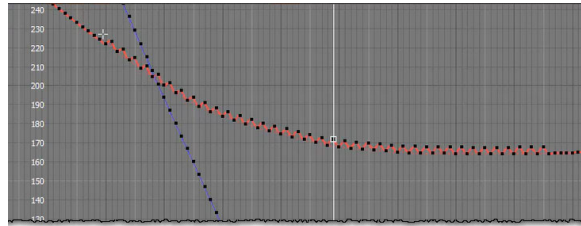


3. Click **Find Bad Data**.
4. Experiment with these values to find out what works best for your data.
5. When you have identified the bad data, remove it by clicking the appropriate **Cut** button, and apply a fill (see [Gap-filling options \(page 196\)](#)).

Clean up data

Find and fix noise

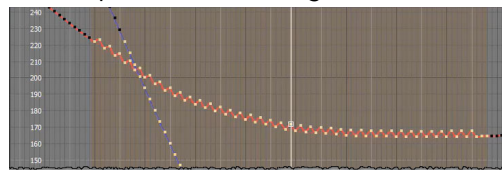
Noise can be easily identified in a Graph view:



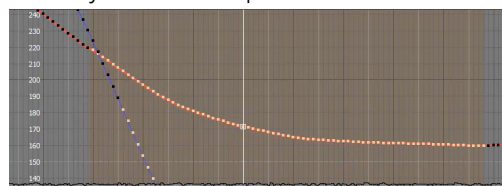
It also produces flickering as you play through a take in the 3D Scene view. You can fix it with the filtering options in the Marker Editing panel.

To fix noisy data:

1. In a Graph view, ALT+drag to select it.



2. At the bottom of the Marker Editing panel, expand the Filter section, and select whether filtering applies to Ranges, as above, or to Selected Keys.
3. If you're not sure how much filtering to apply to your data, keep the default settings (Cut Off: 0.3 and Threshold: 15) and click Apply. You can reapply this as many times as required.



4. In the Graph view and 3D Scene view, check that the trajectory is now smooth over the selected range.



Tip

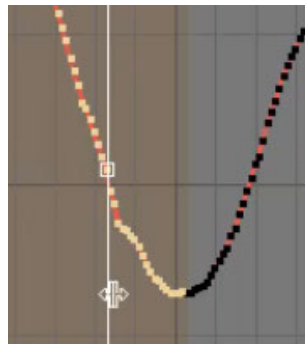
To display a tooltip for any of the controls, hover the mouse pointer over the relevant control.

Clean up data

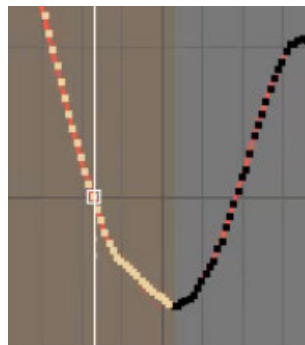
Ensure smooth start and end to filtered trajectories


When you apply filtering, the **Smooth In/Out** option in the **Marker Editing** panel provides smooth blending at the start and end of the filtered section of a trajectory curve.

The following example shows a Graph view of a trajectory curve that requires smoothing.



With **Smooth In/Out** cleared, when filtering is applied, the curve is made smoother, but the start and end does not take into account what is either side of the smoothed section, resulting in a straight line, with an unwanted angle at the end.



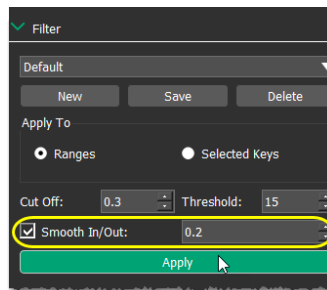
 For details, see the following steps or watch [Vicon Shogun 1.3 Post Tutorial - Filter in/out Smoothing²⁶](https://youtu.be/0csCqSmKe9E) on YouTube.

²⁶ <https://youtu.be/0csCqSmKe9E>

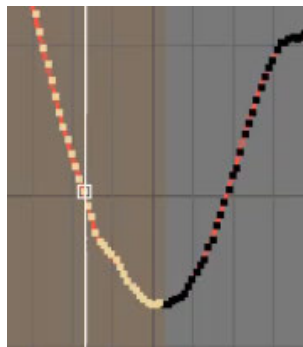
Clean up data

To give a smoother start and end to the filtered section of a trajectory:

1. In the **Marker Editing** panel, expand the **Filter** section and select **Smooth In/Out**.
2. If you want to change how much of the trajectory is affected on either side of the gap, edit the value of the adjacent field. The default is 0.2 (20%).
Smoothing works by blending between the original and filtered result by progressively more or less, across the smoothing range.



The filtered section is smoothed at the start and end.



Clean up data

Use the Labeling panel

You can fix labeling issues using the tools in the **Labeling** panel. The following steps introduce the main components of the labeling panel. To go straight to examples of how to use it to fix labeling issues, see [Fix common labeling issues \(page 184\)](#).

To use the **Labeling** panel:

1. On the **Processing** tab on ribbon, click **Labeling**.
2. In the toolbar at the top of the Shogun Post window, ensure that the required subject is selected in the **Current Subject** list.

**Tip**

By default, the selection in the **Current Subject** list at the top (middle) of the Shogun Post window determines which subject to label.

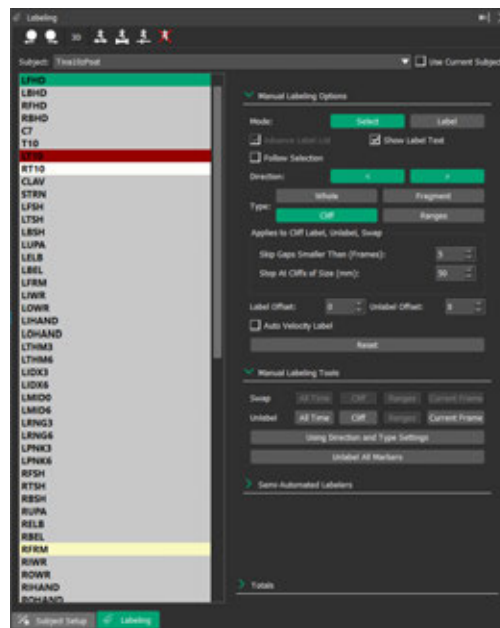
If **All** is selected in the **Current Subject** list, the labeler uses the last subject it was set to.

If you want to select a subject different from that specified in the **Current Subject** list, in the **Labeling** panel, clear the **Use Current Subject** box and select the required subject from the **Subject** list at the left of the check box.

Clean up data

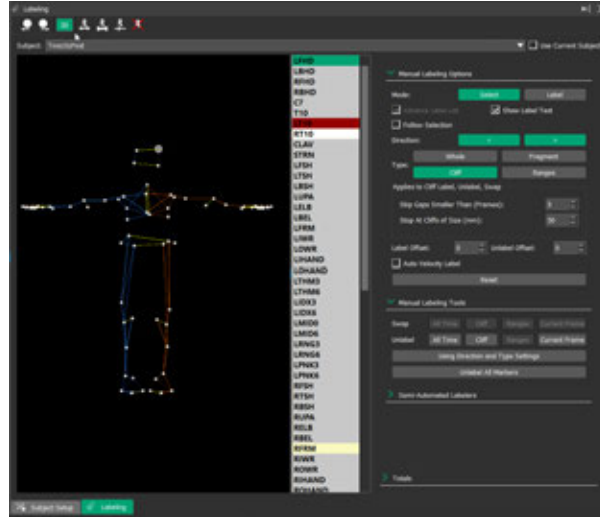
On the left of the Labeling panel, a list of labels for the selected subject is displayed. The color variations indicate marker issues:

- Yellow: Mislabeled or missing labels (the depth of the color indicates the severity of the issue, eg, more or fewer gaps)
- Red: Labels for this marker are missing from the current frame



3. To display a 3D representation of your labels for the current subject, click the 3D button at the top of the Labeling panel. The 3D view helps you to quickly identify where the markers should be. You can drag and drop labels from the 3D Labeling view to the 3D Scene view pane (and vice versa).



Clean up data



You can use the usual mouse actions (click and drag, right-click and drag, left- and right-click and drag) in the 3D view, in the same way as in a 3D Scene view.

4. At the top of the Labeling panel, in the Manual Labeling Options section, select the Mode option (Select or Label), which affects the way in which you select and label markers.
 - **Select** Click a marker on your subject in a 3D Scene view and then click a label name in the list in the Labeling panel.
 - **Label** Click name of the label in the marker list and then click the required marker on the subject in the 3D Scene view.

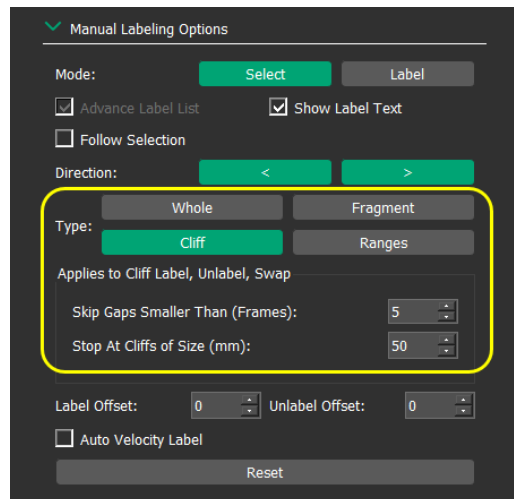
✓ **Tip**
To quickly switch between labeling and select modes when labeling a subject, you can use the default hot key (L) that duplicates the functionality of the Label and Select buttons at the top of the Labeling panel.

5. In the Direction line, choose to label forward  (through time) or backward .

You can also select both options (ie, label both forward and backward), but to help you avoid confusion, at least initially, choose either backward or forward and use only that option.

Clean up data

6. From the **Type** options, select the way in which labeling will be applied:



- **Whole** Labels entire trajectory.
- **Fragment** Labels the trajectory that intercepts the current frame.
- **Cliff** Labels the current frame and continues until a specified value is encountered, which stops the labeling (see the text below in the **Labeling** panel, for example, the default is to skip gaps smaller than 5 frames and stop labeling at cliffs that are larger than 50 mm).
- **Ranges** Lets you select an area on your graph or timeline and label only the selected time range.

In the **Manual Labeling Tools** section in the middle of the **Labeling** panel, you can correct swaps, unlabel information, and unlabel markers.

In the **Semi-Automated Labelers** section, you can access the **Velocity Labeler**, which is normally used after automated labeling, on a partially labeled take. You can use it to correct labeling where the path of a single marker consists of multiple trajectories that are consecutive in time with a small gap in between where the marker is unlabeled over part of its trajectory. The **Velocity Label** option is useful when a marker has been labeled for a range of time, and then becomes unlabeled, yet going forward or backward in time there are multiple trajectories that do not have a large gap between them and are all the same marker. It is best suited for cases when unlabeled trajectories are not many frames away from the labeled marker and the velocity of the marker around the end of the labeled marker and the start of the unlabeled trajectory is fairly constant.

Clean up data

Fix common labeling issues

The following basic procedures are just a few of the ways in which you can use Shogun Post to clean up data.

- [Identify issues \(page 185\)](#)
- [Correct a swap \(page 186\)](#)
- [Label an unlabeled marker \(page 188\)](#)
- [View and select gaps \(page 189\)](#)
- [Auto-fill with intelligent rigid fill \(page 190\)](#)
- [Manually fill gaps \(page 193\)](#)

See also:

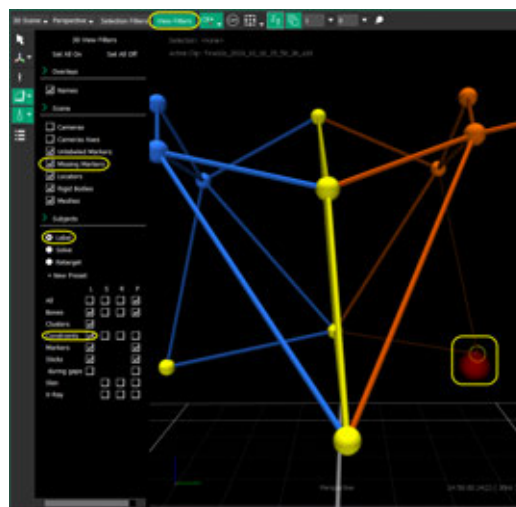
 [Vicon Shogun 1.3 Post Tutorial - Gap List & Auto Rigid Fill²⁷](#) on YouTube.

²⁷ <https://youtu.be/U3jmKTqykOE>

Clean up data

Identify issues

1. To help you identify issues, in the 3D Scene view, click **View Filters**, and ensure that in the **Scene** section, **Missing Markers** is selected. Also ensure that in the **Subjects** section, **Label** is selected and that in the L(abeling) column of the views matrix, **Constraints** is selected.




2. In 3D Scene view, scrub through the whole take (drag the current time indicator along the timeline, or for finer control, press the A or S key), noting times when markers are likely to be occluded (sitting, crouching, subjects interacting, etc).
3. In the marker list in the **Labeling** panel, note any missing (red) markers and watch for 'popping' or moving in the 3D Scene view. Look for any swapped markers (for an example, see the Vicon video [5 - Shogun Post – Labeling Data](#)²⁸, which shows an example of a swap of knee and heel markers).

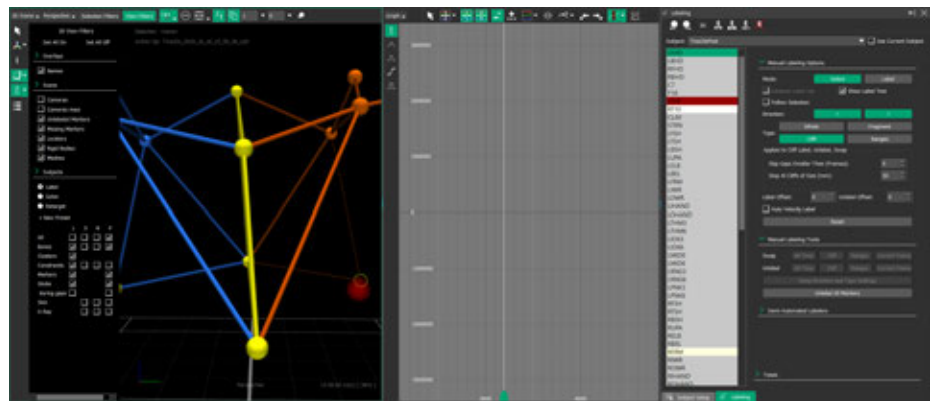
Missing markers are clearly visible, highlighted in red. However, after you've identified the erroneous markers, it may help with labeling to clear **Missing Markers** and **Labeling Constraints**.

²⁸ <https://vimeo.com/218945101>

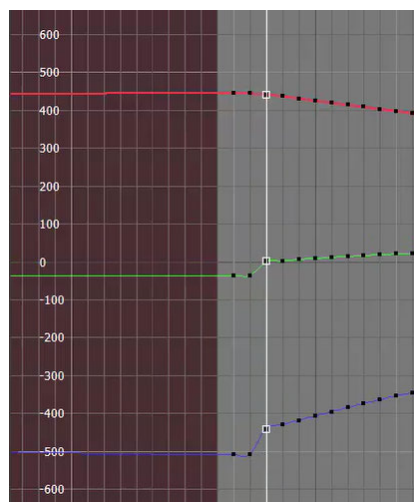
Clean up data

Correct a swap

1. Ensure the Labeling panel is displayed.
2. Split the 3D Scene view (at the top right of the Shogun Post window, click the vertical split button ) and in one of the panes, change to a Graph view, so that you can now see a 3D Scene view, a Graph view and the Labeling panel.

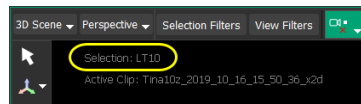


3. In the Labeling panel, ensure Select mode, Forward direction (>), and Cliff are selected.
4. In the 3D Scene view, select a marker that is incorrectly labeled and in the Graph view, zoom in (right-click and drag) and go to the start of the where the swap happens (this should be identifiable on the graph by a sharp change).



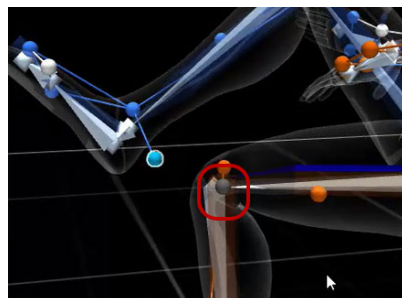
Clean up data

5. From the position of the marker in the 3D Scene view, decide which is the correct marker and click it in the 3D view.
In the marker list, its name is displayed in heavier text, and at the top left of the 3D Scene view, the Selection text displays the name of the selected marker.



6. Click the wrongly labeled marker in the 3D Scene view and then click the correct marker name in the Labeling panel list.
The marker is now correctly labeled. To check, scrub back and forward in the 3D Scene view and check that the marker is now behaving correctly.

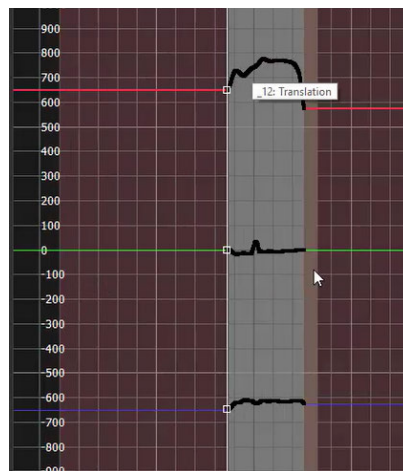
However, you now have a previously incorrectly labeled marker that is unlabeled from this point forward.



Clean up data

Label an unlabeled marker

1. In the **3D Scene** view, click on the unlabeled marker to select it. Scrub back and forward to identify where it is correctly labeled. This is the point at which it is correctly colored in the **3D Scene** view and the **Labeling** panel marker list. You can also observe this on the **Graph**.



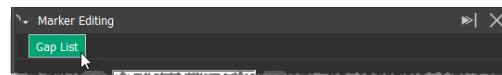
2. To label a marker using the tools in the **Labeling** panel, do one of the following, depending on your chosen **Mode**:
 - If you prefer to label using **Label** mode:
 - a. In the **Manual Labeling Options** section, in the **Mode** line, click **Label**.
 - b. In the marker list in the **Labeling** panel, click the name of the marker and then in the **3D Scene** view, click the marker that is currently unlabeled.
 - Or, if you prefer to label by dragging, using **Select** mode:
 - a. In the **Manual Labeling Options** section, in the **Mode** line, ensure **Select** mode is selected.
 - b. In the **Labeling** panel, click to select the required marker in the **3D** view.
 - c. **SHIFT+CTRL** then click+drag from the selected marker in the **Labeling** panel to the unlabeled marker in the **3D Scene** view.
3. As before, to check the labeling, scrub back and forward in the **3D Scene** view and check that the marker is now behaving correctly.

After you have corrected any swaps, you may want to use Shogun Post's diagnostic tools to help to identify gaps (see [Check data quality \(page 153\)](#)).

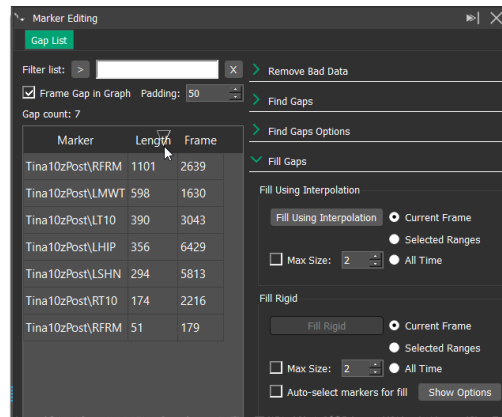
Clean up data

View and select gaps

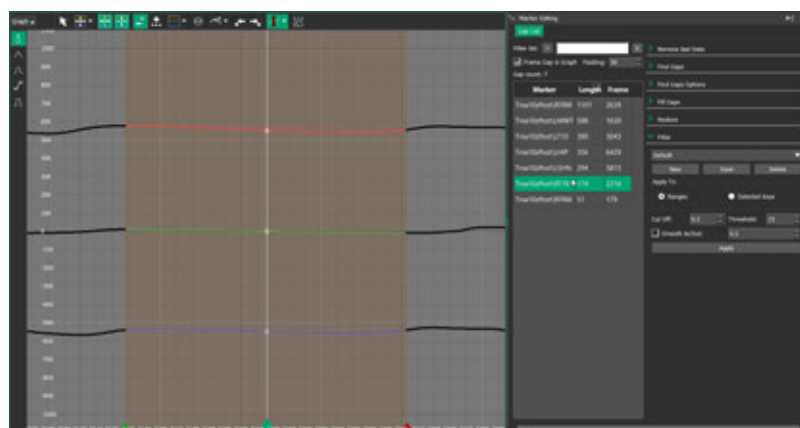
You can view all the gaps in your scene in the **Marker Editing** panel, in the **Fill Gaps** section, by looking at the **Gap List**. (If you can't see the list, at the top of the **Marker Editing** panel, click the **Gap List** button.)



To make it easy to find the longest gaps, click the **Length** column heading to rearrange the list, with the longest gap at the top.



When you select a gap in the list, it is automatically displayed in the **Graph** view, enabling you to edit it.



Clean up data

You can then decide the best approach for filling the gaps:

- As a first step, try automatically filling as many gaps as possible (see [Auto-fill with intelligent rigid fill \(page 190\)](#)).
- If your scene still contains gaps after using the automatic fill, or if auto-fill is unsuitable, try manually filling the gaps (see [Manually fill gaps \(page 193\)](#)).



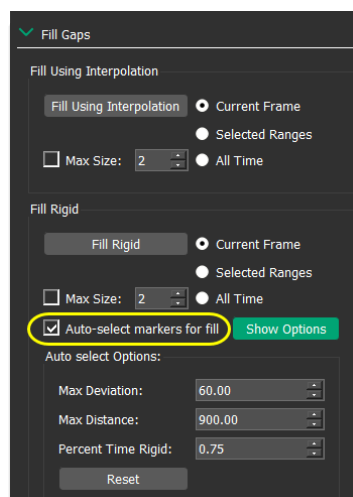
Tip

To undo unwanted gap-filling, click Undo on the quick access toolbar



Auto-fill with intelligent rigid fill

Shogun Post enables you to automatically fill gaps using a rigid fill operation. This looks at all the markers in your scene and then compares them against the marker you are trying to fill. It then uses a combination of similarly moving markers to fill the gap. Finally, it checks the fill to make sure it looks correct and if not, it chooses another set of markers.



This process is also available via scripting, using the `selectMarkersForRigidFill` command to select the markers and the `autoFillGaps` command to fill them. For information on these commands, see *HSL scripting with Vicon Shogun*.

Clean up data

To auto-fill a selected marker:

The following procedure for rigid gap-filling is semi-automated, in that you choose a marker for the fill:

1. In the **Marker Editing** panel, expand the **Fill Gaps** section and in the **Fill Rigid** area, select the **Auto-select markers for fill** check box.

To change the default options for auto-selection, click the **Show Options** button next to the check box. The options are:

- **Max Deviation:** Specifies in mm how rigid the set of markers used to fill must be, as the maximum deviation in distance between all pairs in the set. For example, a value of 60 enables the markers to flex in rigidity by 6 cm.
- **Max Distance:** Specifies in mm how far away the candidate can be from the selected marker. The default of 900 is just under 3 feet (1 m), because a greater distance is likely to be another subject or body part, which is unlikely to move rigidly during the gap.
- **Percent Time Rigid:** Specifies the percentage of time over the adjacent fragment ranges that the selected marker must be rigid with the chosen set. The default of 0.75 means 75% of the time.

2. Select a marker with a gap.
3. Ensure the current time is in the gap.
4. Click **Fill Rigid**.
Gaps are filled using the intelligent rigid fill.

Clean up data

To auto-fill selected markers or all markers:

In addition to the semi-automated procedure described above, you can also automatically fill all gaps on either all markers, or only those currently selected.

To do this:

1. Depending on which markers you want to fill:
 - **Only selected markers.** Ensure you have selected the required markers.
 - **All markers.** Ensure no markers are selected.
2. In the **Marker Editing** panel, expand the **Fill Gaps** section and in the **Fill Rigid** area, select the **Current Frame**, **Selected Ranges** or **All Time** option.
3. Select **Auto-select markers for fill** and ensure the options are as required (see above).
4. Click **Fill Rigid**.
 All gaps on the selected markers, or on all markers if no markers are selected, are filled over the play range, or selected ranges.
 Note that in the case of all markers, only labeled markers are filled, though unlabeled markers can be auto-selected for filling the labeled marker.

Note

After running automated gap-filling, if Shogun did not find a set of rigid markers based on the settings, you may find that not all gaps are filled. You can either fill the remaining gaps manually, or you can try changing the settings, specifically by increasing **Max Deviation** from the default.

You can run automated gap-filling multiple times to achieve the required results, in particular when:

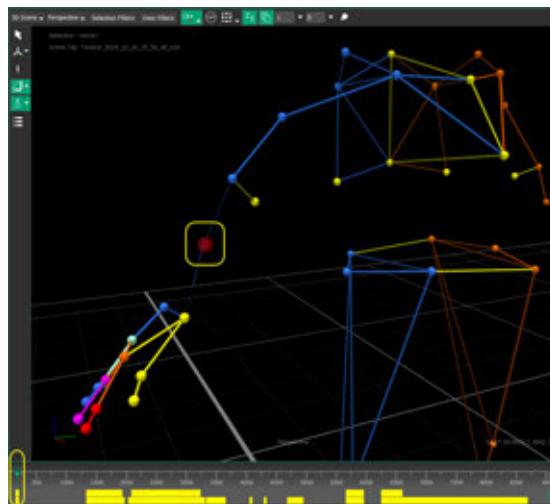
- After first run, it either made an unwanted fill or wasn't able to fill a gap due to a mislabel. Fix the mislabel and then run it again to fill the remaining gaps.
- After first run, it either made an unwanted fill or wasn't able to fill a gap due to the gap being too complex. Fill the gap manually, then run automated gap-filling again to fill any remaining gaps. These can now be filled due to more data being available.
- After first run, some gaps remain. Loosen the rigidity settings (see Note above) and run it again.


Clean up data

Manually fill gaps

You fill gaps using the **Marker Editing** panel, normally in conjunction with the **Data Health** view and/or a **Graph** view. The **Marker Editing** panel contains all the tools necessary to fill gaps, alter trajectory keys and filter your data.

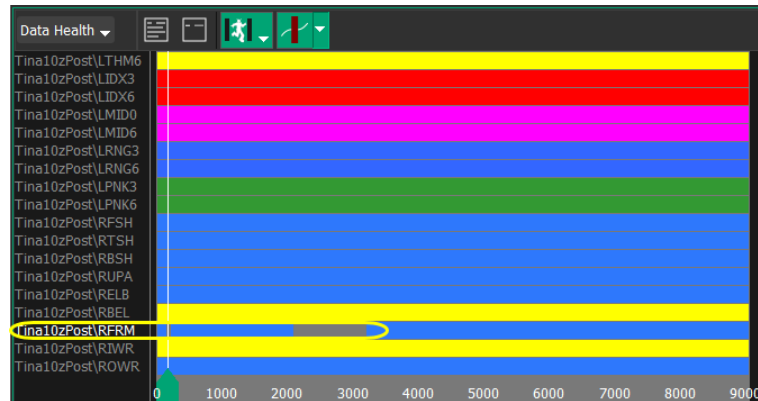
For example, you might first notice a gap from the display on the time bar **Issues** map, then note which marker is affected in the **3D Scene** view:



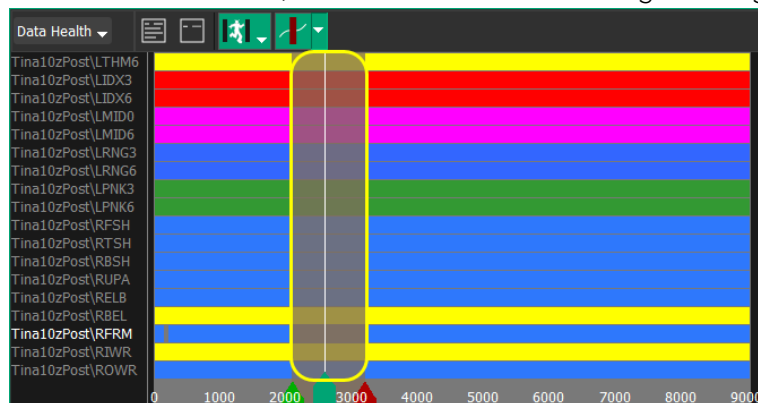
1. To quickly gap-fill the selected marker, on the time bar double-click to move the current time indicator to the relevant frame.
The affected marker is automatically highlighted in the **3D Scene** view (you can right-click and drag to zoom in further to check the marker).
2. To open a **Data Health** view and a **Graph** view, as well as a **3D Scene** view, split the screen by clicking the **Three Views Split Left** button  at the top of the Shogun Post window and change the views in the new panes.
3. If the **Marker Editing** panel is not already open, on the **Processing** tab on the ribbon, click **Marker Editing**.

Clean up data

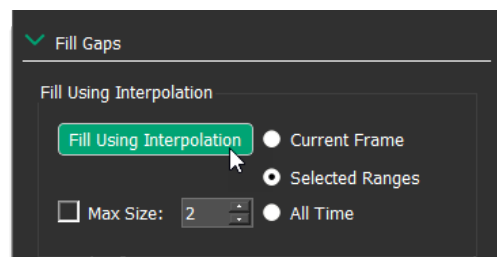
- In the Data Health view, find the relevant marker's line, which shows a gray rectangle that represents the gap.



- In the Data Health view, double-click to select the range of the gap.



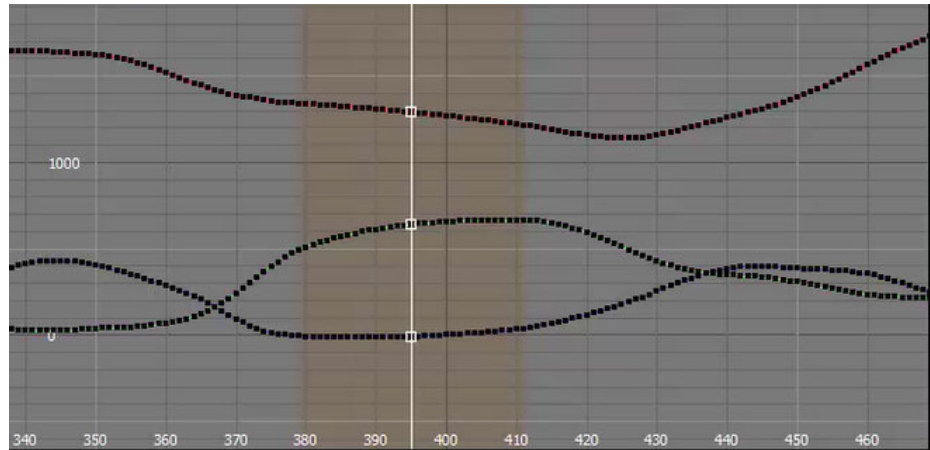
- In the Marker Editing panel, expand the Fill Gaps section. In the Fill Using Interpolation area, select Selected Ranges (to fill only the current selection), and then click Fill Using Interpolation.




This looks at the keys on either side of the gap and fills it by interpolating between them. It works well for small gaps.

Clean up data

7. In the 3D Scene view and Graph view, check that your fill has given the required result.



8. If the fill does not give an appropriate result, you can click Undo on the quick access toolbar , and try other gap-filling options in the Marker Editing panel (see [Options for gap filling \(page 196\)](#)).

Clean up data

Options for manual gap-filling

The appropriate option to use depends on the type of gap that you want to fill.

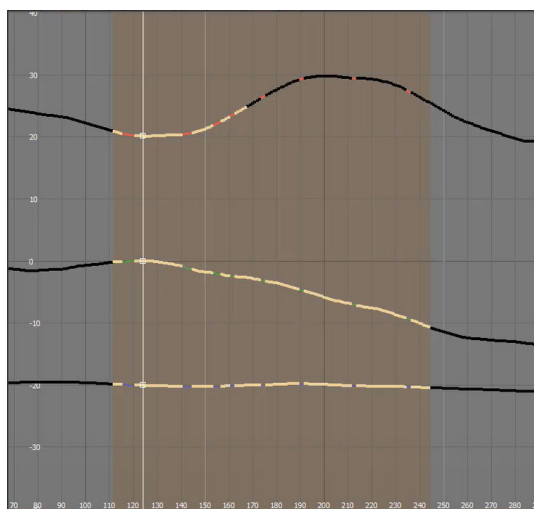
Short gaps

1. Manually select a short gap by double-clicking in a **Graph** view or **Data Health** view, and in the **Marker Editing** panel, expand the **Fill Gaps** section and click **Fill Using Interpolation**.
This looks at data before and after the gap and uses a spline fill to interpolate between them.
2. Check that the result looks reasonable in a **3D Scene** view and **Graph** view.

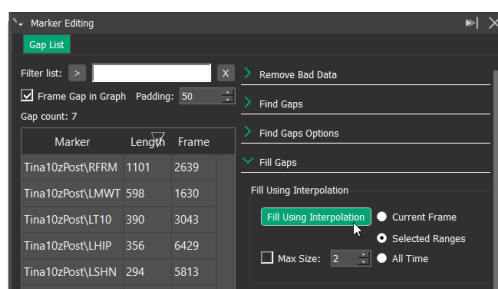
Clean up data

Sequence of short gaps

1. For a sequence of small gaps with a smooth line running through the gap in the Graph view, ALT+drag to select the affected data.



2. In the Fill Using Interpolation area, select Selected Ranges, and then click Fill Using Interpolation.

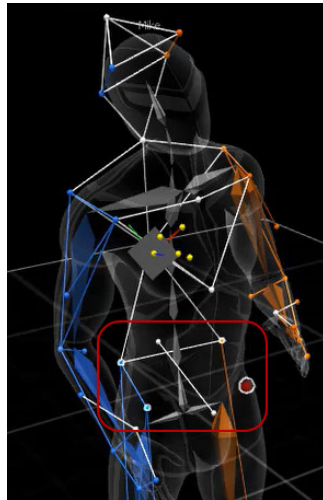


Clean up data

Non-linear motion

For non-linear motion, for example, where rotational movement is involved, as interpolation does not account for this kind of motion, a different approach is needed. If a missing marker is part of set of markers that are rigid (ie, remain in the same relation to each other, for example, a pelvis), you can use three or more markers in the rigid object (three in addition to the marker that has the gap is recommended) to help fill in the data for the missing marker.

1. To select the range of the gap, double-click in a **Graph** view or **Data Health** view, then select (CTRL+click) the three other markers in the rigid object.



2. In the **Marker Editing** panel, expand the **Fill Gaps** section.
3. In the **Fill Rigid** area, select **Selected Ranges** and click **Fill Rigid**.
The pattern of the present markers is copied onto the missing marker.
4. As usual, check in the **Graph** view and in a **3D Scene** view that the fill looks sensible.

Other rigid objects you can use in default marker set include hands, forearm, upper arm, shoulders, thorax, and head.

Clean up data

Non-linear motion where rigid fill impossible

In cases where the motion is non-linear, but a rigid fill is not possible due to all the related markers being absent, you can use the **Fill Using Constraints** option. This uses the labeling or solving skeleton to produce the fill. It requires a skeleton be present, the skeleton to be constrained by markers, and enough markers to have data that the solve is fairly good. The marker being filled must be constrained to the skeleton because it is the constraint offset that is used to determine where the marker should be during the fill.

Before using this type of fill, check that the bones and missing markers (by default displayed in red in the **3D Scene** view), are in sensible locations.

Clean up data

Processing during cleanup

Note that the previous steps for fixing data issues assume that your existing `.mcp` data is largely of acceptable quality. However, in some circumstances (for example when you are trying to produce better quality data), rather than persisting in trying to fix a problematic `.mcp` file, you may need to clear the scene and start from the `.x2d` file, or unlabel all the data first. In this case, do not just open the **Processing** panel and click **Reconstruct** or **Label** or run other **Combined Processing** operations as this will not fix problems with the underlying data.

Clear existing data

To remove all unlabeled data and clear existing labels and solves, at the top of the **Processing** panel, select the **Reset Scene** check box. You can then run **Reconstruct**, etc. Note that you can't undo the reset.

To remove existing labels from the current file, on the **Labeling** tab of the **Processing** panel, select **Clear Existing Labels** and then run **Labeling** as required.

To remove occlusion fixing from your data, in the **Marker Editing** panel, expand the **Restore** section and select the required option.

Solve during cleanup

During the cleanup operation, each time you finish cleaning up a range, check its solve. To do this:

1. Ensure the range you cleaned up is selected.
2. On the **Processing** tab on the ribbon, click the arrow on the **Solve Solving** button.
3. Click **Solve Solving Ranges**.
The selected range is solved, enabling you to quickly check that your cleanup has been successful, without having to solve the whole take.
4. Proceed to clean up the next range that contains mislabels, gaps or noisy markers, etc.
After you have completed all the cleanup required, finish by solving the entire take. For more information see [Solve the data \(page 201\)](#).

Solve the data

Solve the data

When you have finished any necessary cleanup of your data, run a final solve to produce the finished file ready for export.

In addition to the following information, see also the Vicon video [3 - Shogun Post - Processing and Solving](#)²⁹, which covers using the **Processing** panel, editing a solving skeleton, and solving.

Even if you only had to clean up a single frame or a small range of frames, always run a final solve on the entire play range. You can run solves on smaller ranges so that you can review the results of your cleanup while you are working (depending on your requirements, you would probably use the **Solve Labeling** and/or **Solve Solving** options on the ribbon or in the **Processing** panel), but to avoid any jumps at the start and end of the solved range(s), when you have finished editing, you must run a solve of the whole play range.

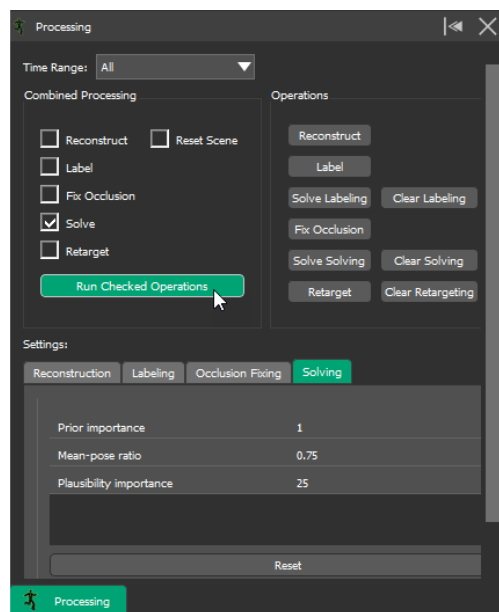
To solve your data:

1. On the **Processing** tab of the ribbon, click **Processing**.
2. At the top of the **Processing** panel, ensure the required options are selected from the **Time Range** list (for example, to affect the whole play range, select **All**, as shown in the following illustration).
3. In the **Processing** panel, ensure the options for **Reconstruct**, **Label**, and **Fix Occlusion** are cleared (for more information, see [About occlusion fixing](#) (page 203)), but **Solve** is selected.

²⁹ <https://vimeo.com/218945089>

Solve the data

4. On the **Solving** tab, ensure the settings are as required.
If you are using any of the high fidelity fingers templates:
 - Ensure that the **Plausibility importance** option is set to a suitable value. The default, 25, is normally a good starting point. Smaller values produce better data fidelity (ie, the markers will better fit their constraints), but the pose likelihood may be weaker. Larger values produce better pose likelihood, but weaker data fidelity.
 - Note that the **Mean pose ratio**, which affects the entire skeleton, has a strong impact on the final hand poses. The default, 0.75, is normally a good starting point, but if you need to adjust it (for example, if there is too much noise), try a lower value.
5. Click **Run Checked Operations**.



Any changes you have made to the labeling skeleton and the solving skeleton are included in this final solve.

6. Review your solved data and perform any further cleanup needed.

Solve the data

About occlusion fixing

i **Note for Blade users:**
Occlusion fixing in Shogun is similar to that available in Blade. However, by default, the *.mcp* files that are produced in Shogun Live are automatically occlusion fixed, so are unlikely to need further occlusion fixing when opened and processed in Shogun Post.

Occlusion fixing uses data from non-occluded markers to supply the missing data for the occluded markers. To give the best results and the smoothest trajectories, occlusion fixing may affect non-occluded markers throughout the take, even if you have selected a range before applying it. If you repeatedly run occlusion fixing in Post, the effect may be cumulative, resulting in greater (possibly unwanted) smoothing.

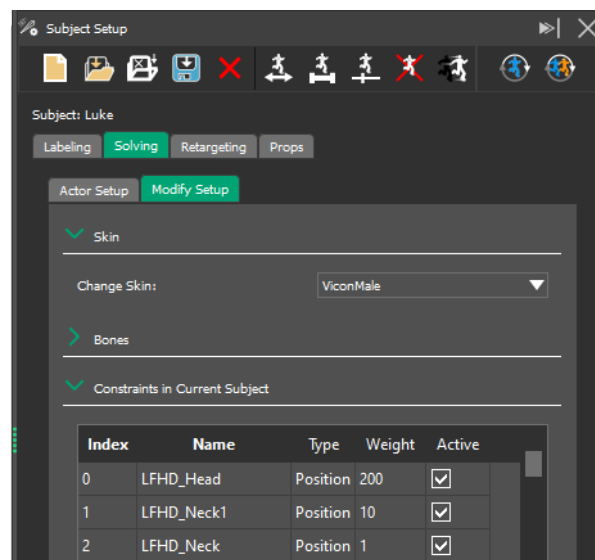
Solve the data


Interactive solving

If you want to perform a simple manipulation of a solving bone, you can save time and a lot of manual tweaking by using the interactive solving feature. This immediately updates the offsets for the constraints that drive the bone that you're adjusting as soon as you release the mouse button.

To manipulate a solving bone:

1. Ensure you have loaded the subject, which must have a solving skeleton.
2. In the Subject Setup panel, click the Solving tab, and on the Modify Setup tab, expand Constraints in Current Subject.



3. In the 3D Scene, select the joint you want to rotate.
4. On the right of the the Subject Setup panel toolbar, click the Enable interactive solving of the solving subject button . At the top of the 3D Scene view, the text Interactive Solving is displayed.
5. Using the manipulator, rotate the subject's joint.
6. When you're happy with the new position of the joint, release the mouse button. The offsets for the constraints which drive the bone are updated.

Solve the data

 **Note**

Interactive solving works best when you want to apply a rotation in a single axis, for example, correcting head aim, hand flatness, etc.

You can follow a similar procedure to manipulate retargeting bones: see [Interactive retargeting](#) (page 225).

For information on the relevant HSL commands, see the following commands in *HSL Scripting with Vicon Shogun*.

- `getInteractiveSolveLabeling`
- `getInteractiveSolveSolving`
- `setInteractiveSolveLabeling`
- `setInteractiveSolveSolving`

Retarget with Shogun Post

Retarget with Shogun Post

Shogun Post's full retargeting pipeline enables you to create and solve motion capture data onto any custom FBX/USD biped.

You can use the resulting VSR file in Shogun Live and stream it to a game engine, or solve and export from Shogun Post for use in a CG app.

You can use either Shogun Post or the Vicon Retarget app for retargeting:

- Use Shogun Post for retargeting instead of Vicon Retarget if you want script the process, need to align the source skeleton to the target skeleton or change the bone lengths of your target skeleton to better match the source.
- Use the Vicon Retarget app if you need Joint Symmetry or Target Symmetry.

The current retargeting implementation is Phase 1 of a longer planned roadmap. Use the retargeting workflow as a first step in the retargeting process, and as a quick and easy way to get your custom characters driven by Vicon mocap.

- [Set up a retarget \(page 207\)](#)
- [Modify a retarget \(page 223\)](#)
- [Interactive retargeting \(page 225\)](#)
- [Export the retarget setup \(page 227\)](#)

See also:

 [Vicon Shogun 1.3 Post Tutorial - Retargeting Setup](#)³⁰

 [Vicon Shogun 1.3 Post Tutorial - Retargeting Test](#)³¹

 [Vicon Shogun 1.3 Post Tutorial - Streaming Retargets into Unreal](#)³²

³⁰ <https://youtu.be/S5otK-hx8QM>

³¹ https://youtu.be/FFYwa2_FSak

³² <https://youtu.be/3vUuTgp0PTE>

Retarget with Shogun Post

Set up a retarget

To set up a retarget in Shogun Post, see the following information.

- [Create an optimal target skeleton \(page 208\)](#)
- [Import the target skeleton into Shogun Post \(page 211\)](#)
- [Prepare the skeleton before posing \(page 213\)](#)
- [Pose the skeleton \(page 215\)](#)
- [Create constraints \(page 216\)](#)
- [Test the retarget setup \(page 222\)](#)

Retargeting terms:

- **Source skeleton:** Solving skeleton
- **Target skeleton:** Retargeting skeleton (game skeleton)
- **Map pose:** The pose that is used for mapping (creating constraints between the source (solving) and target (retargeting) skeletons and setting the offsets). For more information, see *Map pose and best rig practices in Getting more from Vicon Shogun*.
- **Base pose:** The pose of the skeleton when all keys are deleted and the rotation channel for all bones is set to zeros. It's defined by the pre-rotation, which is known as 'joint orient' in Autodesk® Maya®.

Retarget with Shogun Post

Create an optimal target skeleton

The following tips help you to ensure that your FBX, USD or VSR file works well as a target.

- [Use pre-rotation, not keys \(page 208\)](#)
- [Pay attention to degrees of freedom \(DoFs\) \(page 208\)](#)
- [Be aware of dummy bones \(page 209\)](#)
- [Know what's above the root bone \(page 210\)](#)
- [Know how to use scaling \(page 210\)](#)

Use pre-rotation, not keys

It's best to define the base pose of a skeleton using pre-rotation, not keys.

If keys put the skeleton into a T-pose, A-pose, or another suitable pose, and pre-rotations don't exist, you can still use the skeleton, but you'll need to know what the base pose looks like and use the map pose to both retain the pose used for mapping and to get best results. See [About map mode \(page 214\)](#) and, if your skeleton uses keys rather than pre-rotations, see also Map pose and best rig practices in *Getting more from Vicon Shogun*.

Pay attention to degrees of freedom (DoFs)

Most skeletons have Degrees of Freedom (DoFs), and generally, skeletons work best when they have them.

- **FBX files:** After you import an FBX, check that the DoFs are set correctly before setting up retargeting.
- **USD files:** The USD format doesn't currently support DoFs. If you want to use DoFs with a USD skeleton, set them in Post after importing the USD skeleton.

Retarget with Shogun Post

Be aware of dummy bones

End joints that are dummy bones (bones with zero DoFs) are ignored by retargeting in that any keys they may have aren't retained and a map pose isn't stored for them.

- For extremities like the ends of hands, toes, and fingers, this is fine because the end bones must be zero DoF dummy bones with no keys.
- For parts of a skeleton that define things such as face, hair, and clothes, this can be problematic if these bones don't use pre-rotation to define their base pose. If you use keys to define a pose that is required for the skin to look right, note that these keys are not stored in the VSR/map pose because all of these bones are treated as dummy bones. If they aren't dummy bones already, change them to dummy bones because they have no data and setting them to dummy bones enables retargeting to ignore them and therefore to run faster.

To convert unused bones to dummy bones in Shogun Post, either:

- If your bones have pre-rotation values that you want to keep, note their values. In the **Subject Setup** panel, on the **Retargeting** tab, click the **Prep Unused Bones** button. This ensures all unused bones have zero DoFs and moves their rotations from channels to pre-rotations. You can enter the pre-rotation values that you noted to manually reset them.

or

- Manually set the DoFs to off. To do this, in the table on the **Retargeting** tab, select the bones you want to be dummy bones and clear the **Active** check box.

Retarget with Shogun Post

Know what's above the root bone

On import:

Sometimes, skeletons in CG apps like Autodesk® Maya® or Autodesk® MotionBuilder® contain one or many bones, locators, groups, etc, above the root. Generally Vicon Shogun doesn't support this. Aim to have no extra nodes between the Retargeting node and the root bone in Shogun Post. Dummy bones can exist above the root. These must have zero DoFs and the root must have six DoFs. If this isn't already the case on import, in the **Target Root** field, specify the correct root, which switches DoFs.

On export:

In Shogun Post, on the **Retargeting** tab, you can select or clear the **Preserve dummies above root** check box, which controls whether the dummy bones above the root are exported in the VSR.

If any objects above the root have non-zero transforms, they can be successfully imported in FBX format, but you'll probably need to modify the hierarchy in Post to set them aside during setup. If you need them to exist in the exported FBX because it will be merged into the original file, you must restore the hierarchy to its original form after you finish retargeting. You can create export scripts to do this via batching.

Know how to use scaling

Scale (values in the **Scale** channel) is not supported on bones or anything above them.

Retargeting enables you to scale each joint so that it better matches the source skeleton. You can revert this back to the original scale on export, if desired (see [Export FBX \(page 227\)](#)).

Retarget with Shogun Post

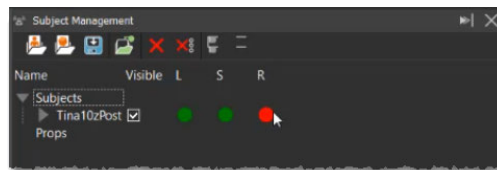
Import the target skeleton into Shogun Post


You can import the target skeleton as an FBX or USD file, or VSR, if a setup already exists. Ideally the imported file will contain just the skeleton and skin and as little else as possible.

To import the target skeleton:

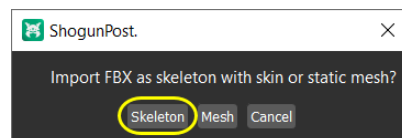
1. In Post, open the relevant .MCP file and ensure that the required solving skeleton is selected in the **Current Subject** field.
2. To check that no target skeleton has been imported, open the **Subject Management** panel.

The Retargeting column displays a red circle, indicating that no retargeting setup is present.



 For more information on the Subject Management panel, watch [Vicon Shogun 1.3 Post Tutorial - Subject Management](https://www.youtube.com/watch?v=QuA8akXSzTw)³³ on YouTube.

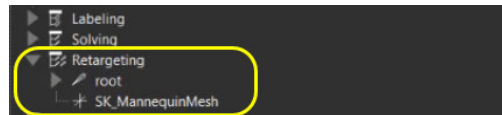
3. Do either of the following:
 - In the **Subject Setup** panel, select the **Retargeting** tab, click the **Load** button and select the required target.
 - Or
 - Drag the target skeleton file into the Shogun Post view pane. When you are prompted, choose **Skeleton**.



³³ <https://youtu.be/QuA8akXSzTw>

Retarget with Shogun Post

The target skeleton is imported into the current subject hierarchy with the topmost bone of the target skeleton parented to a Retargeting node.



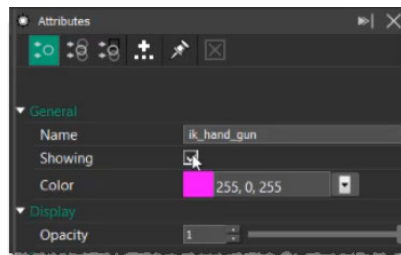
Note

When you import an FBX, it sometimes isn't added under the Retargeting node. In this case, manually parent the skeleton to the node (select the required nodes and on the **Objects** menu, click **Parent**).

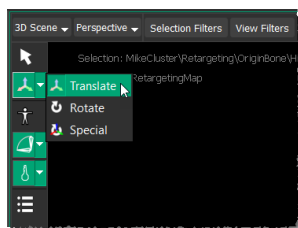
Retarget with Shogun Post

Prepare the skeleton before posing

1. Hide any unnecessary joints. To do this, select the bone, and in the **Attributes** panel, clear the **Showing** box.



2. On the **Retargeting** tab, click **Map Mode** (see [About map mode \(page 214\)](#)) to enable this mode.
This creates a separate clip that you use to pose the target skeleton relative to the source skeleton.
3. In the **Target Root** field, specify which bone is the root. This ensures the root has six DoFs and any bones above it have zero DoFs.
4. Confirm the target skeleton's DoFs were imported or set them as required.
5. If the source and target skeletons don't have roots in the same position or have differing orientation, on the **Retargeting** tab, click **Align Skeletons**. Shogun Post tries to put the skeletons into the same positions and root pose. You can more closely align the skeletons using the **Translate** and **Rotate** manipulators (not the **Special** manipulator).



Be sure to move the root, not any dummy bones above it.

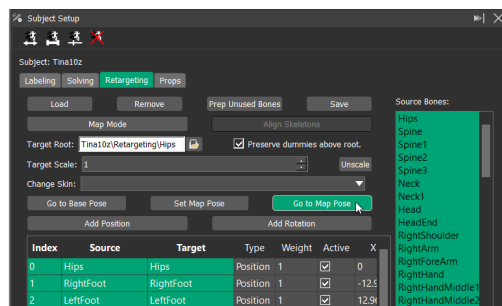
6. If you need to globally scale the target skeleton to be the same size as the source skeleton, on the **Retargeting** tab, change the **Target Scale** value. Ensure that the ankles and clavicles in the target and source skeletons match.

Retarget with Shogun Post

About map mode

The process of creating the constraints between the source (solving) and target (retargeting) skeleton and setting the offsets is called mapping. Before mapping, both skeletons must be in the same pose. This involves posing the target skeleton to match the source (which is its base pose) and you do this in map mode. First you pose the target, then you create the constraints. At the time a constraint is created, its offset is calculated. The offset is the difference in pose between the source and target.

If you need to tweak the setup, or just check how it was set up, you can return to map mode. When making any adjustments, the target must be in the same pose it was when it was mapped. The map pose makes this possible. If constraints exist, implying a map pose is likely to exist, entering map mode automatically places the target skeleton in the map pose. If needed, you can also use the **Go to Map Pose** button (on the Retargeting tab of the Subject Setup panel) to set the retarget skeleton's pose to the map pose.



After you've finished posing, to define the map pose, click **Set Map Pose**.

In addition to restoring the pose you used for mapping, the map pose is also useful for retargeting. Retargeting is faster and easier if the map pose is set because it uses the map pose as a starting point instead of the base pose, which, for some skeletons, may differ widely from the map pose.

Retarget with Shogun Post

Pose the skeleton

1. Make sure that the target skeleton is keyed in the same pose as the source skeleton.
2. Start with the root. Make sure that you've selected the actual root and not any dummy bones above it. Using the **Translate** and **Rotate** manipulators (not the **Special** manipulator), move it to the same place as the source skeleton.
3. Use the **Rotate** manipulator (or enter values in the **Channels** panel) to rotate all the target bones to the same pose as the source skeleton.
Note you can also rotate the source skeleton to match the target skeleton or a mix of the two.
4. If you need to change bone length to make the target skeleton exactly the same proportion as the source (assuming your pipeline both allows this), use the **Special** manipulator. Note that you must remove the **GlobalScale** retargeting parameter. This removes the ability to perform global scaling and unscaling (using the **Unscale** button), so ensure you've scaled your target skeleton first.
5. When you have finished posing the skeleton, in the **Subject Setup** panel, on the **Retargeting** tab, click the **Set Map Pose** button to store the matching pose. If you later modify the pose, remember to click this button again so that the map pose is updated.

Retarget with Shogun Post

Create constraints

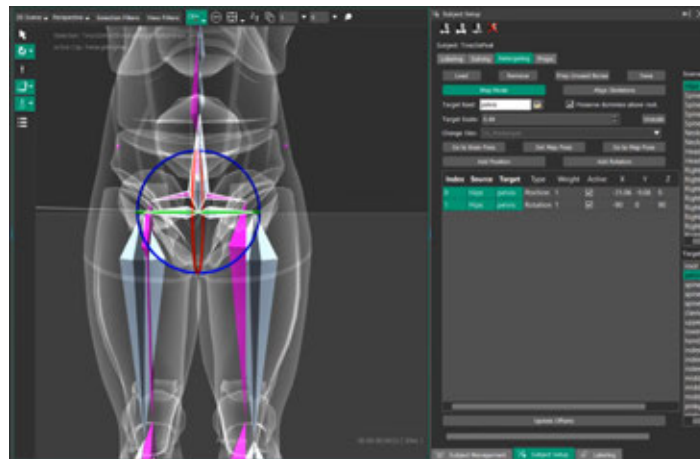


Tip

When creating constraints in Shogun Post 1.6 and later, note the following shortcuts:

- CTRL+T creates a retargeting constraint between the selected solving and retargeting bones, or a solving constraint between the selected solving bone and marker.
- CTRL+R creates a retargeting rotation constraint between the selected solving and retargeting bones.

1. In the lists on the right of the **Retargeting** tab (or anywhere else in Shogun Post), select a matching source and target bone, then click **Add Position** or **Add Rotation** to create a constraint between them. The order of selection does not matter.



2. As a starting point for the constraints, add a position on hands, feet and hips; and rotation on all joints.
If your target skeleton has more joints than the Vicon source skeleton, you can constrain multiple target joints to the same Vicon source joint.


Retarget with Shogun Post

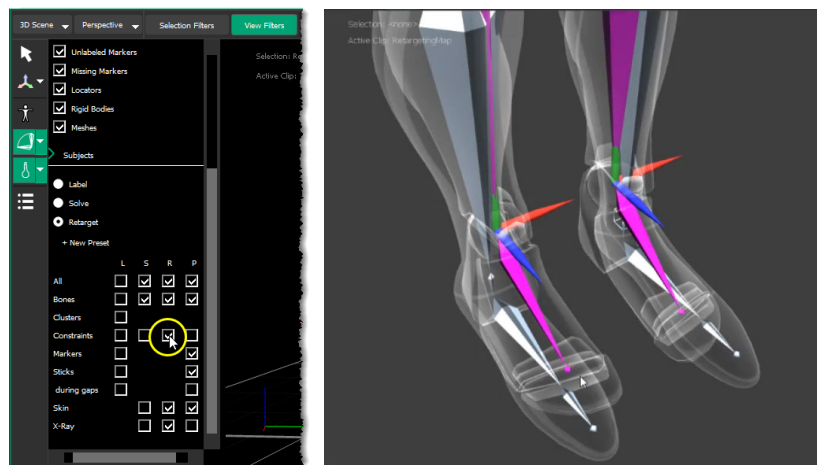


Tip

You can use HSL scripting to speed up creating constraints. For information and examples, see attach in *HSL scripting with Vicon Shogun*.

Another way to speed things up is to mirror the changes you make to one side of the source and target skeletons onto the other side. See [Mirror constraints \(page 219\)](#) and [Mirror joint manipulation \(page 220\)](#).

3. You can alter multiple constraint weights in the table on the **Retargeting** tab. To enable you to immediately see the changes you're making, in the toolbar at the top, ensure the **Enable interactive retargeting** button  is selected (green). You can also select or clear **Active** to turn constraints on or off.
4. To check targets, ensure that the **View Filters** option for **Constraints** (for **Retarget**) is selected.



5. Set weights for all rotations. The recommended value for Rotation weights is 200. To set multiple rotations to 200, on the **Retargeting** tab, drag to select the required rows in the table and then in the **Weight** column, set the value of one of them to 200. All the selected rotation weights are updated to 200.

Retarget with Shogun Post



Tip

If you want to automatically copy your changes to weights from one side of the skeleton to the other, ensure the **Mirror Weight Changes** option is also selected (see [Mirror weights \(page 221\)](#)).

6. To add keys, select the relevant line(s), right-click and select **Set Key**.
To fine-tune keyframes, you can use the controls in the Graph view. For example, you can use the right-click (context) menu in the Graph view to cut or insert sparse keys. You can also change the time of a key by clicking and dragging on the Graph view.
7. To save the VSR mapping file, at the top right of the **Retargeting** tab, click the **Save** button.
By default, VSR files are saved to C:
`\Users\Public\Documents\Vicon\Retargets.`

For information on the relevant HSL commands, see the following commands in *HSL Scripting with Vicon Shogun*.

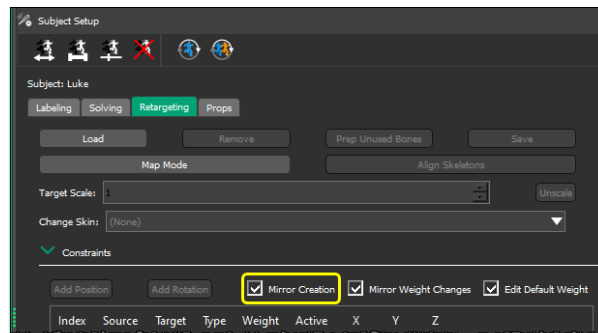
- `getInteractiveRetargetCmd`
- `setInteractiveRetargeting`

Retarget with Shogun Post

Mirror constraints

To make the creation of retargeting constraints faster and less error prone, you can choose to mirror the changes you make to one side of the source and target skeletons onto the other side.

The same option enables you to mirror edits to retargeting constraints.



To mirror retargeting constraints:


1. In the Subject Setup panel, click the Retargeting tab.
2. When you create or edit retargeting constraints, at the top of the Constraints section, ensure the Mirror Creation check box is selected (the default setting). The constraints created between the source and target skeletons on one side are automatically mirrored on the opposite side.

Retarget with Shogun Post

Mirror joint manipulation

When posing a target or source skeleton during retarget setup, you often need to make the same adjustment to each side. To speed up pose adjustments, you can automatically mirror the change you've made to one side to the other side. You can use the same mirroring option when setting up a solve to mirror changes to the pose or bone length. A new button in the manipulator toolbar enables you to do this.

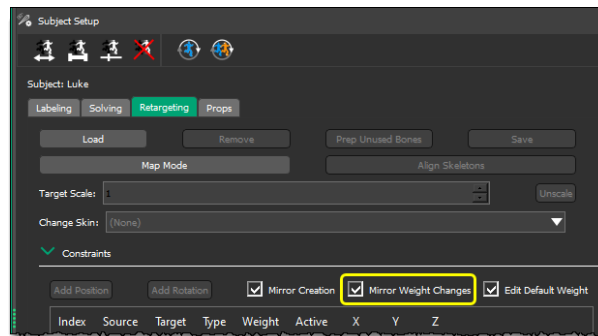
To mirror changes to the pose or bone length of a skeleton:

- In the Manipulator toolbar on the left of the view pane, ensure the Mirror manipulation button  is selected (green). When you create make changes to one side of the subject, they are automatically copied to the other side.

Retarget with Shogun Post

Mirror weights

When you're adding or editing weights, you can use the mirroring option, **Mirror Weight Changes**, to make the same changes on both sides of the skeleton simultaneously.



To mirror weight constraints:

1. In the **Subject Setup** panel, click the **Retargeting** tab.
2. At the top of the **Constraints** section, ensure the **Mirror Weight Changes** check box is selected (the default setting).

When you adjust the weight values between the source and target skeletons on one side, they are automatically mirrored on the opposite side, so that weight values adjusted between, for example, the left lower arm on the source and target skeletons, are mirrored on the right lower arm of the source and target skeletons.

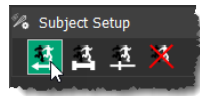
Retarget with Shogun Post

Test the retarget setup

You can test the retarget setup in Shogun Post or in Shogun Live.

To test the retarget setup in Post:

1. When you have finished setup, click **Map Mode** again to turn it off. You are returned to the motion in the file, ideally a ROM.
2. In the **Subject Setup** toolbar, click the **Retarget Play Range** button.



3. Review the retarget.

To test the retarget setup in Live:

1. Load the VSR. To do this, on the **Processing** tab, in the **Retarget** section supply the required names:
 - **Filenames.** Enter or browse to the required VSR files. You can select or enter multiple files, separated with a comma.
 - **Names** Enter the subject name(s). You can enter multiple subject names, separated with a comma. Ensure that the order of multiple names matches that of the VSR file names.
2. In the **General** section, ensure that the **Processing Output Level** is set to **Retarget**.
Your FBX is displayed and is driven by the source skeleton. The retarget skeleton is recorded as part of the MCP capture.

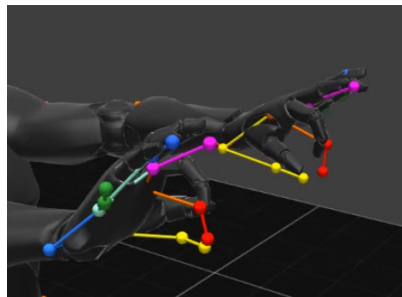
If after testing, you find that further changes are needed, return to map mode and modify the setup (see [Modify a retarget \(page 223\)](#)).

Retarget with Shogun Post

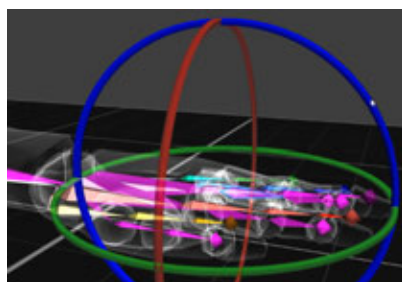
Modify a retarget

To check and modify your retargeting:


1. In Shogun Post, make sure you have turned off **Map Mode** and then run **Retarget** from the **Processing** menu.
2. Assess the results.
When checking the solve, if you need to reduce arm pull, try adding position targets on the clavicles. If the hands need to match more closely, consider zeroing the hand position offsets.
To see any changes, re-run **Retarget** from the **Processing** menu.
3. Pay particular attention to the finger solve. Make sure the hands look correct.



4. If necessary, update the joint placement to get a better fit.



For more information, see:

 [Vicon Shogun 1.3 Post Tutorial - Finger Solve Adjustments](https://youtu.be/IU4BMD1-5IU)³⁴ on YouTube.

³⁴ <https://youtu.be/IU4BMD1-5IU>

Retarget with Shogun Post

5. When you have finished updating the joint placement, in the **Subject Setup** panel, on the **Retargeting** tab, click **Update Offsets** to use the new joint positions.
6. Re-solve the range and check the updated target.
7. Save the final VDF and export the updated VSR.

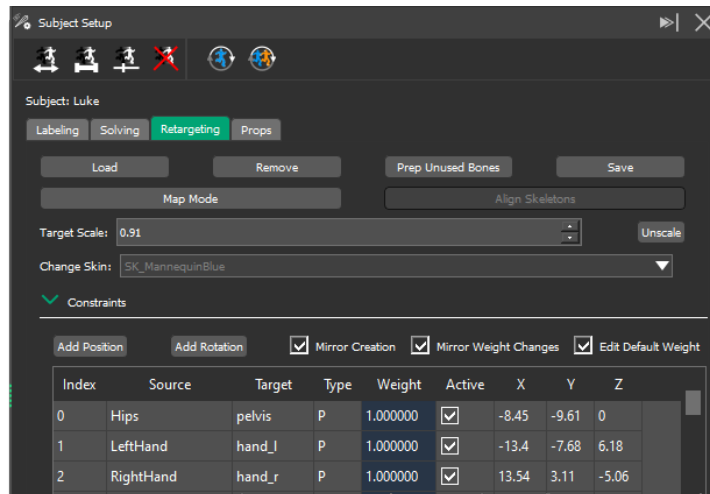
Retarget with Shogun Post


Interactive retargeting

If you want to perform a simple manipulation of a retargeting bone, you can save time and a lot of manual tweaking by using the interactive retargeting feature. This immediately updates the offsets for the constraints that drive the bone that you're adjusting as soon as you release the mouse button.

To manipulate a retargeting bone:

1. Ensure you have loaded the subject, which must have a retargeted skeleton.
2. In the Subject Setup panel, click the **Retargeting** tab and expand **Constraints**.



3. In the 3D Scene, select the joint you want to rotate.
4. From the buttons on Subject Setup panel toolbar, select the **Enable interactive retargeting** button . At the top of the 3D Scene view, the text **Interactive Retargeting** is displayed.
5. Using the manipulator, rotate the subject's joint.
6. When you're happy with the new position of the joint, release the mouse button. The offsets for the constraints which drive the bone are updated.

Retarget with Shogun Post

You can follow a similar procedure to manipulate solving bones: see [Interactive solving \(page 204\)](#).

For information on the relevant HSL commands, see the following commands in *HSL Scripting with Vicon Shogun*.

- `getInteractiveRetargetCmd`
- `setInteractiveRetargeting`

Retarget with Shogun Post

Export the retarget setup

When you're happy with the setup, or if you'd like to see how it works on other motions, export the file, which contains the retarget skeleton, the retargeting constraints, and the map pose.

For more information, see:

- [Export VSR \(page 227\)](#)
- [Export FBX \(page 227\)](#)
- [Export retarget constraints to HSL \(page 228\)](#)

Export VSR

When you export in VSR format, you can:

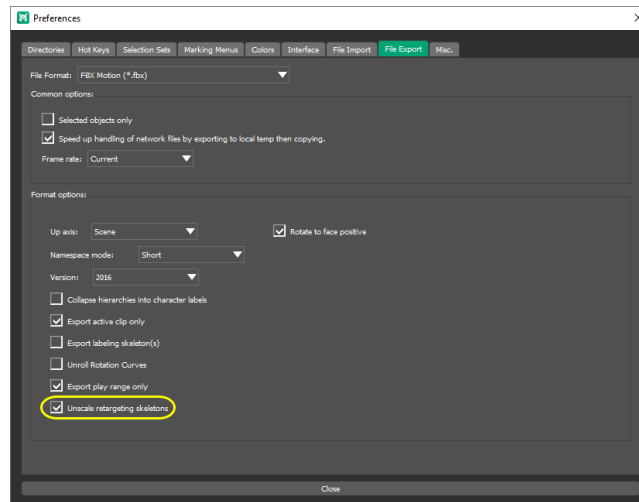
- Load the VSR into other takes that only have a solving skeleton and then run retargeting.
- Load the VSR into Shogun Live to use it in real time.

Export FBX

1. To export in FBX format, select the Retargeting node, then right-click and click **Select Branch**.
This selects the target skeleton, so that you can choose to export **Selected objects only** in the next step.
2. To choose what is exported and whether to reset scaling on export, open the **Preferences** dialog box (on the **General** menu, click **Preferences**), click the **File Export** tab and in the **File Format** box, select **FBX Motion**.

Retarget with Shogun Post

3. If you want to reset scaling on export, ensure that the **Unscale retargeting skeletons** option is selected.



See also [Export from Shogun Post \(page 231\)](#).

You can now test the exported FBX in your CG app.

Export retarget constraints to HSL

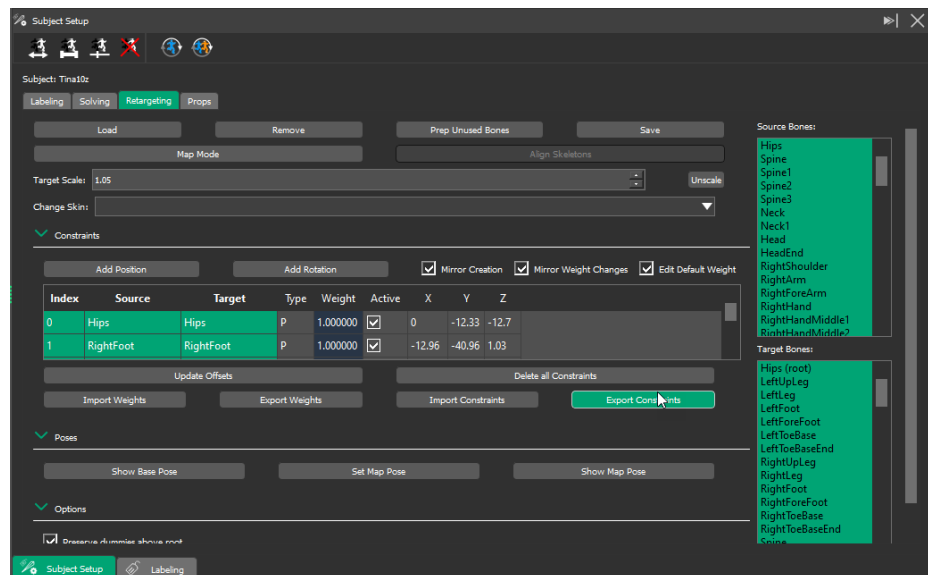
You can export your retargeting setup to an HSL file so that you can re-use it, using the **Export Constraints** feature (Shogun Post 1.6 and later). You do this in a similar way to the current process for exporting solving constraints.

To export retargeting constraints and weights:

1. Load a trial with a fully processed subject (VSK and VSS), which has an associated target skeleton (FBX) with a full set of constraints and weights.
2. In the **Subject Setup** panel, click the **Retargeting** tab and expand the **Constraints** section.
All the configured constraints and weights are listed.

Retarget with Shogun Post

- To export constraints, click **Export Constraints**, which is on the right, underneath the list of constraints.



- In the dialog box, enter or browse to a location and name for the constraints HSL file, and then click **Save** to export the constraints.
- To export weights, click **Export Weights**, which is on the left, underneath the list of constraints.
- In the dialog box, enter or browse to a location and name for the weights HSL file, and then click **Save** to export the weights.

To import the exported constraints and weights:

- Load the MCP file in which you want to use the exported constraints. Ensure that the source bone names that affect constraints and weights are the same as those used in the original MCP file.

The subject and its solving skeleton are displayed in the 3D Scene view.

- Load the associated FBX file. Ensure that the target bone names that affect constraints and weights are the same as those used in the original FBX file.

The FBX target skeleton is displayed in the 3D Scene view.

- ✓ To set the subject's view filter for retargeting, in the 3D Scene view, click **View Filters** and under **Subjects**, select **Retarget**.

Retarget with Shogun Post

3. To import the constraints from the HSL file that you exported earlier, in the **Constraints** section of the **Retargeting** tab, click **Import Constraints**, which is on the right, underneath the constraint list.
4. In the dialog box, enter or browse to the required location and select the constraints HSL file.
5. To import weights, click **Import Weights**, which is on the left, underneath the constraint list). Note that you must import the constraints first, before you import the weights.
6. In the dialog box, enter or browse to the required location and select the weights HSL file. Ensure the same target root bone is set, and a similar target scale is used as before.
The constraints and weights are listed in the **Constraints** section of the **Retargeting** tab.
7. Run the usual retargeting process.

Export from Shogun Post

Export from Shogun Post

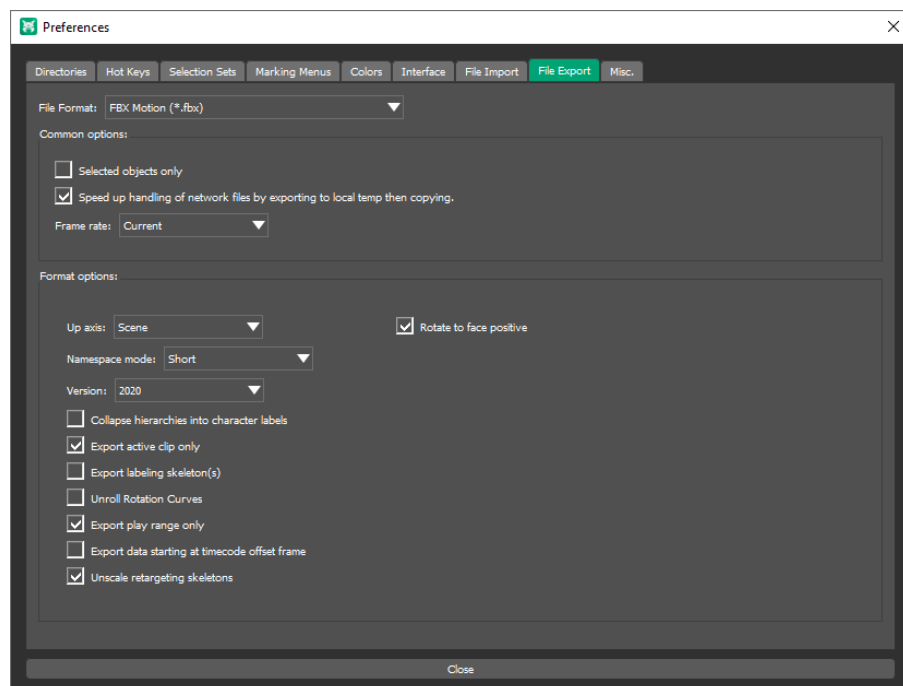
When you are happy with the quality of your data, you can export it from Shogun Post in a format that is appropriate for your chosen animation software.

If you are exporting to FBX, to ensure you choose an appropriate frame rate, see also [Frame rates supported by the FBX file format \(page 233\)](#).

If you are exporting an FBX file for use in Maya® software, see also [Export an FBX file for use in Maya® software \(page 234\)](#).

To export a take:

1. If you want to export only particular aspects of your take (eg bones), select them in your preferred way (eg, in the Selection panel, or by using the Selection Filters options in the 3D Scene view, etc).
2. To specify the required options for your export, on the General menu, click Preferences, and in the Preferences dialog box, click the File Export tab.



Export from Shogun Post

3. Select the required export file format and, if you made a selection for export in Step 1, be sure to select the **Selected objects only** box. Select any other options needed, such as the appropriate frame rate (for FBX, see [Frame rates supported by the FBX file format \(page 233\)](#)), and then click **Close**.
4. On the **File** menu, click **Export**.
5. In the **Export** dialog box, if necessary, change the location of the export and enter a name for your exported file.
6. Select the appropriate file type (e.g. FBX).
7. Click **Save** to export your file to the specified location.

For more information see:

- [Frame rates supported by the FBX file format \(page 233\)](#)
- [Export an FBX file for use in Maya® software \(page 234\)](#)
- [BVH export \(page 236\)](#)

Export from Shogun Post

Frame rates supported by the FBX file format

The following are the frame rates supported by the FBX file format and so are the only frame rates that can be exported from Vicon Post to this format.

- 120 fps
- 100 fps
- 60 fps
- 50 fps
- 48 fps
- 30 fps (black and white NTSC)
- 30 fps (use when display in frame is selected in MotionBuilder, equivalent to NTSC drop)
- ~29.97 fps (drop color NTSC)
- ~29.97 fps (color NTSC)
- 25 fps (PAL/SECAM)
- 24 fps (Film/Cinema)
- 1000 milli/s (use for date time)
- ~23.976 fps
- 96 fps
- 72 fps
- ~59.94 fps
- 119.88 fps (requires custom MotionBuilder version)

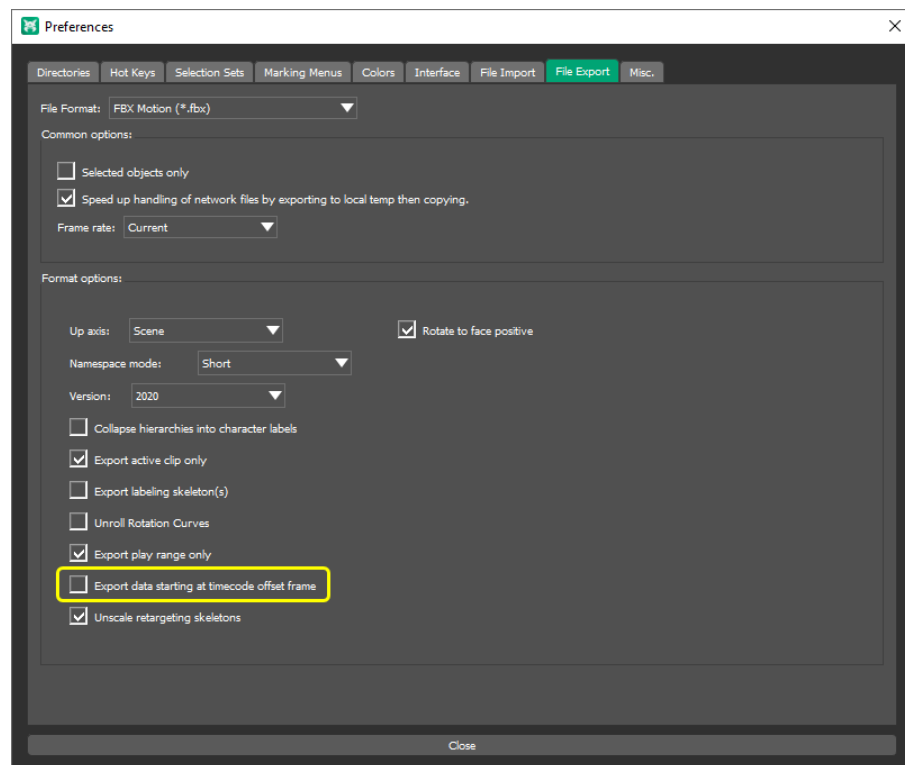
Export from Shogun Post

Export an FBX file for use in Maya[®] software

When exporting an FBX file for use in Maya[®] software, note the following points.

If a timecode is used in Post, the FBX export writes out a JSON file to the same location as the exported FBX file.

In the Preferences dialog box, the Export data starting at timecode offset frame option for FBX export also enables you to choose whether the exported data starts at the timecode start or from frame 1.



When the option is selected, the exported data starts at the timecode start. When the option is cleared (the default), the exported data starts at frame 1. By running a supplied Python script, you can then use the exported JSON file to set the timecode in Maya, provided a timecode was used in Post.

To use the FBX in Maya:

1. In Maya open (don't import) the FBX file.
2. With the file open, run the *CleanupFBXImport.py* script, by default found in:
`C:\Program Files\Vicon\ShogunPost1.#\Scripts\Maya\`

Export from Shogun Post

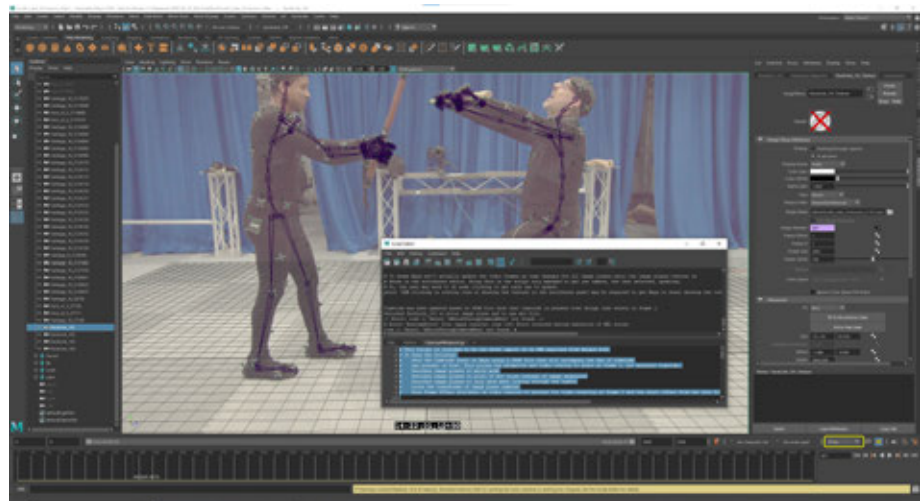
The script sets the scene in a number of ways (see the following list) including setting the correct timecode and linking the MOV file to the correct camera.



Tip

To get Maya to show the video as time changes, you may need to click in Overlay view or select the camera in the Outliner and in the Attributes panel, select the texture tab (see following image).

3. Set the playback speed to the same speed as the video capture rate (eg, 30 fps, as shown in the following image).



In total, the script does the following:

- Sets the timecode start in Maya using the JSON file that is saved with the FBX if timecode was present in Post.
This allows the animation and video overlay to start at frame 1, yet maintains the timecode.
- Switches image planes to movie mode.
- Switches image planes to point to MOV files instead of image sequences.
- Switches image planes to only show when looking through the camera.
- Locks the transforms of image plane cameras.
- Sets the Frame Offset attribute on video texture to account for video starting at frame 0 and the start offset from the JSON file.

Export from Shogun Post

BVH export

With Shogun Post 1.6 and later, you can export takes in BVH format.

If a retargeting skeleton is present, it is exported. If no retargeting skeleton exists, the solving skeleton is exported, if present. As the BVH format permits only one skeleton per file, before you export the scene, ensure that it contains only a single subject/skeleton.

If errors are displayed when you import the resulting BVH, ensure all bones have at least one active DoF before export. (It doesn't matter if they have no keys to go with the DoF(s).)